Announcements

Upcoming CIS Colloquia related to programming languages

Tuesdays, 3:00-4:30, Levine 101

- ♦ Oct 19 Andy Gordon, MSR Cambridge
- ♦ Nov 16 Greg Morrisett, Harvard University
- $\blacklozenge\,$ Nov
 23 Jeanette Wing, CMU

Recursion in the Lambda Calculus

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Today

♦ Encoding recursion

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- Proving properties by induction
- ♦ Variable substitution and alpha-equivalence
- ♦ Program equivalence

Iterated Application

Suppose ${\tt f}$ is some $\lambda\text{-}{\rm abstraction},$ and consider the following term:

$$Y_f = (\lambda x. f(x x)) (\lambda x. f(x x))$$

Now the "pattern of divergence" becomes more interesting:

$$Y_{f} = \frac{(\lambda x. f(x x)) (\lambda x. f(x x))}{\longrightarrow}$$

$$f((\underline{\lambda x. f(x x)}) (\lambda x. f(x x))) (\lambda x. f(x x)))$$

$$f(f((\underline{\lambda x. f(x x)}) (\lambda x. f(x x))))$$

$$f(f(f((\underline{\lambda x. f(x x)}) (\lambda x. f(x x)))))$$

$$\longrightarrow$$

$$\cdots$$

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Delaying Divergence

poisonpill = λy . omega

Note that **poisonpill** is a value — it it will only diverge when we actually apply it to an argument. This means that we can safely pass it as an argument to other functions, return it as a result from functions, etc.

(λp. fst (pair p fls) tru) poisonpill			
\longrightarrow			
fst (pair poisonpill fls) tru			
*			
poisonpill tru			
\longrightarrow			
omega			
\longrightarrow			

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Y_f is still not very useful, since (like omega), all it does is diverge. Is there any way we could "slow it down"?

Iterated Application

Suppose ${\tt f}$ is some $\lambda\text{-}{\rm abstraction},$ and consider the following term:

 $Y_f = (\lambda x. f(x x)) (\lambda x. f(x x))$

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Another delayed variant

Suppose f is a function. Define

$$Z_f = \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y$$

This term combines the "added \mathtt{f} " from \mathtt{Y}_{f} with the "delayed divergence" of <code>omegav</code>.

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A delayed variant of omega

Here is a variant of omega in which the delay and divergence are a bit more tightly intertwined:

omegav = λy . (λx . (λy . x x y)) (λx . (λy . x x y)) y

Note that omegav is a normal form. However, if we apply it to any argument v, it diverges:

omegav v
=

$$(\lambda y. (\lambda x. (\lambda y. x x y)) (\lambda x. (\lambda y. x x y)) y) v$$

 \longrightarrow
 $(\lambda x. (\lambda y. x x y)) (\lambda x. (\lambda y. x x y)) v$
 \longrightarrow
 $(\lambda y. (\lambda x. (\lambda y. x x y)) (\lambda x. (\lambda y. x x y)) y) v$
 $=$
omegav v

 $\begin{array}{rcl} & & & & \\ & & & & \\ & & & & \\ & & & f & = & \lambda fct. & & \\ & & & & \lambda n. & & \\ & & & & if n=0 then 1 & & \\ & & & & else n * (fct (pred n)) & \\ & & & f looks just the ordinary factorial function, except that, in place of a recursive & \\ \end{array}$

call in the last time, it calls the function fct, which is passed as a parameter.

N.b.: for brevity, this example uses "real" numbers and booleans, infix syntax, etc. It can easily be translated into the pure lambda-calculus (using Church numerals, etc.).

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If we now apply Z_f to an argument v, something interesting happens: $Z_f v =$ $(\lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y) v \longrightarrow$ $(\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) v \longrightarrow$ $f (\lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y) v =$ $f (\lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y) v$

Since Z_f and v are both values, the next computation step will be the reduction of f_{Z_f} — that is, before we "diverge," f gets to do some computation. Now we are getting somewhere.

