

# More Concurrency Problems

Computer Operating Systems, Fall 2023

**Instructor:** Travis McGaha

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## TAs:

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# Administrivia

Extended  
wed 29

## ❖ Full PennOS is due ~~Mon Nov 27~~

- You will schedule a time to meet with your TA to demonstrate your working code
- Some info will be posted on the demo & testing functionality soon
- ❖ Check-in due before Lecture next week
- ❖ Recitation after class is open OH  
No Thursday Lecture  
Calendar is updated as of now for OH this week



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❖ Any questions, comments or concerns from last lecture?

# Lecture Outline

- ❖ **Condition Variables**
- ❖ Monitors
- ❖ Reader/Writer Problem
- ❖ Dining Philosophers
- ❖ Deadlock Prevention
- ❖ Deadlock Handling (start)

# Condition Variables

- ❖ Variables that allow for a thread to wait until they are notified to resume
  
- ❖ Avoids waiting clock cycles “spinning”
  
- ❖ Done in the context of mutual exclusion
  - a thread must already have a lock, which it will temporarily release while waiting
  - Once notified, the thread will re-acquire a lock and resume execution

# Condition Variables

- ❖ Condition Variables exist so that:
  - Threads can wait for a shared variable to change
  - Threads can notify waiting threads that a change has been made to the shared variable, and that they can stop waiting
- ❖ Due to condition variables are used to manage access of a shared variable, it is utilized with a mutex (lock).
  - For a thread to wait, it must first have the associated lock. While the thread waits, it gives up the lock
  - For a thread to signal threads sleeping on a condition variable, it must also have the associated lock.
  - When a thread is notified, it will resume executing once it can re-acquire the lock.

# pthread and condition variables

❖ `pthread.h` defines datatype `pthread_cond_t`

```
❖ int pthread_cond_init(pthread_cond_t* cond,  
                        const pthread_condattr_t* attr);
```

- Initializes a condition variable with specified attributes

```
❖ int pthread_cond_destroy(pthread_cond_t* cond);
```

- “Uninitializes” a condition variable – clean up when done

# pthread and condition variables

❖ `pthread.h` defines datatype `pthread_cond_t`

❖ 

```
int pthread_cond_wait(pthread_cond_t* cond,
                    pthread_mutex_t* mutex);
```

- Atomically releases the mutex and blocks on the condition variable. Once unblocked (by one of the functions below), function will return and calling thread will have the mutex locked

❖ 

```
int pthread_cond_signal(pthread_cond_t* cond);
```

- Unblock at least one of the threads on the specified condition

❖ 

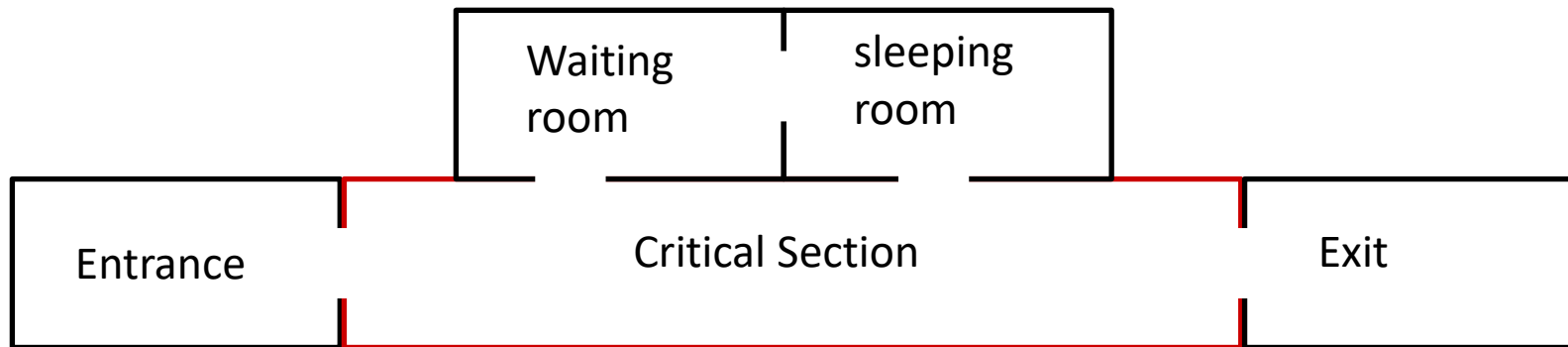
```
int pthread_cond_broadcast(pthread_cond_t* cond);
```

