

# Announcements

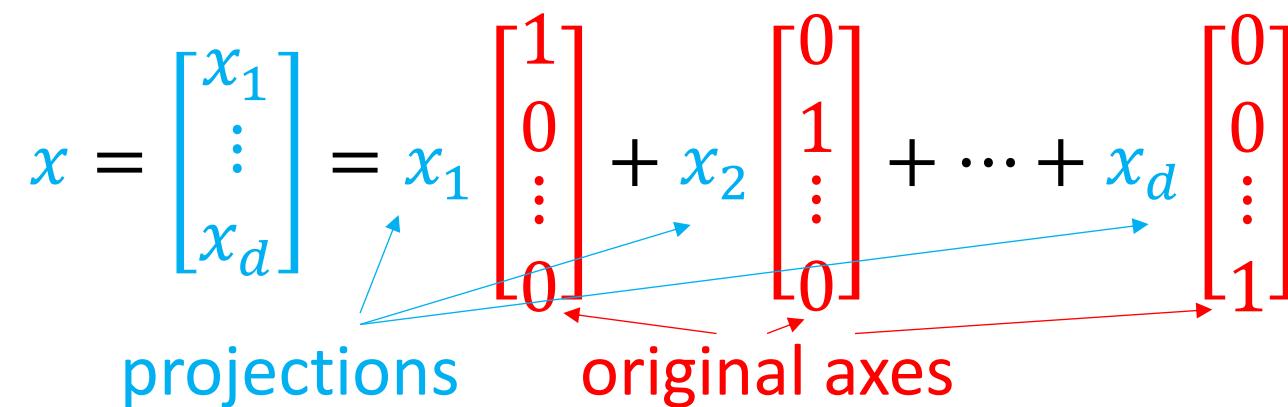
- **Upcoming deadlines**
  - Project Milestone 1 due on **Wednesday, October 18 at 8pm**
  - Quiz 5 due Thursday, October 19 at 8pm

# Dimensionality Reduction

- We can write each input  $x$  as

$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_d \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix} + \cdots + x_d \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

projections      original axes



- We aim to approximate  $x$  using a new basis  $\{v_i\}_i$  (of unit norm):

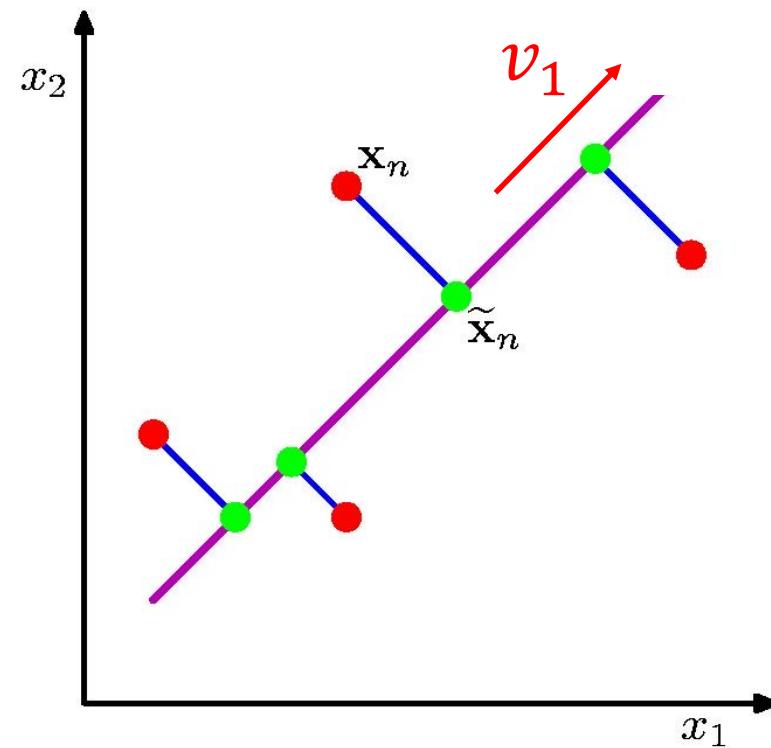
$$x \approx \tilde{f}(x) = f(x)_1 v_1 + f(x)_2 v_2 + \cdots + f(x)_{d'} v_{d'}$$

# 1D Case

- **Simplest case:** If  $d' = 1$ , then we want  $\textcolor{blue}{x} \approx \textcolor{teal}{f}(\textcolor{blue}{x})_1 \textcolor{red}{v}_1$

- Given  $\textcolor{red}{v}_1$ , we can take  $\textcolor{teal}{f}(\textcolor{blue}{x})_1 = \textcolor{blue}{x}^\top \textcolor{red}{v}_1$

- Minimizes MSE of  $\|x - \textcolor{teal}{f}(\textcolor{blue}{x})_1 \textcolor{red}{v}_1\|$
- Then, we have  $\tilde{f}(\textcolor{blue}{x}) = (\textcolor{blue}{x}^\top \textcolor{red}{v}_1) \textcolor{red}{v}_1$
- I.e., orthogonal projection
- Assuming  $\|\textcolor{red}{v}_1\|_2 = 1$



# 1D Case

- In this case, the loss is

$$L(\mathbf{v}_1; \mathbf{Z}) = \frac{1}{n} \sum_{i=1}^n \left\| \mathbf{x}_i - (\mathbf{x}_i^\top \mathbf{v}_1) \mathbf{v}_1 \right\|_2^2$$

# 1D Case

- Since we have assumed  $\|\textcolor{green}{v}_1\|_2 = 1$ , we have

$$\left\| \textcolor{blue}{x}_i - (\textcolor{blue}{x}_i^\top \textcolor{green}{v}_1) \textcolor{green}{v}_1 \right\|_2^2$$

# 1D Case

- Since we have assumed  $\|\mathbf{v}_1\|_2 = 1$ , we have

$$\begin{aligned}\|\mathbf{x}_i - (\mathbf{x}_i^\top \mathbf{v}_1) \mathbf{v}_1\|_2^2 &= \|\mathbf{x}_i\|_2^2 - 2\mathbf{x}_i^\top (\mathbf{x}_i^\top \mathbf{v}_1) \mathbf{v}_1 + \|(\mathbf{x}_i^\top \mathbf{v}_1) \mathbf{v}_1\|_2^2 \\ &= \|\mathbf{x}_i\|_2^2 - 2(\mathbf{x}_i^\top \mathbf{v}_1)^2 + (\mathbf{x}_i^\top \mathbf{v}_1)^2 \|\mathbf{v}_1\|_2^2 \\ &= \|\mathbf{x}_i\|_2^2 - (\mathbf{x}_i^\top \mathbf{v}_1)^2 \\ &= \|\mathbf{x}_i\|_2^2 - \mathbf{v}_1^\top \mathbf{x}_i \mathbf{x}_i^\top \mathbf{v}_1\end{aligned}$$

# 1D Case

- Thus, we have

$$\sum_{i=1}^n \left\| \textcolor{blue}{x}_i - (\textcolor{blue}{x}_i^\top \textcolor{green}{v}_1) \textcolor{green}{v}_1 \right\|_2^2$$

# 1D Case

- Thus, we have

$$\begin{aligned}\sum_{i=1}^n \left\| \mathbf{x}_i - (\mathbf{x}_i^\top \mathbf{v}_1) \mathbf{v}_1 \right\|_2^2 &= \sum_{i=1}^n \|\mathbf{x}_i\|_2^2 - \mathbf{v}_1^\top \mathbf{x}_i \mathbf{x}_i^\top \mathbf{v}_1 \\ &= \text{const} - \sum_{i=1}^n \mathbf{v}_1^\top \mathbf{x}_i \mathbf{x}_i^\top \mathbf{v}_1 \\ &= \text{const} - \mathbf{v}_1^\top \left( \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^\top \right) \mathbf{v}_1 \\ &= \text{const} - n \mathbf{v}_1^\top C \mathbf{v}_1\end{aligned}$$

# General Case

PCA( $Z$ ):

$$Z \leftarrow \{x - \text{Mean}(Z) \mid x \in Z\}$$

$$C \leftarrow \frac{1}{n} \sum_{i=1}^n x_i x_i^\top$$

**for**  $j \in \{1, \dots, d'\}$ :

$$v_j \leftarrow \text{Eigenvector}(C, j)$$

**return**  $f: x \mapsto [x^\top v_1 \quad \dots \quad x^\top v_{d'}]^\top$

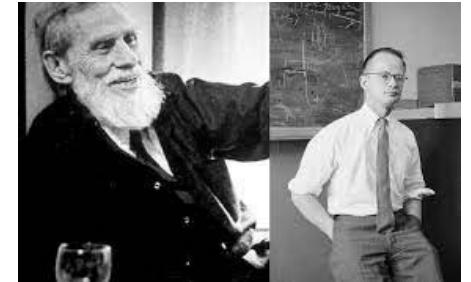
# Lecture 13: Neural Networks

CIS 4190/5190

Fall 2023

# Brief History of Neural Networks

- **1943:** Perceptron model (McCulloch & Pitts)
  - Intended as theoretical model of biological neurons
  - Linear classifiers! (Specialized learning algorithm)



- **1958:** Implementation as Mark I Perceptron (Rosenblatt)
  - Demonstrated capabilities of handwritten letter recognition



- **1969:** Perceptrons cannot learn XOR (Minsky & Papert)
  - Highly controversial (may have helped cause “AI winter”)



# Brief History of Neural Networks

- **1985:** Representation learning (Rumelhart, Hinton, & Williams)
  - Interpret intermediate computations of neural networks
- **1989:** Convolutional neural networks (Lecun)
  - Convert handcrafted convolutional filters into learnable parameters
- **1995:** Long short-term memory (Hochreiter & Schmidhuber)
  - Refinement of neural networks designed to predict sequences
  - Complex design demonstrates flexibility of neural networks

# Brief History of Neural Networks

- **1998:** Convolutional neural networks for MNIST (Lecun)
  - Human-level performance on handwritten digit recognition
- **2012:** ImageNet breakthrough (Krizhevsky, Sutskever, & Hinton)
  - Reduced error on image classification by 50%
- **2017:** Transformer architecture (Vaswani et al.)
- **2018:** Turing award (Bengio, Hinton, & Lecun)
- To be continued?