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A Generic Z Technical note: The term Z here is essentially the same as the **fix** discussed the book. If we define Z = $\lambda f. \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y$ $Z = \lambda f \cdot Z_f$ fix = $\lambda f. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y))$ i.e., $Z = \lambda f. \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y$ Z is hopefully slightly easier to understand, since it has the property that $Z f v \longrightarrow^* f (Z f) v$, which fix does not (quite) share. then we can obtain the behavior of Z_f for any f we like, simply by applying Z to **f**. $Z f \longrightarrow Z_f$ CIS 500, 29 September 13 CIS 500, 29 September 15We can use Z to "tie the knot" in the definition of f and obtain a real recursive For example: factorial function:

 $Z_{f} 3$ \longrightarrow^{*} $f Z_{f} 3$ = $(\lambda fct. \lambda n. ...) Z_{f} 3$ $\longrightarrow \longrightarrow$ if 3=0 then 1 else 3 * (Z_{f} (pred 3))) \longrightarrow^{*} $3 * (Z_{f} (pred 3)))$ \longrightarrow^{*} $3 * (Z_{f} 2)$ \longrightarrow^{*} $3 * (f Z_{f} 2)$ \cdots

Two induction principles

Like before, we have mentioned two ways to prove properties are true of the untyped lambda calculus.

- \blacklozenge Structural induction
- Induction on derivation of $t \to t'$.

Let's do an example of the latter.

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Proofs about the Lambda Calculus

Example

We can formally define the set of free variables in a $\lambda\text{-}\mathrm{term}$ as follows:

$$\begin{split} FV(\mathtt{x}) &= \{\mathtt{x}\} \\ FV(\lambda\mathtt{x}.\mathtt{t}_1) &= FV(\mathtt{t}_1)/\{\mathtt{x}\} \\ FV(\mathtt{t}_1 \ \mathtt{t}_2) &= FV(\mathtt{t}_1) \cup FV(\mathtt{t}_2) \end{split}$$

Theorem: if $t \to t'$ then $FV(t) \supseteq FV(t')$.

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Induction principle

Recall the induction principle for the small-step evaluation relation.

We can show a property P is true for all derivations of $t \to t'$, when

- $\blacklozenge~P$ holds for all derivations that use the rule E-AppAbs.
- ♦ *P* holds for all derivations that end with a use of E-App1 assuming that *P* holds for all subderivations.
- ♦ *P* holds for all derivations that end with a use of E-App2 assuming that *P* holds for all subderivations.

Induction on derivation

We want to prove, for all derivations of $t \rightarrow t'$, that $FV(t) \supseteq FV(t')$.

We have three cases.

♦ The derivation of $t \to t'$ could just be a use of E-AppAbs. In this case, t is $(\lambda x.u)v$ which steps to $[x \mapsto v]u$.

$$FV(t) = FV((\lambda x.u)v)$$

= FV(u)/{x} \cup FV(v)
 \supseteq FV([x \mapsto v]u)
= FV(t')

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Induction on derivation

We want to prove, for all derivations of $t \rightarrow t'$, that $FV(t) \supseteq FV(t')$. We have three cases. • The derivation could end with a use of E-App1. In other words, we have a derivation of $t_1 \rightarrow t'_1$ and we use it to show that $t_1 \ t_2 \rightarrow t'_1 \ t_2$.

By induction $FV(t_1) \supseteq FV(t'_1)$.

 $FV(t) = FV(t_1 t_2)$ = FV(t_1) \cup FV(t_2) \supseteq FV(t_1') \cup FV(t_2) = FV(t_1' t_2) = FV(t_1' t_2)

• The derivation could end with a use of E-App2. Here, we have a derivation of $t_2 \rightarrow t'_2$ and we use it to show that $t_1 \ t_2 \rightarrow t_1 \ t'_2$. This case is analogous to the previous case.

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• The derivation could end with a use of E-App1. In other words, we have a derivation of $t_1 \rightarrow t'_1$ and we use it to show that $t_1 \ t_2 \rightarrow t'_1 \ t_2$. By induction $FV(t_1) \supseteq FV(t'_1)$.

```
\begin{aligned} FV(t) &= FV(t_1 t_2) \\ &= FV(t_1) \cup FV(t_2) \\ &\supseteq FV(t_1') \cup FV(t_2) \\ &= FV(t_1' t_2) \\ &= FV(t_1' t_2) \end{aligned}
```

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Substitution

Our definition of evaluation was based on the substitution of values for free variables within terms.