- Unblock all threads blocked on the specified condition



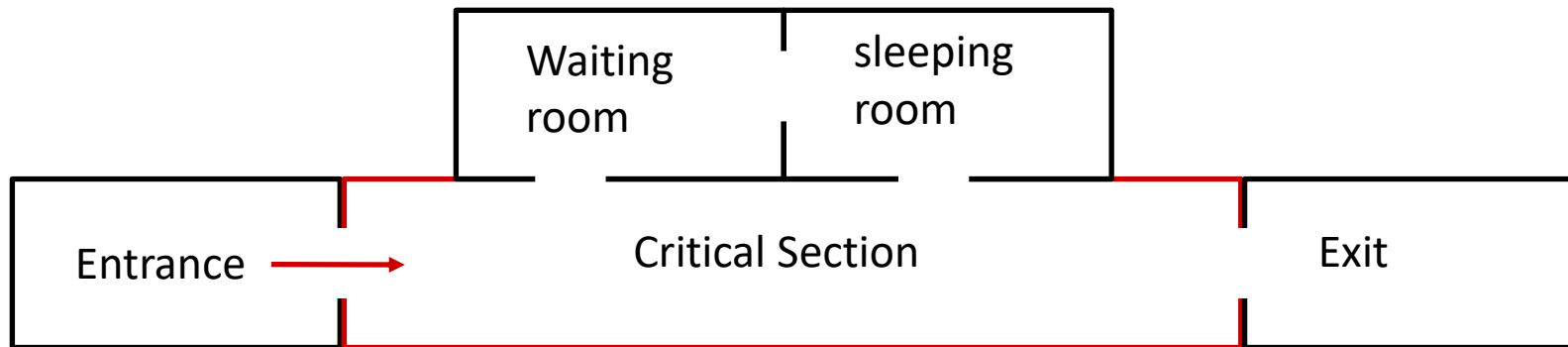
# Condition Variable & Mutex Visualization

- ❖ This is to visualize how we are using condition variables in this example



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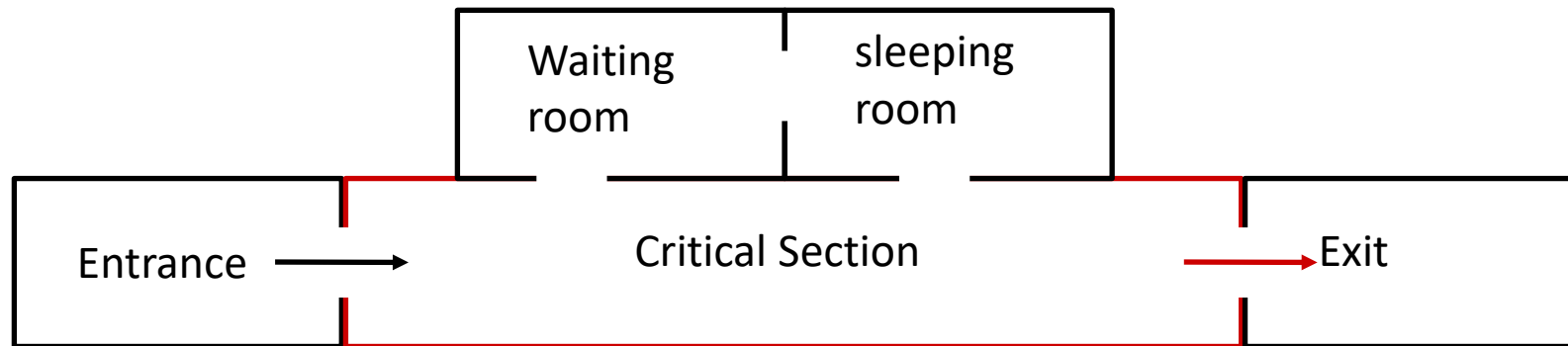