# What Changed?

- **More compute:** GPUs
- **More data:** ImageNet, Wikipedia/Web, etc.
  - New applications
- **Better optimization algorithms:** Mini-batch SGD, acceleration, etc.
- **Accumulation of “folk knowledge”:** Parameter initialization, etc.
  - Encoded in open source software packages
- **Modern perspective:** “Differentiable programming”
- **Lots of investment from tech companies**

# Agenda

- **Model family**
  - Custom model family rather than a single model family
- **Optimization**
  - Backpropagation algorithm for computing gradient

# A Simple Neural Network

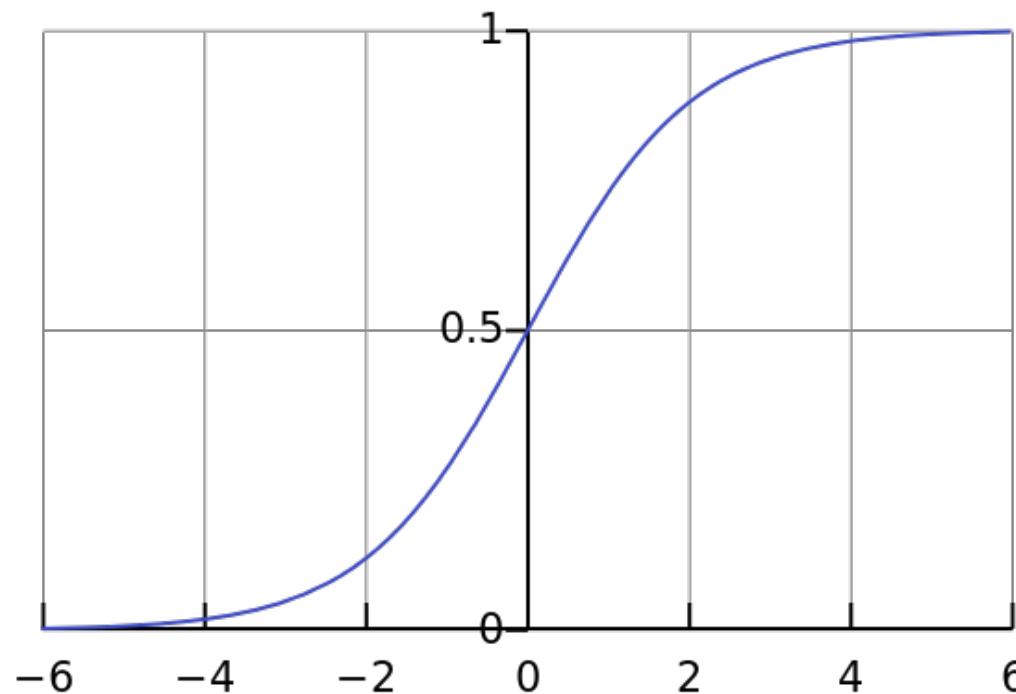
- Feedforward neural network model family (for regression):

$$f_{W,\beta}(x) = \beta^T g(Wx)$$

- Parameters: Matrix  $W \in \mathbb{R}^{k \times d}$  and vector  $\beta \in \mathbb{R}^k$ 
  - $k$  is a hyperparameter called the **number of hidden neurons**
- Here,  $g: \mathbb{R} \rightarrow \mathbb{R}$  is a given **activation function**
  - It is applied componentwise in  $f_{W,\beta}$  (i.e.,  $g \left( \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} \right) = \begin{bmatrix} g(z_1) \\ g(z_2) \end{bmatrix}$ )
  - Example:  $g(z) = \sigma(z)$  (where  $\sigma$  is the sigmoid function)

# A Simple Neural Network

- Possible choice of activation function:  $g(z) = \sigma(z)$



# A Simple Neural Network

- Feedforward neural network model family (for regression):

$$f_{W,\beta}(x) =$$

# A Simple Neural Network

- Feedforward neural network model family (for regression):

$$f_{W,\beta}(x) = x$$

$x_1$

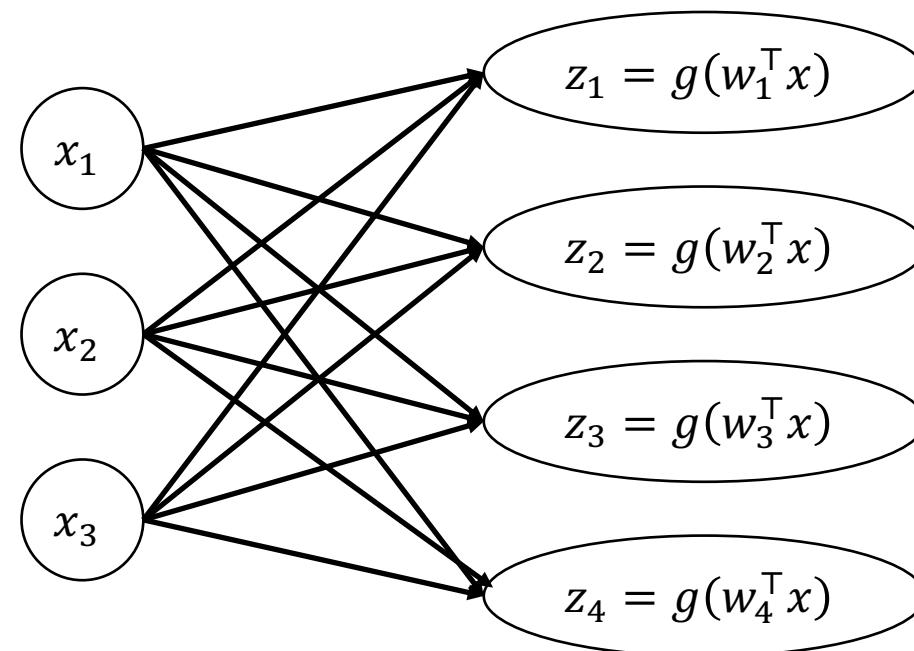
$x_2$

$x_3$

# A Simple Neural Network

- Feedforward neural network model family (for regression):

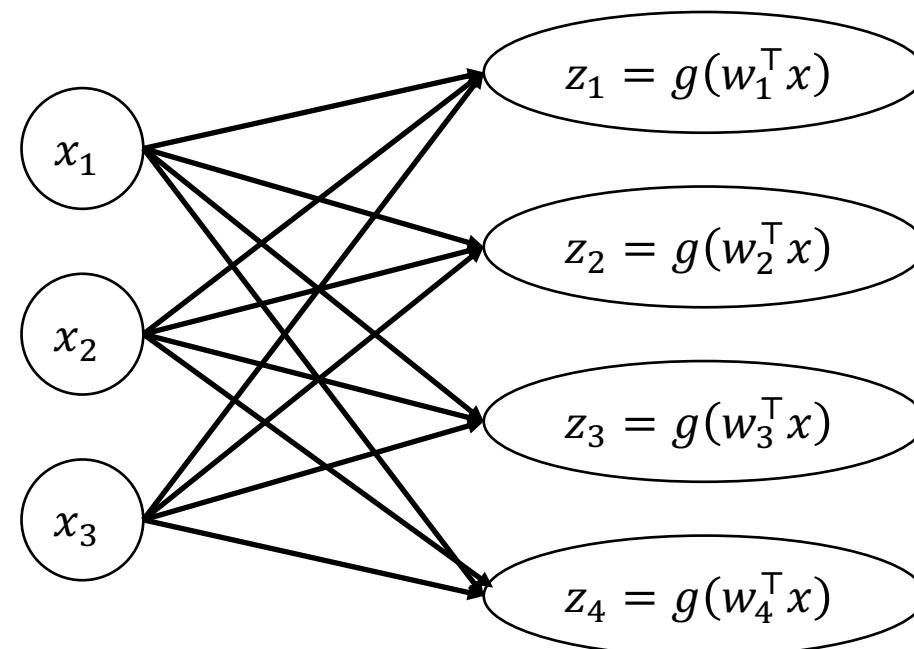
$$f_{W,\beta}(x) = Wx$$



# A Simple Neural Network

- Feedforward neural network model family (for regression):

