Devices, Drivers, DMA, Buffering Computer Operating Systems, Fall 2023

Instructor: Travis McGaha

Head TAs: Nate Hoaglund & Seungmin Han

TAs:

Administrivia

❖MILESTONE 1 IS DUE between Friday 11/10 – Tuesday 11/14

- Expecting around 60% progress on this
- Should have stand-alone PennFAT
- Must meet with your TA in the specified window to demonstrate what you have implemented

❖ Recitation after lecture today will be about PennFAT

Administrivia

- ❖ I synched a bunch of grades to canvas. **PLEASE CHECK THAT THEY ARE ACCURATE**
	- \blacksquare All check-ins
	- Project 0 & peer-eval
- ❖ Midterm Grades Posted
	- **Regrade requests open, due Saturday night @ midnight**

❖ Any questions, comments or concerns from last lecture?

Lecture Outline

- ❖ Device Drivers
	- LC4_GETC
- ❖ Stdio Buffering
	- fflush()
	- fsync()

I/O

- ❖ Reading/writing anything "beyond" memory is called I/O
	- We call the locations we read/write to I/O devices
- ❖ I/O devices include:
	- Keyboard
	- Mouse
	- Files
	- Graphics Displays
	- Networks
	- \blacksquare Etc.

Devices

- ❖ There are other "devices" than just the file storage
	- Auxiliary hardware that extends the functionality of the computer. The computer sends and/or receives data to communicate with the device
	- Sometimes called "Peripheral Devices"
- ❖ Examples:
	- Mouse
	- Keyboard
	- Game Controller
	- Printer
	- Network adapter
	- Projector
	- \blacksquare etc.

Kinds of Devices

- ❖ These devices have many different functionalities and characteristics
- ❖ Block based vs character based
	- File system is block based
	- Keyboards are character based
- ❖ Shared by many processes
	- Network card, disk
- ❖ User related vs OS related
	- Keyboard vs system clock

Device Drivers

- ❖ How does a computer support these various device types?
- ❖ Each device has a *driver*: a piece of software that acts as the interface to the device. Abstracts away some of the hardware details of the device
	- Contains device specific routines for communicating with the computer and routines for controlling/configuring the device
- ❖ Your computer comes with some device drivers installed
- ❖ When you plug in a new device, your computer will start installing device drivers for that device.

IOCTL

- ❖ Input/Output Control
- ❖ The provided Linux system calls (e.g. read, write) are not enough to express the different functions a device may have.

❖ Ioctl int **ioctl**(int fd, int request, ...)

- Specify the file descriptor of the device you want to interact with
- Request contains information on what you would like to do (and some other information)
- Variadic arguments (usually a char^{*} or void^{*})

Device Naming & Separation

- ❖ It can be difficult to keep track of which device is using what resources. If we use memory mapped I/O, what addresses belong to which files?
- ❖ If we have everything resident in OS memory, then it could also be difficult to manage concurrent processes accessing the same device

Everything is File

- ❖ Idea: Give each device a named file and have most requests go through the filesystem.
- ❖ The filesystem allows us to name our devices.
	- /dev/ directory contains various devices as "files"
	- For example, /dev/printer1
- ❖ I/O requests through the file system are already scheduled, have an order enforced, and are checked to be concurrent safe*
	- \blacksquare (from the filesystem level, user can still mess it up)

Everything is File

- ❖ Note: these devices are not like normal "files" as discussed previously
- ❖ These things just appear as files and can be read/written to perform some functionality.
- ❖ Many things are files in linux, it provides a nice consistent interface to interact with devices. **13**

Special Devices

- ❖ Some special devices that exist in /dev/
- ❖ /dev/urandom and /dev/random
	- Provides bytes by the computers cryptographically secure pseudorandom number generator
- ❖ /dev/null
	- Discards anything that is written to it and reports the write as a success.
- \div /dev/fd/
	- Directory containing the open file descriptors for the running process
- ❖ /dev/stdin, /dev/stdout, /dev/stderr
	- Access to the process' standard streams **14** and 14