`pthread_mutex_lock`

A thread enters the critical section by acquiring a lock

# Condition Variable & Mutex Visualization

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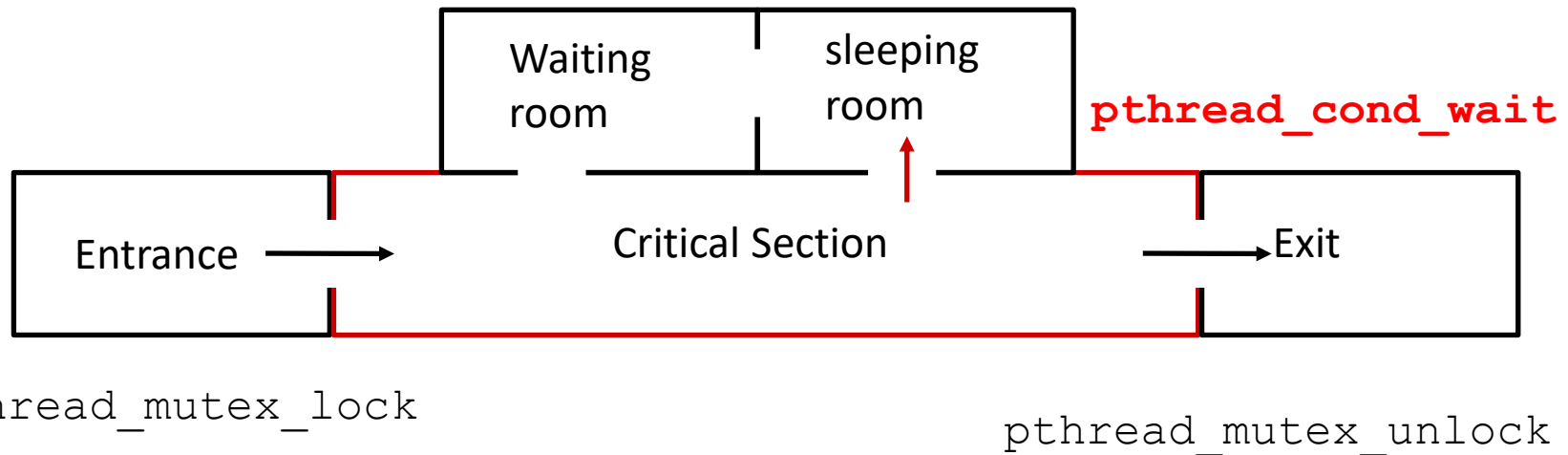
`pthread_mutex_lock`

`pthread_mutex_unlock`

A thread can exit the critical section by acquiring a lock

# Condition Variable & Mutex Visualization

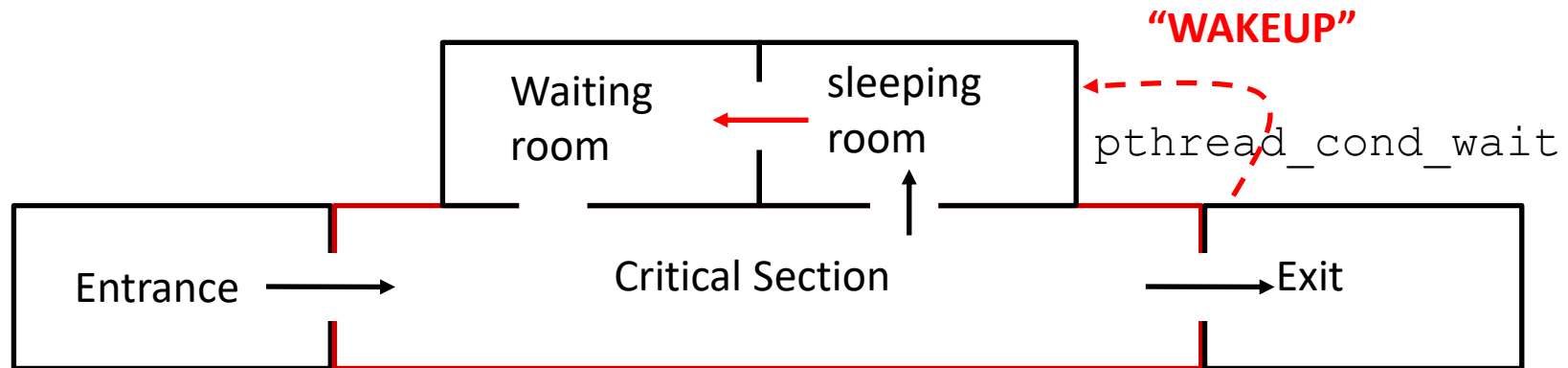
- ❖ This is to visualize how we are using condition variables in this example



If a thread can't complete its action, or must wait for some change in state, it can "go to sleep" until someone wakes it up later.