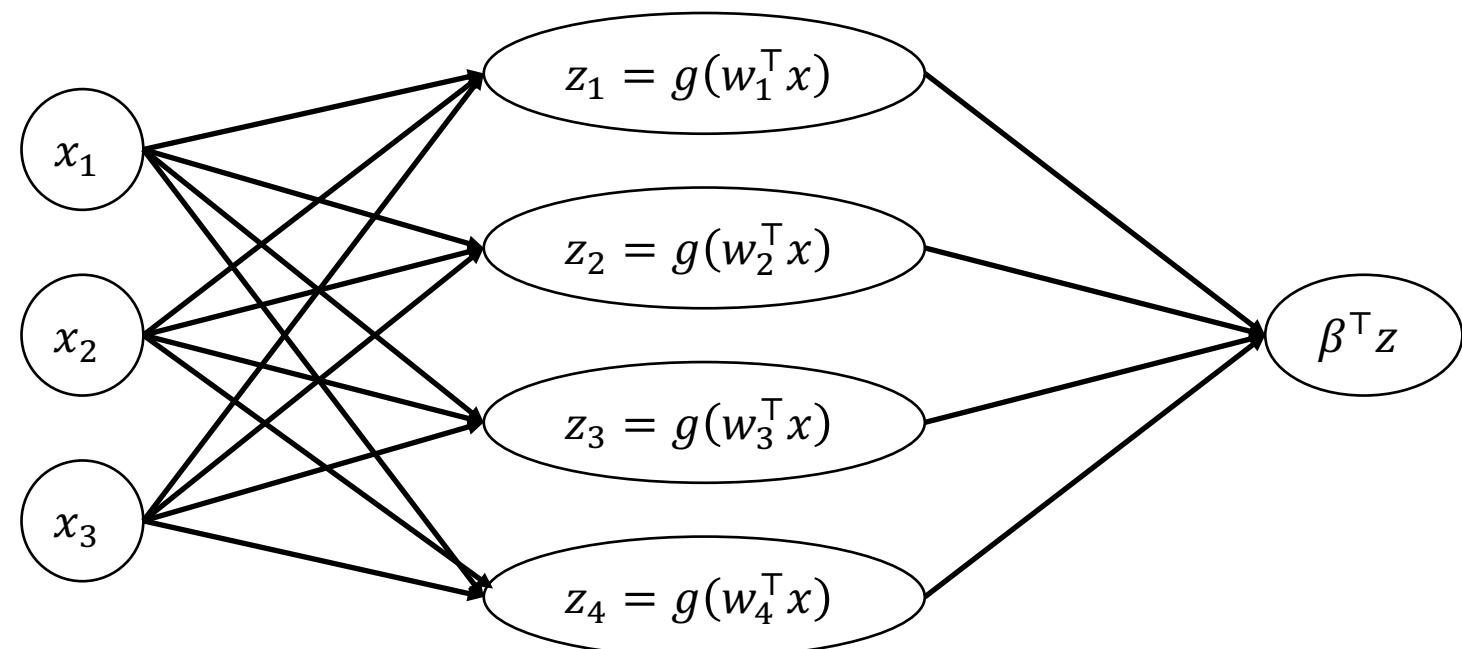
$$f_{W,\beta}(x) = g(Wx)$$



# A Simple Neural Network

- Feedforward neural network model family (for regression):

$$f_{W,\beta}(x) = \beta^T g(Wx)$$



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- What happens if  $g$  is linear?

# A Simple Neural Network

- Feedforward neural network model family (for regression):

$$f_{W,\beta}(\mathbf{x}) = \boldsymbol{\beta}^\top g(W\mathbf{x})$$

- What happens if  $g$  is linear? Recovers linear functions!
  - Special case of identity:

# A Simple Neural Network

- Feedforward neural network model family (for regression):

$$f_{W,\beta}(\textcolor{blue}{x}) = \beta^T g(W\textcolor{blue}{x})$$

- What happens if  $g$  is linear? Recovers linear functions!
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$$f_{W,\beta}(\textcolor{blue}{x}) = \beta^T g(W\textcolor{blue}{x})$$

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$$f_{W,\beta}(\mathbf{x}) = \boldsymbol{\beta}^\top g(W\mathbf{x}) = \boldsymbol{\beta}^\top W\mathbf{x}$$

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$$f_{W,\beta}(\textcolor{blue}{x}) = \beta^\top g(W\textcolor{blue}{x})$$

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  - Special case of identity:

$$f_{W,\beta}(\textcolor{blue}{x}) = \beta^\top g(W\textcolor{blue}{x}) = \beta^\top W\textcolor{blue}{x} = \tilde{\beta}^\top \textcolor{blue}{x}$$

# A Simple Neural Network

- Feedforward neural network model family (for regression):

$$f_{W,\beta}(\textcolor{blue}{x}) = \beta^\top g(W\textcolor{blue}{x})$$

- What happens if  $g$  is linear? Recovers linear functions!
  - Special case of identity:

$$f_{W,\beta}(\textcolor{blue}{x}) = \beta^\top g(W\textcolor{blue}{x}) = \beta^\top W\textcolor{blue}{x} = \tilde{\beta}^\top \textcolor{blue}{x}$$

- Using a nonlinearity is important!
  - **In general:** Linear regression over “features”  $g(W\textcolor{blue}{x})$

# What About Classification?

- **Recall:** For logistic regression, we choose the likelihood to be

$$p_{\beta}(Y = 1 \mid \textcolor{blue}{x}) = \frac{1}{1 + e^{-\beta^T \textcolor{blue}{x}}}$$

# What About Classification?

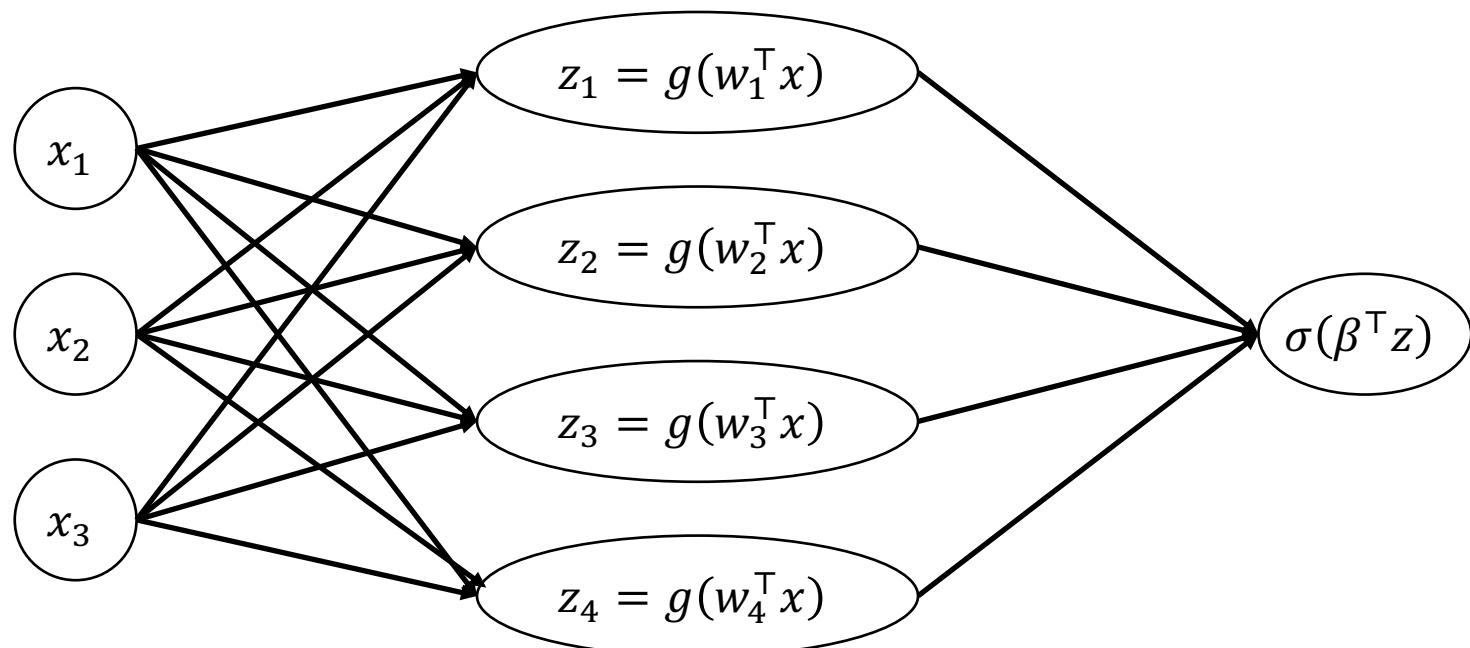
- **Recall:** For logistic regression, we choose the likelihood to be

$$p_{\beta}(Y = 1 \mid \textcolor{blue}{x}) = \sigma(\boldsymbol{\beta}^T \textcolor{blue}{x})$$