E-AppAbs

$(\lambda \texttt{x}.\texttt{t}_{12}) \texttt{v}_2 \ \rightarrow \ \texttt{[x} \ \mapsto \ \texttt{v}_2\texttt{]}\texttt{t}_{12}$

But what is substitution, really? How do we define it?

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Formalizing Substitution

Consider the following definition of substitution:

 $[x \mapsto s]x = s$ $[x \mapsto s]y = y \qquad \text{if } x \neq y$ $[x \mapsto s](\lambda y.t_1) = \lambda y. ([x \mapsto s]t_1)$ $[x \mapsto s](t_1 t_2) = ([x \mapsto s]t_1)([x \mapsto s]t_2)$ What is wrong with this definition? It substitutes for free and bound variables! $[x \mapsto y](\lambda x. x) = \lambda x.y$

This is not what we want.

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More about bound variables

Formalizing SubstitutionConsider the following definition of substitution: $[x \mapsto s]x = s$ $[x \mapsto s]y = y$ $[x \mapsto s]y = y$ $[x \mapsto s](\lambda y.t_1) = \lambda y. ([x \mapsto s]t_1)$ $[x \mapsto s](t_1 t_2) = ([x \mapsto s]t_1)([x \mapsto s]t_2)$ What is wrong with this definition?

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Substitution, take two

 $[x \mapsto s]x = s$ $[x \mapsto s]y = y \qquad \text{if } x \neq y$ $[x \mapsto s](\lambda y.t_1) = \lambda y. ([x \mapsto s]t_1) \qquad \text{if } x \neq y$ $[x \mapsto s](\lambda x.t_1) = \lambda x. t_1$

 $[x \mapsto s](t_1 t_2) = ([x \mapsto s]t_1)([x \mapsto s]t_2)$

What is wrong with this definition?

It suffers from variable capture!

 $[x \mapsto y](\lambda y.x) = \lambda x. x$

This is also not what we want.

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Substitution, take tw	VO	
$[x \mapsto s]x = s$		
$[\mathbf{x} \mapsto \mathbf{s}]\mathbf{y} = \mathbf{y}$	if x ≠ y	
$[x \mapsto s](\lambda y.t_1) = \lambda y. ([x \mapsto s]t_1)$	if x ≠ y	
$[x \mapsto s](\lambda x.t_1) = \lambda x. t_1$		
$[x \mapsto s](t_1 t_2) = ([x \mapsto s]t_1)([x \mapsto s]t_2)$		
What is wrong with this definition?		

Substitution, take three

 $[x \mapsto s]x = s$

$[x \mapsto s]y = y$	if x is not y
$[x \mapsto s](\lambda y.t_1) = \lambda y. ([x \mapsto s]t_1)$	$\text{if } \mathtt{x} \neq \mathtt{y}, \mathtt{y} \not\in FV(\mathtt{s}) \\$
$[x \mapsto s](\lambda x.t_1) = \lambda x.t_1$	
$[x \mapsto s](t_1 t_2) = ([x \mapsto s]t_1)([x \mapsto s]t_2)$	
What is wrong with this definition?	
Now substition is a partial function!	
$[x \mapsto y](\lambda y.x)$ is undefined.	
But we want an answer for every substitution.	

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 Substitution, take three

 $[x \mapsto s]x = s$
 $[x \mapsto s]y = y$ if x is not y

 $[x \mapsto s](\lambda y.t_1) = \lambda y.$ ($[x \mapsto s]t_1$)
 if $x \neq y, y \notin FV(s)$
 $[x \mapsto s](\lambda x.t_1) = \lambda x.$ t_1 $[x \mapsto s](t_1 t_2) = ([x \mapsto s]t_1)([x \mapsto s]t_2)$

 What is wrong with this definition?