I/O Architecture

I/O Devices & Controllers

- ❖ Most I/O devices are not purely digital, they have their own hardware
	- Electro-mechanical: e.g. keyboard, mouse, disk, motor
	- Analog/digital: e.g. touchscreen, network interface, monitor, speaker, mic
- ❖ … all have digital interfaces presented by an I/O Controller
	- I/O Device (analog/digital mix) talks to controller
	- CPU (digital) talks to controller (typically through a device driver)
	- Controller acts as a translator: digital (CPU) <-> analog (device)

I/O Controller to CPU Interface

- ❖ I/O controller interface abstracts I/O device as "device registers"
	- Control/Status: may be one register or two
		- Control: lets us toggle options on the device (we won't focus on this)
		- Status: lets us know if we are data is ready to be read/written
	- Data: may be more than one register
		- The data we are reading/writing
- ❖ Example: CPU reading data from input device
	- CPU checks status register if input is available
	- \blacksquare Reads input the data register

Similar steps for writing. More details later!

How can we handle I/O with code/asm?

- ❖ **Two common options**
- ❖ We could create new "I/O instructions" for the ISA
	- Designate opcode(s) for I/O
	- Register and operation encoded in instruction
- ❖ Memory-mapped I/O (Using LDR/STR for LC4)
	- Assign a memory address to each device register
	- Use conventional loads and stores
	- Hardware intercepts loads/stores to these address
	- No actual memory access performed (MMU and caches get more complicated as a result)
	- LC4 (and most other platforms) do this
	- This allows for the I/O code to be written in C and is more portable to other systems.

- ❖ Do you see any problem with this way of getting data from a device (e.g. file/keyboard/etc.)
	- This is what we did in LC4

```
char getc() {
 while(*device status == NOT READY) {
    // do nothing
 }
  char user input = *device_data;
   return user_input;
}
```


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Busy waiting \odot

- ❖ Do you see any problem with this way of getting data from a device (e.g. file/keyboard/etc.)
	- This is trying to make this "No hang", do not block if character is not available

```
char getc() {
  if (*device status == NOT READY) {
     return NOT_READY;
 }
  char user input = *device_data;
   return user_input;
}
```


- ❖ Do you see any problem with this way of getting data from a device (e.g. file/keyboard/etc.)
	- This is trying to make this "No hang", do not block if character is not available

```
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  if (*device status == NOT READY) {
     return NOT_READY;
 }
  char user input = *device_data;
   return user_input;
}
```
Busy waiting still possible… What happens if the process is blocked on waiting for input?

Interrupts

- ❖ Can instead have the hardware device interrupt the CPU to let the OS know that some I/O request is done
- ❖ Allows OS to not run blocked processes, and scheduler other processes that will utilize the CPU

SEKNEES (ONE.) 2016

Question: what?

- ❖ How do interrupts work to solve the problem we just discussed?
- ❖ If the CPU is not doing the work, then what is?

CPU vs Co-processors

- ❖ The CPU is the **C**entral **P**rocessing **U**nit
	- \blacksquare The set of instructions that are possible is fixed, but the exact instructions & program changes.
	- This allows the CPU to be more "general purpose"
- ❖ Our computer also has Coprocessors
	- These are hardware devices that also perform some computation to supplement the CPU.
	- **Usually more specialized**
	- Examples: Graphics Processing Unit (GPU), Floating Point Unit (FPU), I/O processors, network cards, sound cards, etc.
	- What these do and how they are controlled can vary a lot.

DMA

- ❖ To support co-processors, they are usually Direct Memory Access (DMA)
	- If DMA is supported, then allowed coprocessors can directly access memory independently of CPU
- ❖ In our I/O example, this means that an I/O request looks something like:
	- First the CPU sends a request to the I/O coprocessor for a storage medium to perform some read/write.
	- The coprocessor can fulfill this request and access memory directly to store what is read or get what needs to be written
	- The CPU does other things while the I/O request is running and eventually is interrupted by the coprocessor when the request is done. 26

Multi-threaded Search Engine (Execution)

*Running with 1 CPU

Remember this? Coprocessors are the reason why this works.