# What About Classification?

- For binary classification:

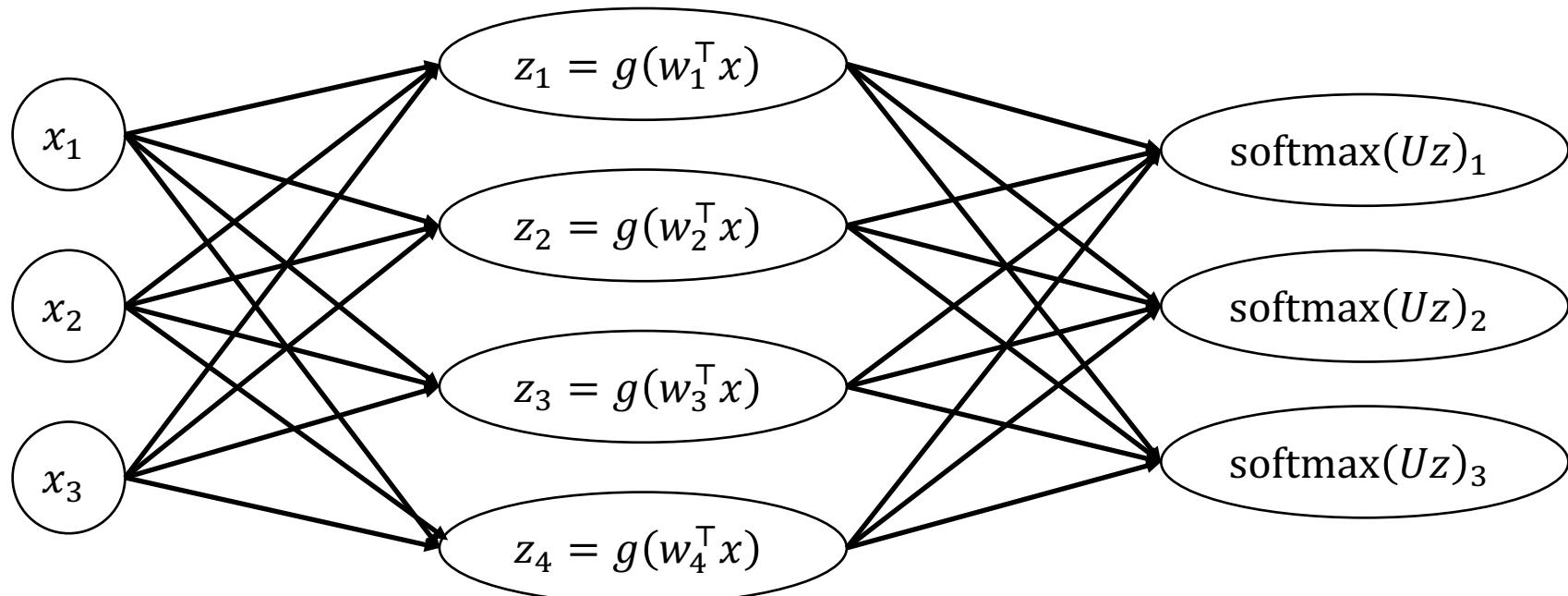
$$p_{W,\beta}(Y = 1 \mid \mathbf{x}) = \sigma(\boldsymbol{\beta}^\top g(\mathbf{W}\mathbf{x}))$$



# What About Classification?

- For multi-class classification:

$$p_{W,U}(Y = \mathbf{y} \mid \mathbf{x}) = \text{softmax}(\mathbf{U}g(\mathbf{W}\mathbf{x}))_{\mathbf{y}}$$



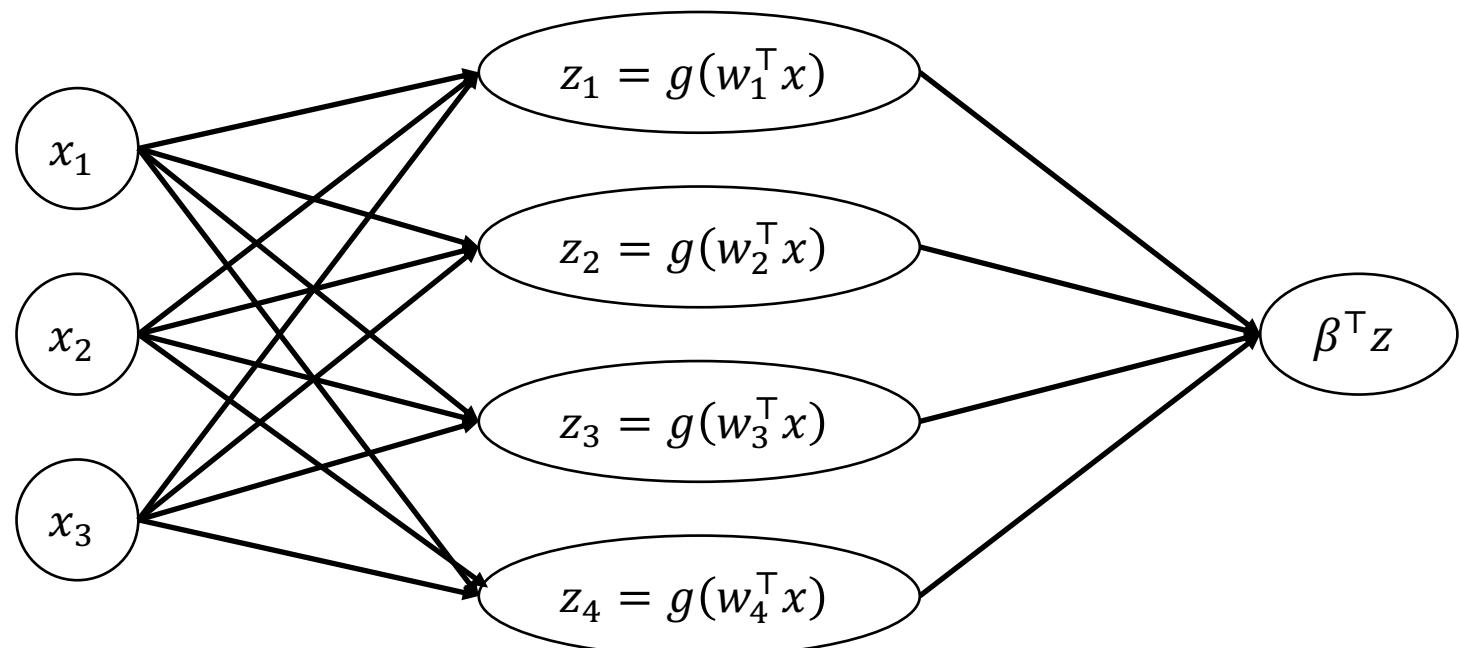
# Historical vs. Modern View

- **Historical view:** Specific model families
  - Feedforward neural networks, convolutional neural networks, etc.
  - Each new model family (“architecture”) requires a custom implementation
- **Modern view:** Design model families by composing building blocks
  - Building blocks are “layers”
  - Layers can be **programmatically** composed together (by composing, concatenating, etc.) to form different model families

# Historical View

- Feedforward neural network model family (for regression):

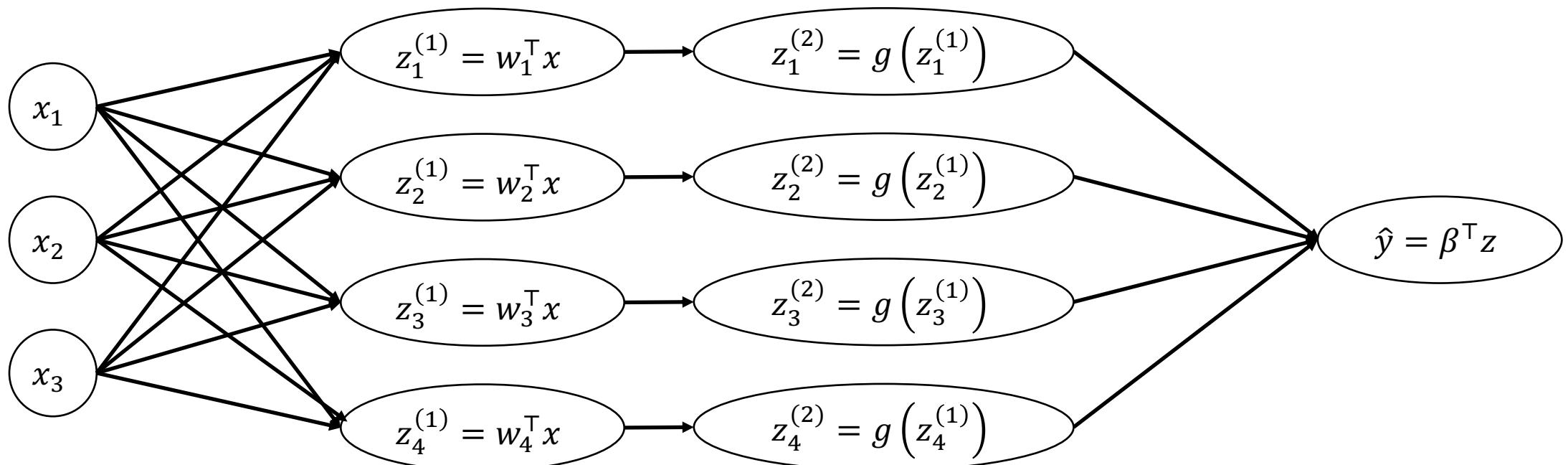
$$f_{W,\beta}(x) = \beta^T g(Wx)$$



# Modern View

- Feedforward neural network model family (for regression):

$$f_{W,\beta}(x) = f_\beta \left( g(f_W(x)) \right) = f_\beta \circ g \circ f_W(x)$$