# Condition Variable & Mutex Visualization

- ❖ This is to visualize how we are using condition variables in this example



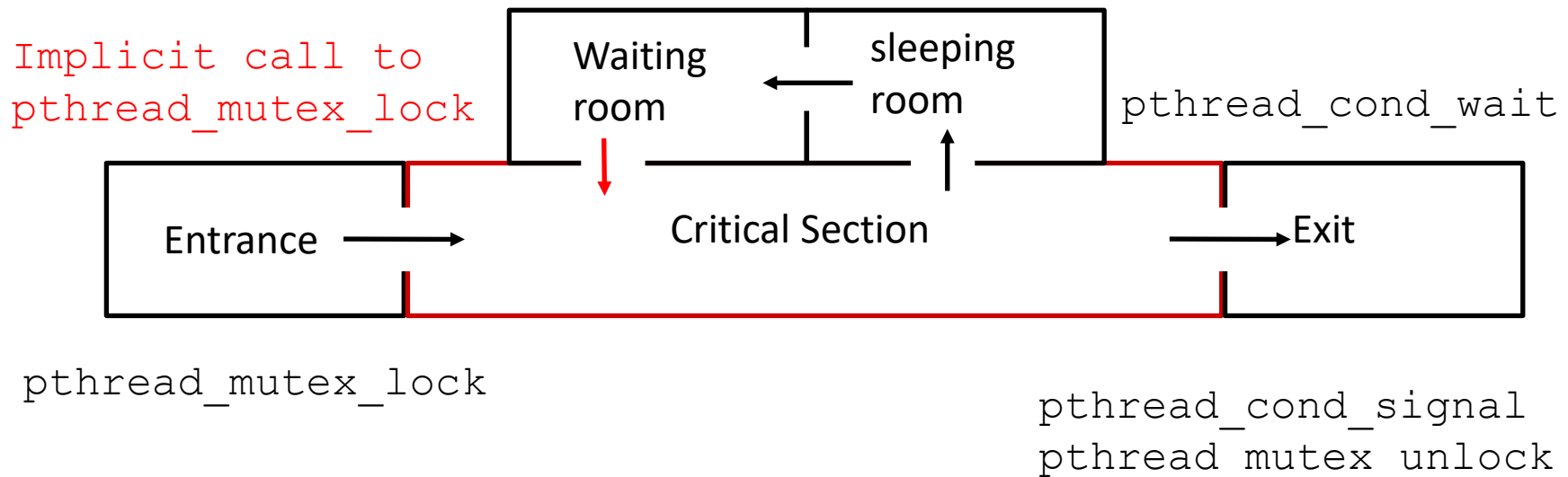
`pthread_mutex_lock`

`pthread_cond_signal`  
`pthread_mutex_unlock`

When a thread modifies state and then leaves the critical section, it can also call `pthread_cond_signal` to wake up threads sleeping on that condition variable

# Condition Variable & Mutex Visualization

- ❖ This is to visualize how we are using condition variables in this example



One or more sleeping threads wake up and attempt to acquire the lock.

Like a normal call to `pthread_mutex_lock` the thread will block until it can acquire the lock

# Revisiting Producer Consumer

- ❖ Demo: `producer_and_consumer.cpp`
  - Original producer and consumer code
  - One thread reads a line from `stdin` and puts it in the deque
  - The other thread gets that string and prints it
  - The consumer thread spins while doing this
  
- ❖ Demo: `cond.cpp`
  - Consumer and producer uses condition variable
  - Consumer waits if there is no value to process
  - Producer notifies any sleeping threads
  - No more spinning 😊

# Poll Everywhere

[pollev.com/tqm](https://pollev.com/tqm)

- ❖ We still need a while loop in the consumer, even with condition variables.
- ❖ Why is this needed? Why may our code be incorrect if we don't have one?

```
deque<int> dq;
pthread_mutex_t dq_lock;
pthread_cond_t dq_cond;

void* consumer_thread(void* arg) {
    while (true) {
        pthread_mutex_lock(&dq_lock);
        while (dq.size() == 0) {
            pthread_cond_wait(&dq_cond,
                              &dq_lock);

            // do nothing
        }
        int val = dq.at(0);
        dq.pop_front();
        do_something(val);
        pthread_mutex_unlock(&dq_lock);
    }
}
```





# Poll Everywhere

[pollev.com/tqm](https://pollev.com/tqm)

- ❖ Why is this needed? Why may our code be incorrect if we don't have one?
- ❖ By the time a thread wakes up, the shared state (the queue maybe empty again)

```
deque<int> dq;
pthread_mutex_t dq_lock;
pthread_cond_t dq_cond;

void* consumer_thread(void* arg) {
    while (true) {
        pthread_mutex_lock(&dq_lock);
        while (dq.size() == 0) {
            pthread_cond_wait(&dq_cond,
                              &dq_lock);

            // do nothing
        }
        int val = dq.at(0);
        dq.pop_front();
        do_something(val);
        pthread_mutex_unlock(&dq_lock);
    }
}
```

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# Monitors

- ❖ Monitors are a higher-level synchronization concept.
- ❖ A Monitor is associated with an object and enforces that only one thread can access data/call the functions of an object at a time.
- ❖ A monitor is made up of a mutex and a condition variable.
- ❖ Every Object in java is/has a monitor.

