Check-in Quiz 02 pipe(), signals(), critical sections

Q1 pipe() 5 Points

For this problem, read and consider the following code:

```
#include <unistd.h>
#include <stdio.h>
#include <stdlib.h>
#include <sys/wait.h>
int main(int argc, char* argv[]) {
 int pipe fds[2];
 pipe(pipe_fds);
  /*** 1 ***/
 pid_t child1 = fork();
 if (child1 == 0) {
   // first child
   dup2(pipe_fds[1], STDOUT_FILENO);
   close(pipe_fds[0]);
   /*** 2 ***/
   // should print "hello" to the pipe
   char* args[] = {"echo", "hello", NULL};
    execvp(args[0], args);
    perror("execvp error");
    exit(EXIT FAILURE);
  } else if (child1 < 0) {
   // error!
   perror("fork error");
   exit(EXIT_FAILURE);
  /*** 3 ***/
  pid_t child2 = fork();
```

```
if (child2 == 0) {
  // second child
  dup2(pipe fds[0], STDIN_FILENO);
  close(pipe_fds[0]);
  /*** 4 ***/
  \ensuremath{//} should read from the pipe till EOF
  // print to stdout everything it reads
  char* args[] = {"cat", NULL};
  execvp(args[0], args);
 perror("execvp error");
  exit(EXIT FAILURE);
} else if (child2 < 0) {
  perror("fork error");
 exit(EXIT FAILURE);
/*** 5 ***/
close(pipe fds[0]);
close(pipe_fds[1]);
int wstatus;
// incase you haven't seen a do-while loop,
// it always does one iteration of the loop, and then
// it acts like a while loop after the first iteration.
//
// For example, these two do the same thing:
// -----
// some_function();
// while (condition) {
// some function();
// }
// -----
// do {
// some_function();
// } while(condition);
// -----
do {
 if (waitpid(child1, &wstatus, 0) == -1) {
   perror("waitpid error");
   exit(EXIT FAILURE);
} while (!WIFEXITED(wstatus) && !WIFSIGNALED(wstatus)); /*** 6 ***/
do {
 if (waitpid(child2, &wstatus, 0) == -1) {
    perror("waitpid error");
    exit(EXIT FAILURE);
```

```
}
} while (!WIFEXITED(wstatus) && !WIFSIGNALED(wstatus)); /*** 7 ***/
/*** 8 ***/
return EXIT_SUCCESS;
}
```

Q1.1 What is the problem? 1 Point

There is a bug in this code, causing it to have the incorrect behaviour. The intended behaviour is to do the same thing as echo hello | cat in the terminal.

What is the kind of error this program faces?

Parent does not wait for the children properly

Child2 does not inherit the pipe correctly and cannot read from it

Child1 does not redirect stdout to the pipe correctly

Child2 never hits EOF when reading from the pipe

Child1 never sends EOF when writing to the pipe

The arguments to execvp are malformed

Explanation

Correct! To not give the answer away to 1.3, the explanation for this will be in the 1.3 explanation

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Q1.2 What line to edit? 1 Point

program works. Which line is it?

Note that [/*** 6 ***/] and [/*** 7 ***/] are the only ones that are on a line that already has code.

For the other ones, you can still "edit" the line by replacing the line with a line that has code.



Explanation

Correct! To not give the answer away to 1.3, the explanation for this will be in the 1.3 explanation

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Q1.3 How do we fix it? 3 Points

For the selected line above, please provide what the line should look like to have the expected behaviour.

Be sure to follow the same spacing and style as the provided code, gradescope is picky about the formatting for the accepted answer.

If you are submitting, and think you are correct, but think it may be a formatting issue; make a private post on Ed and course staff will help. close(pipe_fds[1]);

Explanation

Correct! We need to close the write-end of the pipe. Not closing the write-end of the pipe causes child2 to not hit EOF from the pipe. To fix this, we need to close the write-end that is owned by child2 for this. It is worth noting that the write-end of the pipe is not **explicitly** closed in child1 either, and it doesn't **have** to since when child1 exits it will close the open file descriptors it has automatically.

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Q2 Critical Section 3 Points

In lecture, we defined a critical section slightly incorrectly. The definition didn't properly cover all possible cases that should be considered a critical section. The wording was also made slightly better. Wording that was added/changed are in **bold**.

Here is an updated definition below:

There can be issues when **one or more resources** are accessed concurrently that causes the **program** to be put in an **unexpected**, invalid, or error state.