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Alpha-equivalence classes

In fact, we can create equivalence classes of terms that differ only in the names of bound variables.

When working with the lambda calculus, it is convenient to think about these equivalence classes, instead of raw terms.

For example, when we write $\lambda x.x$ we mean not just this term, but the class of terms that includes $\lambda y.y$ and $\lambda z.z$.

Unfortunately, we have to be more clever when implementing the lambda calculus in ML... (cf. TAPL chapters 6 and 7)

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Equivalence of Lambda Terms

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Bound variable names shouldn't matter

It's annoying that that the names of bound variables are causing trouble with our definition of substitution.

Intuition tells us that there shouldn't be a difference between the functions $\lambda x \cdot x$ and $\lambda y \cdot y$. Both of these functions will do the same thing.

Because they differ only in the names of their bound variables, we'd like to think that these are the same function.

We call such terms alpha-equivalent.

Substitution, for alpha-equivalence classes Now consider substitution as an operation over alpha-equivalence classes of

- -

terms:

- $[x \mapsto s]x = s$
- $[x \mapsto s]y = y \qquad \text{if } x \neq y \\ [x \mapsto s](\lambda y.t_1) = \lambda y. ([x \mapsto s]t_1) \qquad \text{if } x \neq y, y \notin FV(s) \\ [x \mapsto s](t_1 t_2) = ([x \mapsto s]t_1)([x \mapsto s]t_2)$

Examples:

- $[x \mapsto y](\lambda y.x)$ must give the same result as $[x \mapsto y](\lambda z.x)$. We know the latter is $\lambda z.y$, so that is what we will use for the former.
- $[x \mapsto y](\lambda x.z)$ must give the same result as $[x \mapsto y](\lambda w.z)$. We know the latter is $\lambda w.z$ so that is what we use for the former.

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Why is program equivalence important?

We have seen how certain terms in the lambda-calculus can be used to

Representing Numbers

represent natural numbers. $c_0 = \lambda s. \lambda z. z$

 $c_0 = \lambda_s, \ \lambda_z, \ s_z$ $c_1 = \lambda_s, \ \lambda_z, \ s_z$ $c_2 = \lambda_s, \ \lambda_z, \ s \ (s \ z)$ $c_3 = \lambda_s, \ \lambda_z, \ s \ (s \ (s \ z))$

Other lambda-terms represent common operations on numbers:

 $scc = \lambda n. \lambda s. \lambda z. s (n s z)$

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Program Equivalence

- Syntactic equivalence Are the terms the same "letter by letter"? Not that useful.
- Alpha-equivalence Are the terms equivalent up to renaming of bound variables?
- Beta/eta-equivalence Can we use specific program transformations to convert one term into another?
- Behavioral equivalence If both terms are placed in the same context, will they produce the same result?

- Why is program equivalence important?
- Used to catch cheaters in low-level programming classes.
- ♦ Used to prove the correctness of embeddings. (Why should we believe that Church encodings represent natural numbers?)
- ♦ Used to prove the correctness of compiler optimizations.
- Used to show that updates to a program do not break it.

The naive approach

One possibility:

For each n, the term scc c_n evaluates to c_{n+1} .

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A better approach

Recall the intuition behind the church numeral representation:

- \blacklozenge a number n is represented as a term that "does something n times to something else"
- ♦ scc takes a term that "does something n times to something else" and returns a term that "does something n + 1 times to something else"

I.e., what we really care about is that $scc c_2$ behaves the same as c_3 when applied to two arguments.

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Representing Numbers

We have seen how certain terms in the lambda-calculus can be used to represent natural numbers.

 $\begin{array}{l} c_0 = \lambda s. \ \lambda z. \ z\\ c_1 = \lambda s. \ \lambda z. \ s \ z\\ c_2 = \lambda s. \ \lambda z. \ s \ (s \ z)\\ c_3 = \lambda s. \ \lambda z. \ s \ (s \ (s \ z)) \end{array}$

Other lambda-terms represent common operations on numbers:

scc = λ n. λ s. λ z. s (n s z)

In what sense can we say this representation is "correct"?