While one coprocessor is doing some I/O, the CPU can run some other query

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Lecture Outline

❖ d

❖ If we compile this and run it, how many times is hello printed?

```
int main() {
   if (fork() == 0) {
    write(STDOUT_FILENO, "hello", 5);
   }
   if (fork() == 0) {
    write(STDOUT_FILENO, "hello", 5);
 }
   return EXIT_SUCCESS;
}
```


Raise Your Hands

❖ If we compile this and run it, how many times is hello printed?

```
int main() {
   if (fork() == 0) {
     printf("hello");
   }
   if (fork() == 0) {
     printf("hello");
 }
   return EXIT_SUCCESS;
}
```


Raise Your Hands

❖ If we compile this and run it, how many times is hello printed?

```
int main() {
   if (fork() == 0) {
     printf("hello\n");
   }
   if (fork() == 0) {
     printf("hello\n");
 }
   return EXIT_SUCCESS;
}
```
C stdio vs POSIX

- ❖ Why are we getting these different outputs?
- ❖ Let's start with the first two. Both use different ways of writing to standard out.
	- C stdio : user level portable library for **st**andar**d i**nput/**o**utput. Should work on any environment that has the C standard library
		- E.g. printf, fprintf, fputs, getline, etc.
	- POSIX C API: **P**ortable **O**perating System Interface. Functions that are supported by many operating systems to support many OSlevel concepts (Input/Output, networking, processes, threads…)

Buffered writing

- ❖ By default, C stdio uses buffering on top of POSIX:
	- When one writes with **fwrite** (), the data being written is copied into a buffer allocated by stdio inside your process' address space
	- As some point, once enough data has been written, the buffer will be "flushed" to the operating system.
		- When the buffer fills (often 1024 or 4096 bytes)
	- This prevents invoking the write system call and going to the filesystem too often

```
int main(int argc, char** argv) {
char buf[2] = {^{\dagger}h^{\dagger}}, {\^{\dagger}i^{\dagger}}; FILE* fout = fopen("hi.txt", "wb");
   // read "hi" one char at a time
   fwrite(&buf, sizeof(char), 1, fout);
   fwrite(&buf+1, sizeof(char), 1, fout);
   fclose(fout);
   return EXIT_SUCCESS;
}
```


Arrow signifies what will be executed next

Store 'h' into

Arrow signifies what will be executed next

int **main**(int argc, char** argv) { char buf $[2] = {^{\dagger}h^{\dagger}}, {\^{\dagger}i^{\dagger}};$ FILE* fout = **fopen**("hi.txt", "wb"); *// read "hi" one char at a time* **fwrite**(&buf, **sizeof**(char), 1, fout); **fwrite**(&buf+1, **sizeof**(char), 1, fout); **fclose**(fout); return EXIT_SUCCESS; }

Store 'i' into buffer, so that we do not go to filesystem yet

Arrow signifies what will be executed next

```
int main(int argc, char** argv) {
char buf[2] = {^{\dagger}h^{\dagger}}, {\^{\dagger}i^{\dagger}}; FILE* fout = fopen("hi.txt", "wb");
   // read "hi" one char at a time
   fwrite(&buf, sizeof(char), 1, fout);
   fwrite(&buf+1, sizeof(char), 1, fout);
   fclose(fout);
   return EXIT_SUCCESS;
}
```


hi.txt (disk/OS) When we call fclose, we deallocate and flush the buffer to disk

```
int main(int argc, char** argv) {
char buf[2] = {^{\dagger}h^{\dagger}}, {\^{\dagger}i^{\dagger}}; FILE* fout = fopen("hi.txt", "wb");
   // read "hi" one char at a time
   fwrite(&buf, sizeof(char), 1, fout);
   fwrite(&buf+1, sizeof(char), 1, fout);
   fclose(fout);
   return EXIT_SUCCESS;
}
```



```
int main(int argc, char** argv) {
char buf[2] = {^{\dagger}h^{\dagger}}, {\^{\dagger}i^{\dagger}}; int fd = open("hi.txt", O_WRONLY | O_CREAT);
   // read "hi" one char at a time
   write(fd, &buf, sizeof(char));
   write(fd, &buf+1, sizeof(char));
   close(fd);
   return EXIT_SUCCESS;
}
```



```
int main(int argc, char** argv) {
char buf[2] = {^{\dagger}h^{\dagger}}, {\^{\dagger}i^{\dagger}}; int fd = open("hi.txt", O_WRONLY | O_CREAT);
   // read "hi" one char at a time
   write(fd, &buf, sizeof(char));
   write(fd, &buf+1, sizeof(char));
   close(fd);
   return EXIT_SUCCESS;
}
```