# Modern View

- Each **layer** is a parametric function  $f_{W_j}: \mathbb{R}^k \rightarrow \mathbb{R}^h$  for some  $k, h$
- Compose sequentially to form model family:

$$f_W(x) = f_{W_m} \left( \dots \left( f_{W_1}(x) \right) \dots \right)$$

- We will use the following notation:

$$f_W = f_{W_m} \circ \dots \circ f_{W_1}$$

# Modern View

- Each **layer** is a parametric function  $f_{W_j}: \mathbb{R}^k \rightarrow \mathbb{R}^h$  for some  $k, h$
- Can compose layers in other ways, e.g., concatenation:

$$f_W(x) = f_{W_1}(x) \oplus f_{W_2}(x)$$

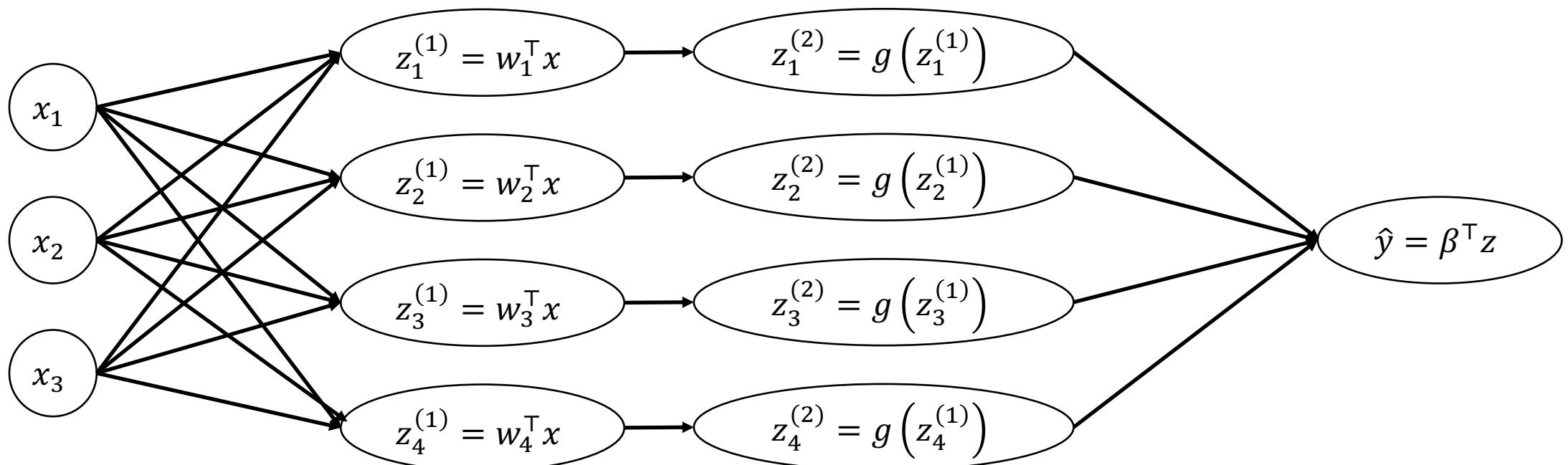
- Here, we have defined

$$[z_1 \quad \cdots \quad z_d]^\top \oplus [z'_1 \quad \cdots \quad z'_{d'}]^\top = [z_1 \quad \cdots \quad z_d \quad z'_1 \quad \cdots \quad z'_{d'}]^\top$$

# Modern View

- Feedforward neural network model family (for regression):

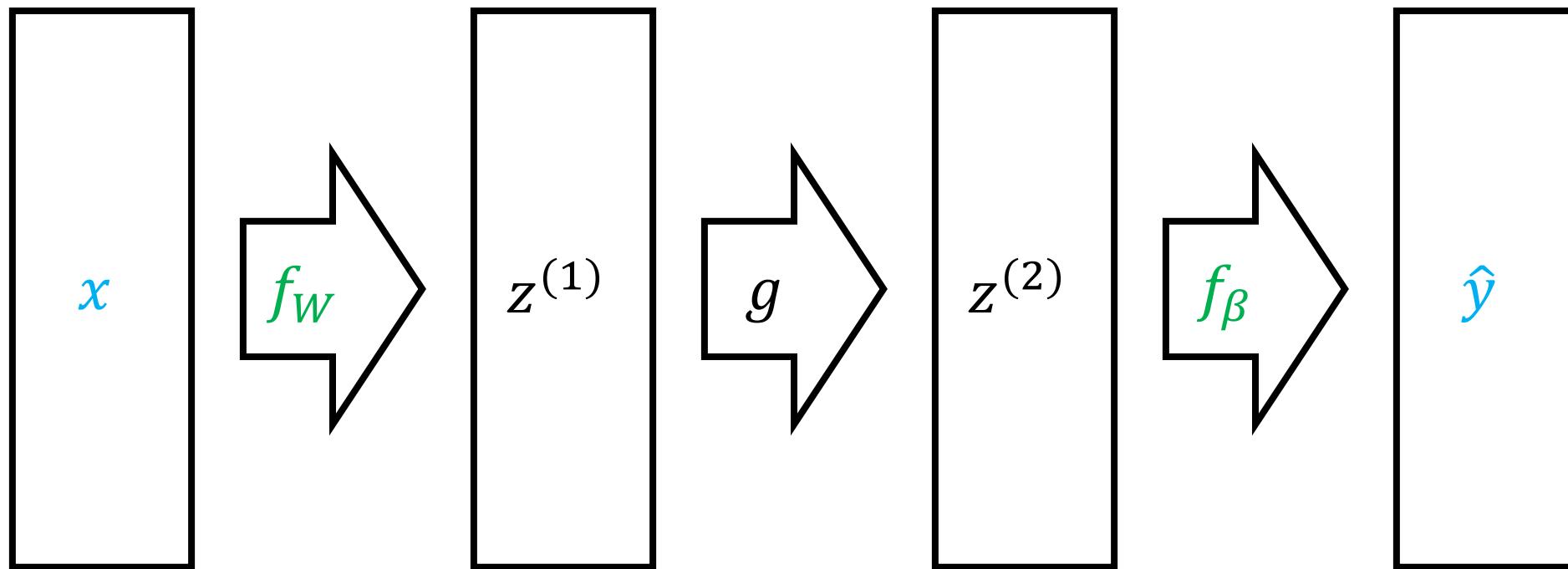
$$f_{W,\beta}(x) = f_\beta \circ g \circ f_W(x)$$