# Java Monitor Example

```

public class obj {
    private List<String> data;

    public synchronized String get() {
        while (this.data.size() == 0) {
            wait();
            // Ommitted Java exception handling bs
        }
        return this.data.remove(0);
    }

    public synchronized void set(String new_data) {
        this.data.add(new_data);
        notifyAll();
    }
}
    
```

# Monitor vs Condition Variables

- ❖ What we implemented with condition variables was essentially a monitor. But condition variables are not restricted to being used in that context.
- ❖ Monitors in Java work in a lot of cases and can help abstract away some of the details with synchronization
- ❖ In some cases, a monitor would not make the most sense, but you can still use condition variables to solve the issue.
- ❖ **Monitors are a concept, a condition variable is an implementation detail**

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# Readers / Writers Problem

- ❖ What if we have some shared data/object and threads can either read or write to the shared data
- ❖ How many readers can we have at a time?
  - Any number of readers, as long as no one is writing, we can have an unlimited number of readers.
- ❖ How many writers can we have at a time?
  - If a thread is writing to the shared data, then only that thread can have access to the shared data
- ❖ How do we support multiple readers but single writer?

# Reader/Writers

- ❖ We need some metadata, more than just a lock and a cond. Consider the following solutions.

```
// These would normally be put  
// into a rdwr_lock structure  
int num_readers = 0;    // number of active readers  
int writers_waiting = 0; // number of writers waiting  
bool writer_active = false; // is there a writer active?  
  
// lock to make sure only one thread can access &  
// modify the metadata at a time  
pthread_mutex_t lock;  
  
// allows a reader/writer to wait until  
// it is ok to read/write  
pthread_mutex_t cond;
```



# Reader/Writers Demo

- ❖ Demo: `rw_lock.c`
  - Lots of code for how we grant access to readers & writers

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- ❖ There are (at least 2) issues with liveness in this solution, what are they?

```
void read_lock() {
    pthread_mutex_lock(&lock);
    while (writer_active || writers_waiting > 0) {
        pthread_cond_wait(&cond, &lock);
    }
    num_readers++;
    pthread_mutex_unlock(&lock);
    // after we return, the caller is safe to read
}

void read_unlock() {
    pthread_mutex_lock(&lock);
    num_readers--;
    if (num_readers == 0) {
        pthread_cond_broadcast(&cond);
        // why do we need to broadcast here?
    }
    pthread_mutex_unlock(&lock);
}
```

```
void write_lock() {
    pthread_mutex_lock(&lock);
    writers_waiting++;
    while(num_readers > 0 || writer_active) {
        pthread_cond_wait(&cond, &lock);
    }
    writer_active = true;
    writers_waiting--;
    pthread_mutex_unlock(&lock);

    // after we return, caller thread
    // is ok to write to data
}

void write_unlock() {
    pthread_mutex_lock(&lock);
    writer_active = false;
    pthread_cond_broadcast(&cond, &lock);
    pthread_mutex_unlock(&lock);
}
```

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        // why do we need to broadcast here?
    }
    pthread_mutex_unlock(&lock);
}
```

```
void write_lock() {
    pthread_mutex_lock(&lock);
    writers_waiting++;
    while(num_readers > 0 || writer_active) {
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    }
    writer_active = true;
    writers_waiting--;
    pthread_mutex_unlock(&lock);

    // after we return, caller thread
    // is ok to write to data
}

void write_unlock() {
    pthread_mutex_lock(&lock);
    writer_active = false;
    pthread_cond_broadcast(&cond, &lock);
    pthread_mutex_unlock(&lock);
}
```

**Starvation on readers if enough writers come in.**

**More minor: Condition broadcast may unnecessarily awake readers if there are waiting writers**

# pthread\_rwlock

- ❖ Pthread provides a read/write lock implementation that handles this problem for us and hides many of the dirty implementation details
- ❖ Very similar to pthread\_mutex, but two types of locking
  - `pthread_rwlock_rdlock(...)`; // lock as a reader
  - `pthread_rwlock_wrlock(...)`; // lock as a writer

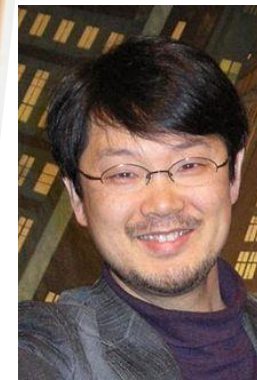
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# Dining Philosophers

## ❖ Assume the following situation

- There are  $N$  philosophers (computer scientists) that are trying to eat rice.
- They only have one chopstick each!
  - Need two chopsticks to eat ☹️
- Alternate between two states:
  - Thinking
  - Eating
- They are arranged in a circle with a chopstick between each of them



# Dining Philosophers

- ❖ Philosophers have good table manners
  - Must acquire two chopsticks to eat
- ❖ Useful abstraction / “standard problem”:
  - Soundness
    - Every chopstick is held by  $\leq 1$  philosopher at a time
  - Deadlock Free
    - No state where no one gets to eat
  - Starvation Free
    - Solution guarantees that all philosophers occasionally eat



# First Solution Attempt

- ❖ If we number each philosopher  $0 - N$  and the each chopstick is also  $0 - N$ , we can model the problem with mutexes, each chopstick is a mutex and each philosopher is a thread
  - To eat, thread  $I$  must acquire lock  $I$  and  $I + 1$
  - This ensures that each chopstick is only in use by one philosopher at a time