These sections of code **where these accesses happen**, called critical sections, need to be protected from concurrent accesses happening during it

Q2.1 List 2 Points

Consider the example with critical sections we discussed in

lecture:

```
// assume this works
void list_push(list* this, float to_push) {
 Node* node = malloc(sizeof(Node));
 if (node == NULL) exit(EXIT FAILURE);
 node->value = to_push;
 node->next = NULL;
 this->tail->next = node;
 this->tail = node;
void handler(int signo) {
 list push(list, NaN);
int main(int argc, char* argv[]) {
 signal(SIGINT, handler);
 float f;
 while(list size(list) < 20) {</pre>
  read_float(stdin, &f);
  list push(list, f);
  // omitted: do stuff with list
```

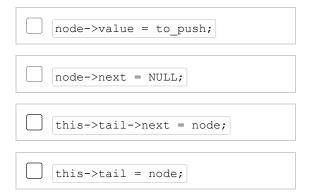
With this example we also said you could:

- Assume we have implemented a linked list, and it works
- Assume list is an initialized global linked list

In lecture we, said to fix this we could block signals temporarily in main() and handler() just before they $list_push()$ and then unblock right after we return from $list_push()$

Lets say that instead of changing <code>main()</code> and <code>handler()</code>, we instead change <code>list_push()</code> to block signals. Which of the following lines **at minimum** would need to be included in the critical section to have the program work correctly.

Select all that apply:



Note the call to malloc would also be part of the critical section, but I am just going to tell you that one since it would be hard to know without thinking about how malloc() works

Explanation

Correct! it is only the two lines of code that manipulate the global state. The first two lines are only modifying memory that is local to that function call.

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Q2.2 Vector 1 Point

A vector is data structure that represents a resizable array. For those used to Java, think of it like an ArrayList.

Consider the following C snippet that outlines what a vector of floats is and how we would push a value to the end of it

```
typedef struct vec_st {
    size_t length;
    size_t capacity;
    float* eles;
} Vector;

void vec_push(Vector* this, float to_push) {
    // assume that we don't have to resize for simplicity
    assert(this->length < this->capacity);

this->length += 1; // increment length to include it
```

```
this->eles[this->length - 1] = to_push; // add the ele to the end
}
```

Is there a critical section in the vec_push function? If so, what line(s)?

There is no critical section in vec push

There is a critical section, and it is the line this->length += 1;

There is a critical section, and it is the line

```
this->eles[this->length - 1] = to_push;
```

There is a critical section, and it includes both of the lines mentioned in the above two answers

Explanation

Correct! Even if the vec is still in a "valid state" when vec_push gets interrupted by another call to vec_push, the vector may not store both numbers correctly in the vector. The length field may also not be incremented correctly, but that will be discussed more in a much later lecture.

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Q3 Signals

2 Points

In lecture we talked about signal blocking and unblocking. This is a slightly altered version of the code from <code>delay_sigint.c</code> lecture code.

The difference being that the lecture code had <code>main()</code> wait for <code>sigalrm</code> to go off and then have <code>main()</code> unblock <code>sigint</code>. The edited code below just has <code>main()</code> loop infinitely without checking to see if the alarm goes off, and the <code>handler()</code> function that goes off when <code>sigalrm</code> is raised will unblock the <code>sigint</code> signal.

```
sigset t mask;
```

```
sigset_t old_mask;
void handler(int signo) {
 if (signo == SIGALRM) {
   printf("alarm delivered\n");
   if (sigprocmask(SIG_SETMASK, &old_mask, NULL) == -1) {
     perror("sigprocmask failed, idk how but it did");
      exit(EXIT FAILURE);
   }
  }
 if (signo == SIGINT) {
  printf("got sigint\n");
   exit(EXIT_SUCCESS);
 }
}
int main() {
 // initialize the set
 if (sigemptyset(&mask) == -1) {
  perror("sigemptyset failed, idk how but it did");
   exit(EXIT FAILURE);
 // add SIGINT to the set
 if(sigaddset(&mask, SIGINT) == -1) {
   perror("sigaddset failed, idk how but it did");
   exit(EXIT FAILURE);
  // block SIGINT
 if (sigprocmask(SIG_BLOCK, &mask, &old_mask) == -1) {
   perror("sigprocmask failed, idk how but it did");
    exit(EXIT FAILURE);
  // not error checking cause I am too tired
  signal(SIGALRM, handler);
  signal(SIGINT, handler);
  alarm(5);
 // infinitely loop, SIGINT should be able
 // to terminate us after the alarm goes off
 while (true) { }
 return EXIT SUCCESS;
}
```

Does this work? If not, what is the difference in behaviour?

This program works the same as the original example lecture code

If SIGINT is sent before the alarm goes off, it is handled immediately and not delayed

SIGINT will always be blocked once main() blocks it

If SIGINT is sent after the alarm goes off, it will not be handled correctly

SIGALRM is not handled correctly, and the handler does not get invoked as expected

Segmentation Fault or other Memory Error

Explanation

Correct! the issue comes from the fact that when a signal handler returns, the operating system will implicitly reset the signal disposition and block mask to what it was before the handler was invoked. This means that SIGINT is re-blocked when the handler returns.

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