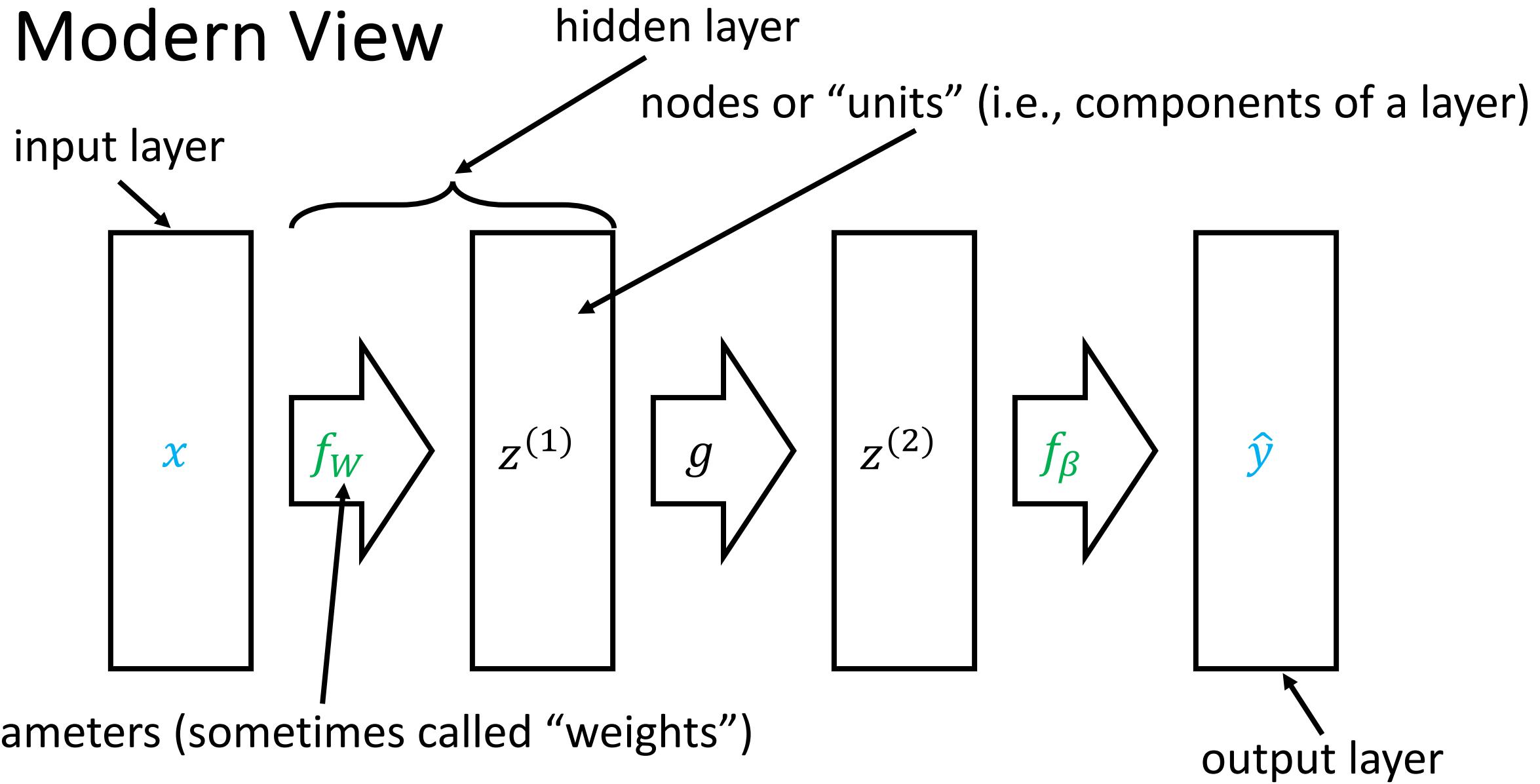
# Modern View

- Feedforward neural network model family (for regression):

$$f_{W,\beta}(x) = f_\beta \circ g \circ f_W(x)$$



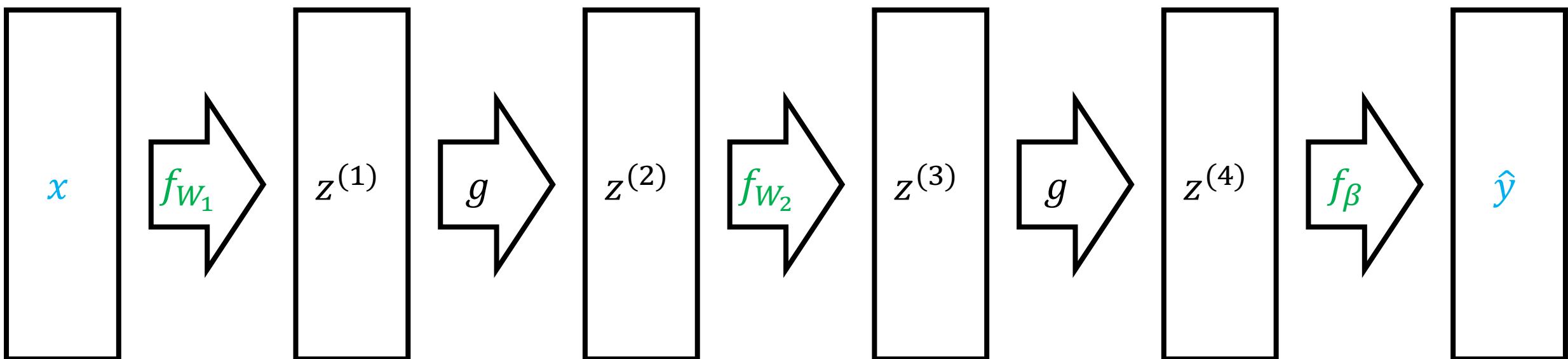
# Modern View



# Modern View

- Neural network with two hidden linear layers:

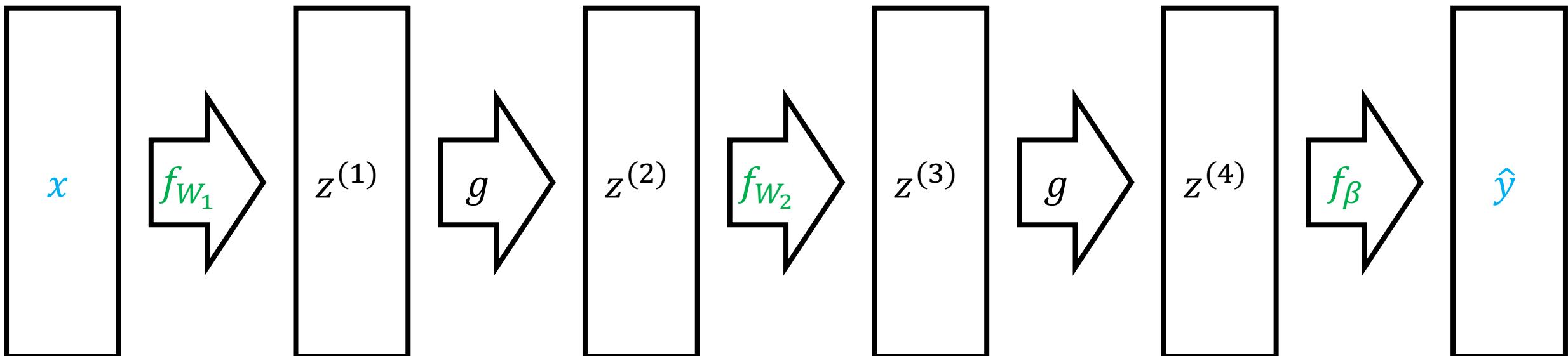
$$f_{W_1, W_2, \beta}(x) = f_\beta \circ g \circ f_{W_2} \circ g \circ f_{W_1}(x)$$



# Modern View

- Neural network with two hidden linear layers:

$$f_{W_1, W_2, \beta}(x) = f_\beta \left( g \left( f_{W_2} \left( g \left( f_{W_1}(x) \right) \right) \right) \right)$$



Learn successively more “high-level” representations

# Computing AND

$x_1$	$x_2$	$x_1$ AND $x_2$
0	0	0
0	1	0
1	0	0
1	1	1

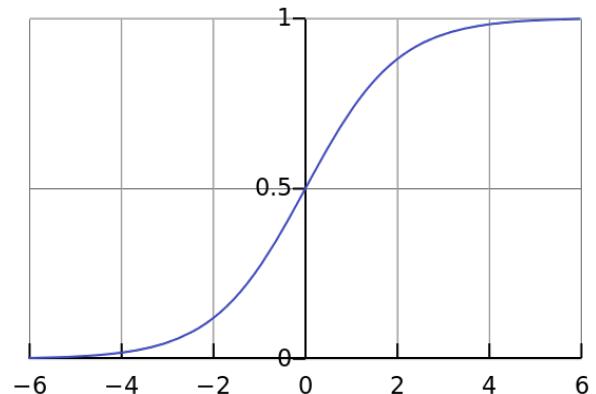
# Computing AND

$x_1$	$x_2$	$x_1$ AND $x_2$
0	0	0
0	1	0
1	0	0
1	1	1

$$f_{\beta}(x) = \sigma(-30 + 20x_1 + 20x_2)$$

# Computing AND

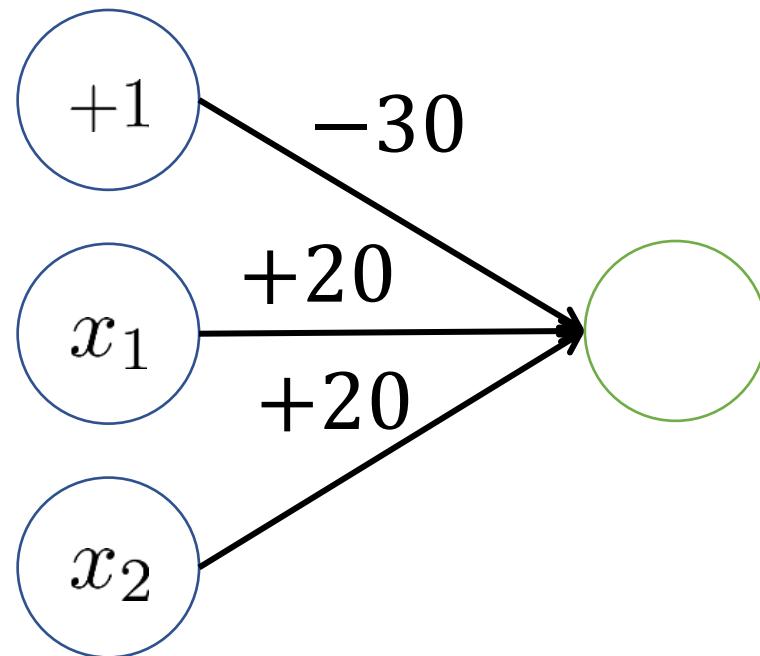
$x_1$	$x_2$	$x_1 \text{ AND } x_2$	$f_\beta(x)$
0	0	0	$\sigma(-30) \approx 0$
0	1	0	$\sigma(-10) \approx 0$
1	0	0	$\sigma(-10) \approx 0$
1	1	1	$\sigma(10) \approx 1$