```
while (true) {  
    pthread_mutex_lock(&chopstick[i]);  
    pthread_mutex_lock(&chopstick[(i + 1) % N]);  
    eat();  
    pthread_mutex_unlock(&chopstick[(i + 1) % N]);  
    pthread_mutex_unlock(&chopstick[i]);  
    think();  
}
```



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- ❖ What's wrong with this? Any Ideas on how to fix it?

```
while (true) {  
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```

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```
while (true) {  
    pthread_mutex_lock(&chopstick[i]);  
    pthread_mutex_lock(&chopstick[(i + 1) % N]);  
    eat();  
    pthread_mutex_unlock(&chopstick[(i + 1) % N]);  
    pthread_mutex_unlock(&chopstick[i]);  
    think();  
}
```

Deadlock is possible: what happens if all threads pickup their left at the same time?

# Second Attempt: Round Robin

- ❖ Our first attempt deadlocks.
- ❖ What if we instead we tried doing this “round robin”, we pass around a token that says “it is your turn to eat”
- ❖ Can this deadlock?

No

- ❖ What issues arise with this solution?

Not parallel, just sequential eating 😞

Everyone guaranteed gets to eat though 😊

# Third Attempt: Global Mutex

- ❖ What if instead, we add another “global” mutex that controls permission to pick up chopsticks. Once a philosopher has chopsticks, they can release the lock before they eat
- ❖ In our metaphor, this means that each philosopher “waits in line” to pick up chopsticks
- ❖ Can this deadlock?
  - No
  - Not the most parallel, could result in sequential
- ❖ What issues arise with this solution?
  - Not everyone guarantee gets to eat

# Fourth Attempt: More Human Approach

- ❖ What if instead, if a philosopher fails to get a chopstick, it puts down any chopsticks it has, waits for a little bit and then tries again?
- ❖ Can we do this in code?
  - `pthread_mutex_trylock`: if the lock can't be acquired, return immediately
  - `pthread_mutex_timedlock`: timeout after trying to get a mutex for some specified amount of time
- ❖ Can this deadlock? **No**
- ❖ What issues arise with this solution?

**Possible spinning and starvation**

# Fifth Attempt: Break the Symmetry

- ❖ What if the even numbered philosophers and odd numbered philosophers do things differently?
  - Even Numbered: Grab chopstick on their left and then right
  - Odd Numbered: Grab chopstick on their right and then left

- ❖ Can this deadlock?

No

- ❖ What issues arise with this solution?

threads may still possibly starve 😞

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# Previously: Deadlocks

- ❖ Consider the case where there are two threads and two locks
  - Thread 1 acquires lock1