In particular, on what basis can we argue that **scc** on church numerals corresponds to ordinary successor on numbers?

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\label{eq:constraint} \begin{array}{l} The \ naive \ approach... \ doesn't \ work \\ \\ One \ possibility: \\ \ For \ each \ n, \ the \ term \ scc \ c_n \ evaluates \ to \ c_{n+1}. \\ \\ Unfortunately, \ this \ is \ false. \\ \\ E.g.: \\ \\ \begin{array}{l} scc \ c_2 \ = \ (\lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)) \ (\lambda s. \ \lambda z. \ s \ (s \ z)) \\ \qquad \longrightarrow \ \lambda s. \ \lambda z. \ s \ ((\lambda s. \ \lambda z. \ s \ (s \ z)) \ s \ z) \\ \qquad \neq \ \lambda s. \ \lambda z. \ s \ (s \ (s \ z)) \\ \qquad = \ c_3 \end{array}
```

A More General Question

We have argued that, although $scc c_2$ and c_3 do not evaluate to the same thing, they are nevertheless "behaviorally equivalent."

What, precisely, does behavioral equivalence mean?

Some test cases

tru = λt . λf . t tru' = λt . λf . ($\lambda x.x$) t fls = λt . λf . f omega = ($\lambda x. x x$) ($\lambda x. x x$) poisonpill = λx . omega placebo = λx . tru Y_f = ($\lambda x. f$ (x x)) ($\lambda x. f$ (x x))

Which of these are behaviorally equivalent?

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 $scc c_2 v w = (\lambda n. \lambda s. \lambda z. s (n s z)) (\lambda s. \lambda z. s (s z)) v w$ $\rightarrow (\lambda s. \lambda z. s ((\lambda s. \lambda z. s (s z)) s z)) v w$ $\rightarrow (\lambda z. v ((\lambda s. \lambda z. s (s z)) v z)) w$ $\rightarrow v ((\lambda s. \lambda z. s (s z)) v w)$ $\rightarrow v ((\lambda z. v (v z)) w)$ $\rightarrow v (v (v w))$ $c_3 v w = (\lambda s. \lambda z. s (s (s z))) v w$ $\rightarrow (\lambda z. v (v (v z))) w$ $\rightarrow v (v (v w))$

Intuition

Roughly,

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terms \mathbf{s} and \mathbf{t} are behaviorally equivalent

should mean:

there is no "test" that distinguishes s and t — i.e., no way to use them in the same context and obtain different results.

Observational equivalence

As a first step toward defining behavioral equivalence, we can use the notion of normalizability to define a simple way of testing terms.

Two terms **s** and **t** are said to be observationally equivalent if either both are normalizable (i.e., they reach a normal form after a finite number of evaluation steps) or both are divergent.

I.e., our primitive notion of "observing" a term's behavior is simply running it on our abstract machine.

Aside:

♦ Is observational equivalence a decidable property?

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Observational equivalence

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Examples

♦ omega and tru are not observationally equivalent

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Observational equivalence

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I.e., our primitive notion of "observing" a term's behavior is simply running it on our abstract machine.

Aside:

- ♦ Is observational equivalence a decidable property?
- Does this mean the definition is ill-formed?

Behavioral Equivalence

This primitive notion of observation now gives us a way of "testing" terms for behavioral equivalence

Terms s and t are said to be behaviorally equivalent if, for every finite sequence of values v_1, v_2, \ldots, v_n , the applications

 $s v_1 v_2 \dots v_n$

and

t V1 V2 ... Vn

are observationally equivalent.

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Examples

♦ omega and tru are not observationally equivalent

tru and **fls** are observationally equivalent

Examples

These terms are behaviorally equivalent: tru = λt . λf . t tru' = λt . λf . ($\lambda x.x$) t

So are these:

omega = $(\lambda x. x x) (\lambda x. x x)$ $Y_f = (\lambda x. f (x x)) (\lambda x. f (x x))$

These are not behaviorally equivalent (to each other, or to any of the terms above):

fls = λt . λf . f poisonpill = λx . omega placebo = λx . tru