$$f_\beta(x) = \sigma(-30 + 20x_1 + 20x_2)$$

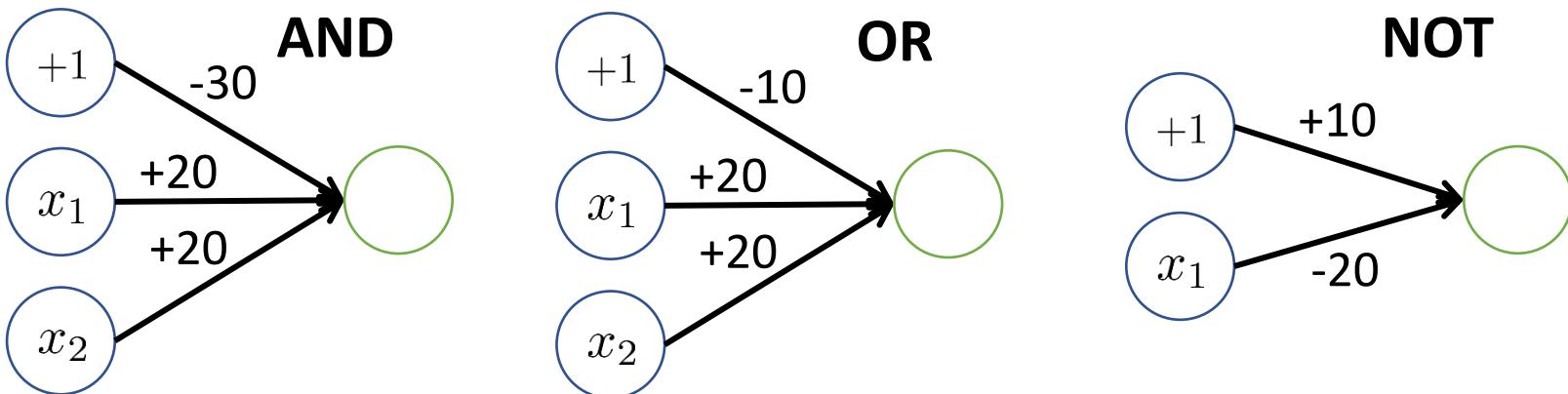
$$\sigma(x)$$

# Computing AND

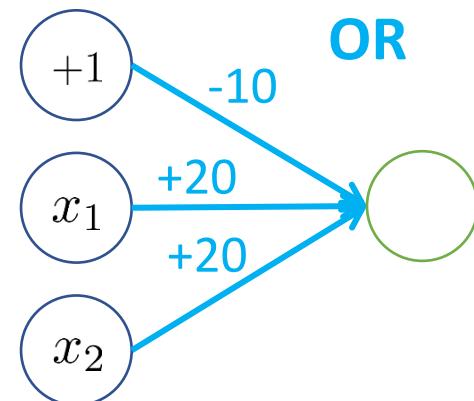
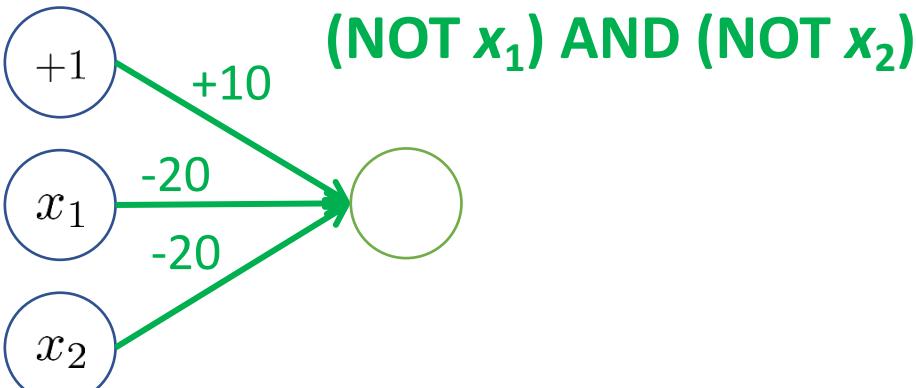
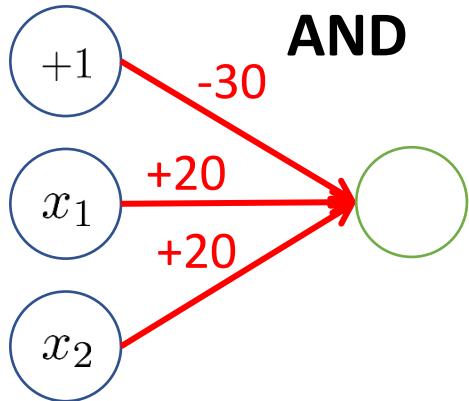


$$f_{\beta}(x) = \sigma(-30 + 20x_1 + 20x_2)$$

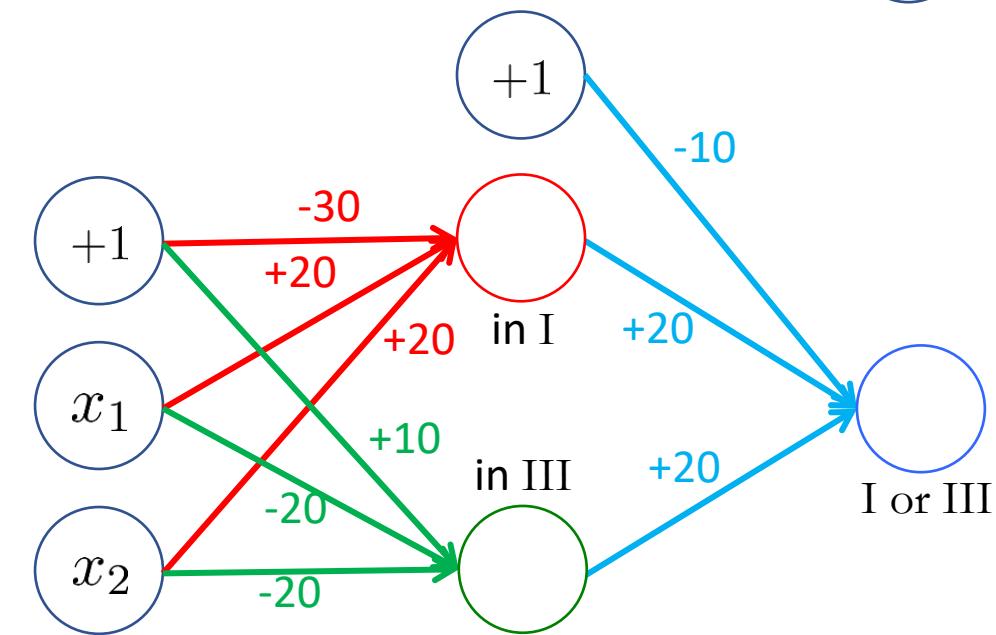
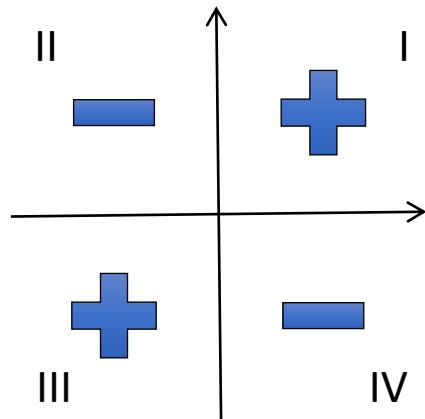
# Computing Boolean Functions