Arrow signifies what will be executed next

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   // read "hi" one char at a time
   write(fd, &buf, sizeof(char));
   write(fd, &buf+1, sizeof(char));
   close(fd);
   return EXIT_SUCCESS;
}
```


Two OS/File system accesses instead of one

Buffered Reading

- ❖ By default, C stdio uses buffering on top of POSIX:
	- When one reads with **fread** (), a lot of data is copied into a buffer allocated by stdio inside your process' address space
	- \blacksquare Next time you read data, it is retrieved from the buffer
		- This avoids having to invoke a system call again
	- As some point, the buffer will be "refreshed":
		- When you process everything in the buffer (often 1024 or 4096 bytes)
	- Similar thing happens when you write to a file

```
int main(int argc, char** argv) {
   char buf[2];
   FILE* fin = fopen("hi.txt", "rb");
   // read "hi" one char at a time
   fread(&buf, sizeof(char), 1, fin);
   fread(&buf+1, sizeof(char), 1, fin);
   fclose(fin);
   return EXIT_SUCCESS;
}
```


Arrow signifies what will be executed next

hi.txt (disk/OS)


```
int main(int argc, char** argv) {
   char buf[2];
  FILE* fin = fopen("hi.txt", "rb");
   // read "hi" one char at a time
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```
int main(int argc, char** argv) {
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   fclose(fin);
 return EXIT SUCCESS;
}
```


Why NOT Buffer?

- \triangleleft Reliability the buffer needs to be flushed
	- \blacksquare Loss of computer power = loss of data
	- "Completion" of a write (*i.e.* return from **fwrite** ()) does not mean the data has actually been written
- \div Performance buffering takes time
	- Copying data into the stdio buffer consumes CPU cycles and memory bandwidth
	- Can potentially slow down high-performance applications, like a web server or database (*"zero-copy"*)
- ↓ When is buffering faster? Slower?

Many small writes Or only writing a little Large writes

Fork Problem Explained

Arrow signifies what will be executed next. I execute processes in parallel and "in sync" for demonstration purposes

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BASE

Fork Problem Explained **Researce the processes in parallel and "in sync"**

Arrow signifies what will be executed next. for demonstration purposes

Fork Problem Explained **Researce the processes in parallel and "in sync"**

Arrow signifies what will be executed next. for demonstration purposes

Fork Problem Explained (pt.2)

- ❖ Why did we get different outputs when printf printed a newline character after hello?
	- Only difference was:

 $printf("hello");$ | Vs **printf**("hello"); **printf**("hello\n");

- ❖ All we needed to do to get the expected output was add a \n. why?
- ❖ **printf** prints to stdout and by default stdout is line buffered. Meaning it flushes the buffer on a newline character
	- **If we ran ./prog > out.txt (redirect the output), we would get** different output since buffering policy changes.

How to flush/modify the cstdio buffer

❖ For C stdio:

Flushes the stream to the OS/filesystem

- Has a family of related functions like setbuf(), setbuffer(), setlinebuf();
- Can set the stream to be unbuffered or a specified buffer

How to flush POSIX?

- ❖ When we write to a file with POSIX it is sent to the filesystem, is it immediately sent to disc? No
	- Well, we do have the block cache... so it may not be written to disc
	- Since all File I/O requests go to the file system, if another process accesses the same file, then it should see the data even if it is the block cache and not in disc.
	- If we lose power though...

How to flush POSIX to disk

- ❖ Two functions
	- Fsync int **fsync**(int fd);
	- Flushes all in-core data and metadata to the storage medium
	- fdatasync int **fdatasync**(int fd);
	- Sends the file data to disk
	- Does not flush modified metadata unless necessary for data.
- ❖ C stdio is usually implemented using POSIX on posix compliant systems
	- **fflush** may not necessarily call **fsync**