  - Thread 2 acquires lock2
  - Thread 1 attempts to acquire lock2 and blocks
  - Thread 2 attempts to acquire lock1 and blocks

*Neither thread can make progress 😞*



# Deadlock Definition

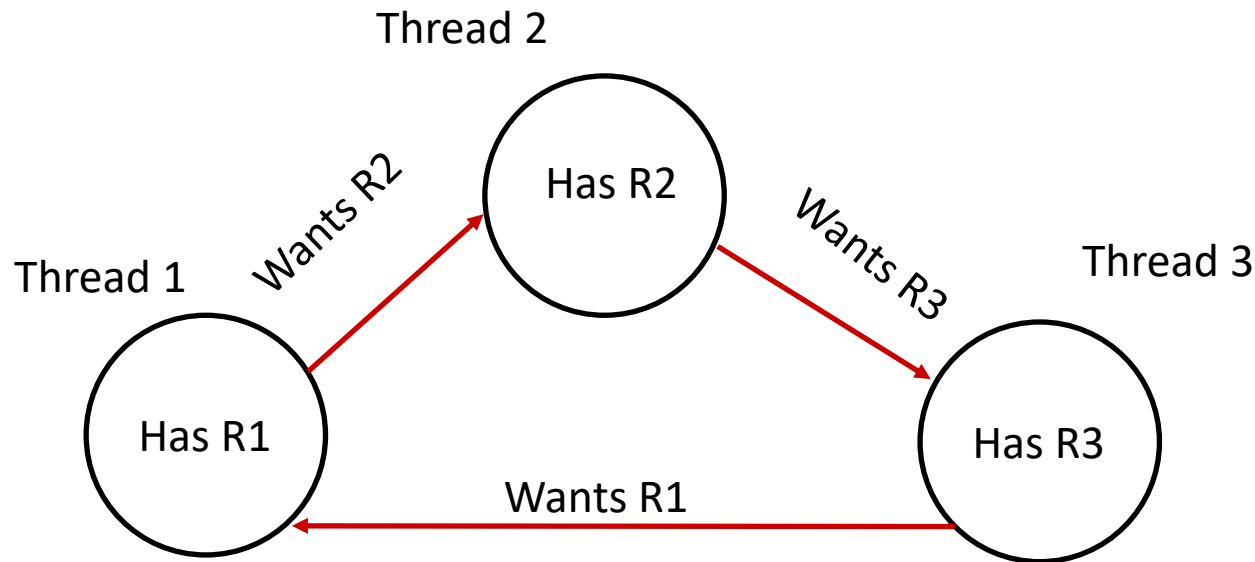
- ❖ A computer has multiple threads, finite resources, and the threads want to acquire those resources
  - Some of these resources require exclusive access
- ❖ A thread can acquire resources:
  - All at once
  - Accumulate them over time
  - If it fails to acquire a resource, it will (by default) wait until it is available before doing anything
- ❖ Deadlock: Cyclical dependency on resource acquisition so that none of them can proceed
  - Even if all unblocked processes release, deadlock will continue

# Preconditions for Deadlock

- ❖ Deadlock can only happen if these occur simultaneously:
  - **Mutual Exclusion**: at least one resource must be held exclusively by one thread
  - **Hold and Wait**: a thread must be holding a resource, requesting a resource that is held by a thread, and then waiting for it.
  - **No preemption**: A resource is held by a thread until it explicitly releases it. It cannot be preempted by the OS or something else to force it to release the resource
  - **Circular Wait**:
    - Can be a chain of more than 2 threads
    - Each thread must be waiting for a resource that is held by another thread. That other thread must be waiting on a resource that forms a chain of dependency

# Circular Wait Example

- ❖ A cycle can exist of more than just two threads:





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- ❖ Can a thread deadlock if there is only one thread?

# Deadlock Prevention

- ❖ If we can remove the conditions for deadlock, we could avoid prevent deadlock from every happening

# Deadlock Prevention: Mutual Exclusion

- ❖ **Mutual Exclusion**: at least one resource must be held exclusively by one thread
- ❖ You usually need mutual exclusion or you don't, so it is hard to avoid.
- ❖ Some resources require exclusive access
- ❖ A lot of work done related to this
  - called: Lock-free programming, Lock-less programming, or Non-blocking algorithms
  - General idea is to take advantage of operations that are atomic at the hardware level when sharing is needed

# Deadlock Prevention: Hold and Wait

- ❖ **Hold and Wait:** a thread must be holding a resource, requesting a resource that is held by a thread, and then waiting for it.
- ❖ What if we had each thread acquire all resources it needs in the begging “at once”
  - This is like one of our dining philosophers implementations
  - Not always practical, a thread may not know ahead of time all the resources it will need

# Deadlock Prevention: No Preemption

- ❖ **No preemption:** A resource is held by a thread until it explicitly releases it. It cannot be preempted by the OS or something else to force it to release the resource
- ❖ If we force a thread to release a resource, how do we ensure it is in a valid state?
  - Undoing actions and recovering valid state is complex (more on this next lecture)



# Deadlock Prevention: Circular Wait

- ❖ **Circular Wait:** Each thread must be waiting for a resource that is held by another thread. That other thread must be waiting on a resource that forms a chain of dependency
- ❖ Break cycles in resource acquisition.
- ❖ We could enforce an ordering to resource acquisition.
  - Consider dining philosophers, what if each thread was required to get the lowest numbered chopstick it wants first?
- ❖ Challenge: Still we may not know all resources we need ahead of time

# Deadlock Prevention Summary

- ❖ Prevent deadlocks by removing any one of the four deadlock preconditions
- ❖ But eliminating even one of the preconditions is often hard/impossible
  - Mutual Exclusion is necessary in a lot of situations
  - Forcing a lower priority process to release resources early requires rollback of execution
  - Not always possible to know all resources that an operating system or process will use upfront

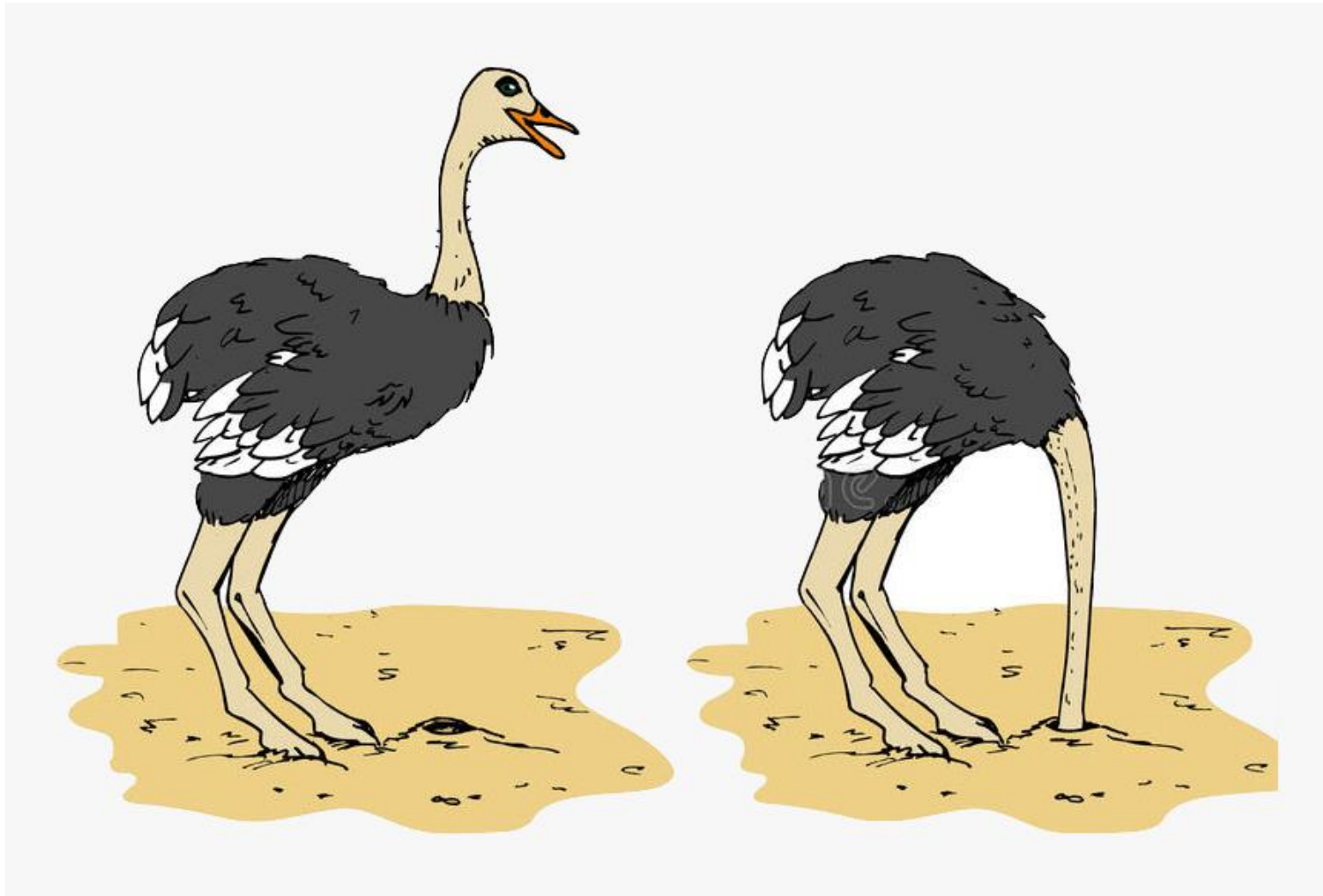
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- ❖ **Deadlock Handling (start)**

# Deadlock Handling: Ostrich Algorithm



# Deadlock Handling: Ostrich Algorithm



Ostriches don't actually do this, but it is an old myth

# Deadlock Handling: Ostrich Algorithm

- ❖ Ignoring potential problems
  - Usually under the assumption that it is either rare, too expensive to handle, and/or not a fatal error
- ❖ Used in real world contexts, there is a real cost to tracking down every possible deadlock case and trying to fix it
  - Cost on the developer side: more time to develop
  - Cost on the software side: more computation for these things to do, slows things down

# Deadlock Handling: Prevention

## ❖ Ad Hoc Approach

- Key insights into application logic allow you to write code that avoids cycles/deadlock
- Example: Dining Philosophers breaking symmetry with even/odd philosophers

## ❖ Exhaustive Search Approach

- Static analysis on source code to detect deadlocks
- Formal verification: model checking
- Unable to scale beyond small programs in practice  
Impossible to prove for any arbitrary program (without restrictions)

# Next Lecture:

- ❖ More On Deadlock
  - Detection
  - Handling
  - Avoidance