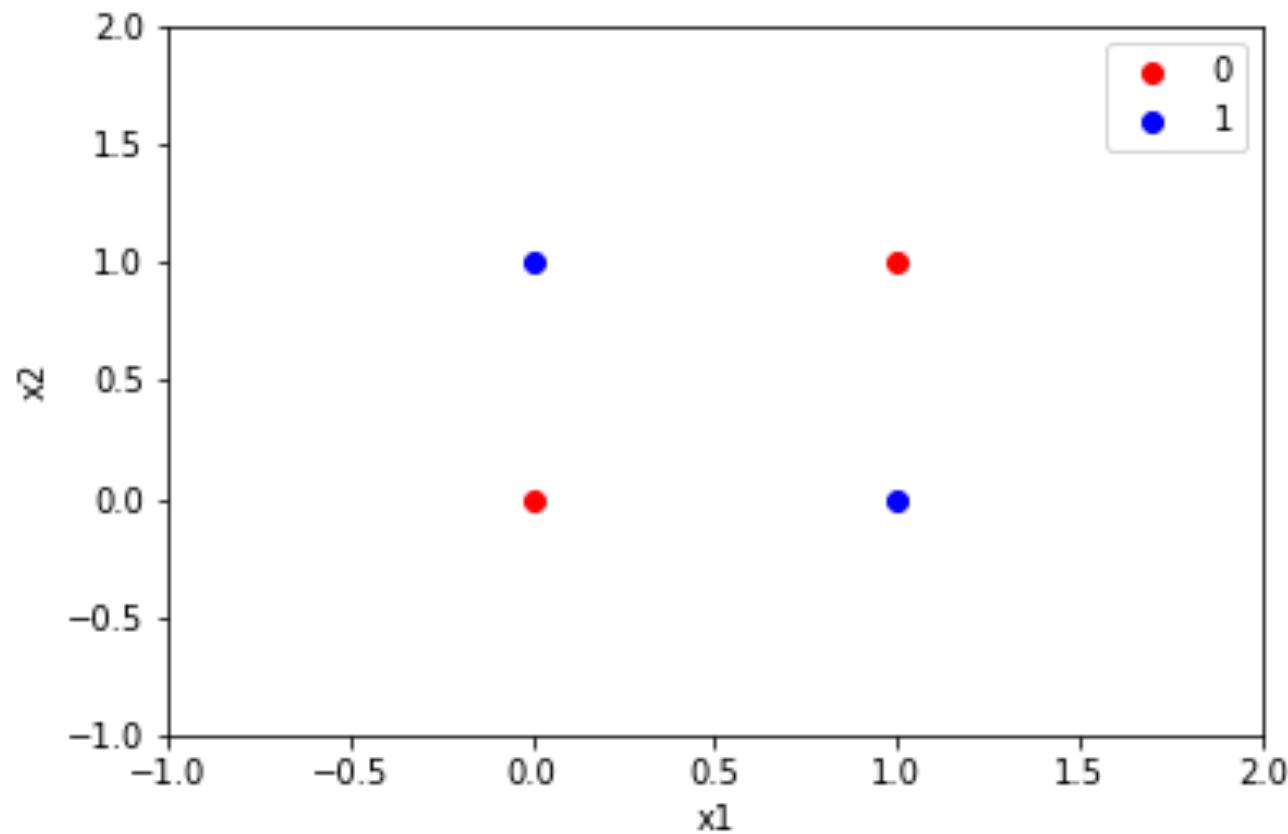
# Computing Boolean Functions



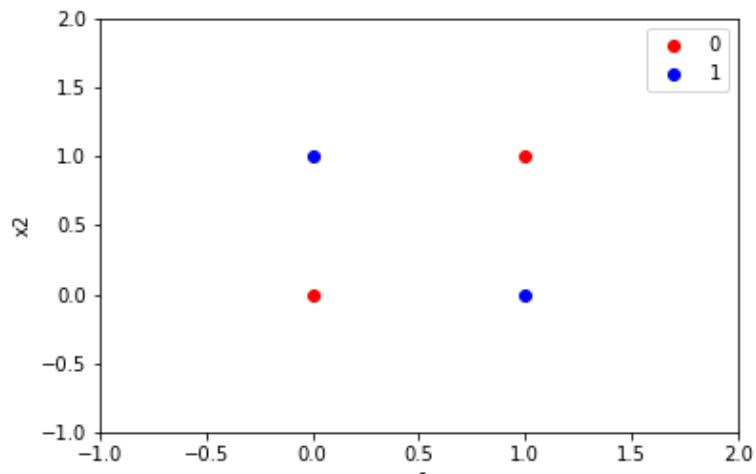
**NOT XOR**



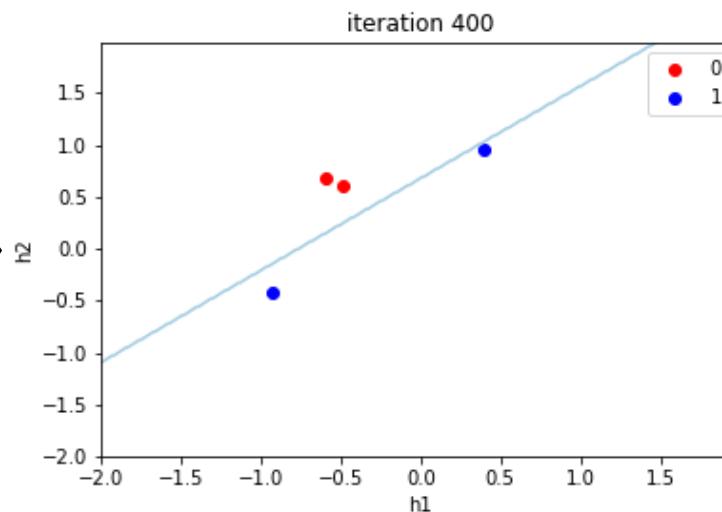
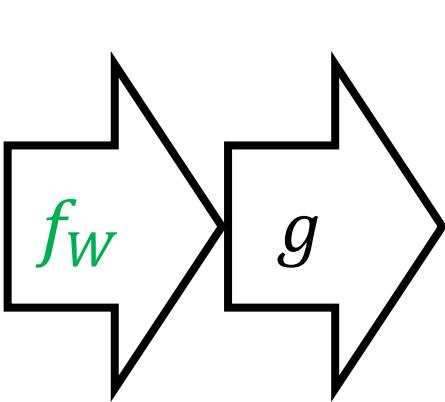
# Computing XOR



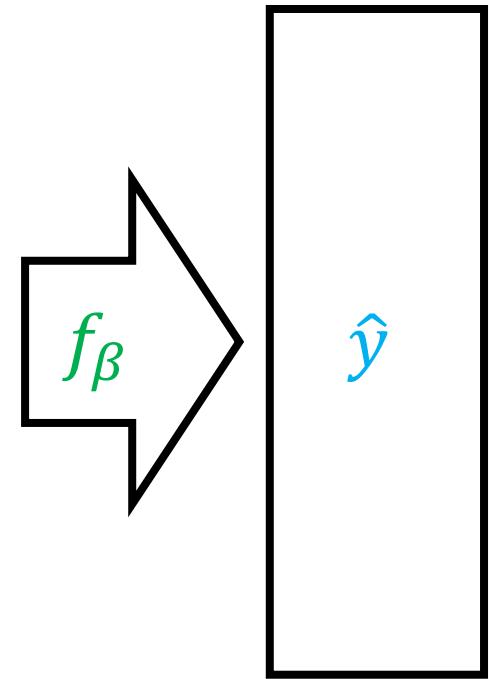
# Computing XOR



$x$



$z^{(2)}$



$\hat{y}$

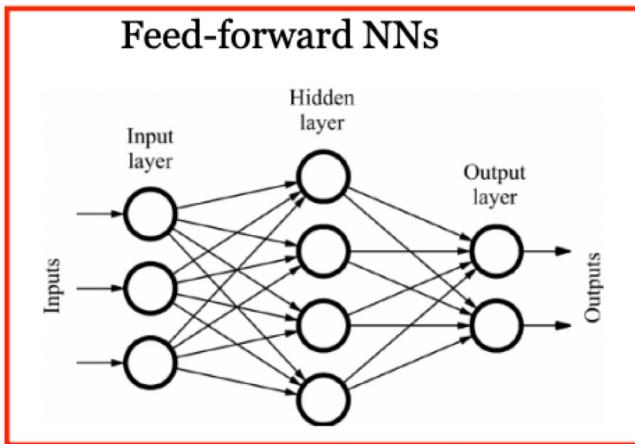
# Computing XOR

- **Before:**
  - Linear regression + feature engineering
  - Include quadratic features to compute XOR
- **Neural networks:**
  - Design architecture to capture function
  - Automatically learn good “features”  $\mathbf{z}^{(2)} = g(\mathbf{f}_W(\mathbf{x}))$  perform linear regression on these features  $\mathbf{f}_{W,\beta}(\mathbf{x}) = \boldsymbol{\beta}^\top \mathbf{z}^{(2)}$
  - Called **representation learning**

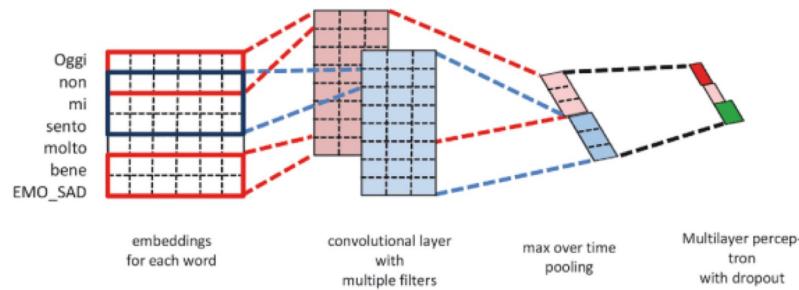
# Neural Networks

- **Pros**
  - “**Meta**” **strategy**: Enables users to **design** model family
  - Design model families that capture **symmetries/structure** in the data (e.g., read a sentence forwards, translation invariance for images, etc.)

# Common Layers

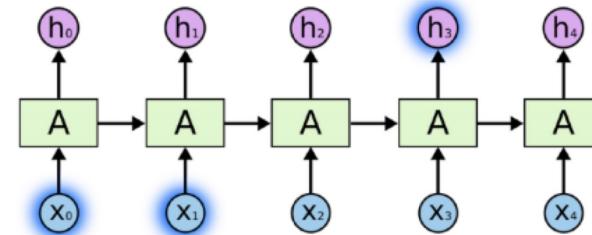


Convolutional NNs

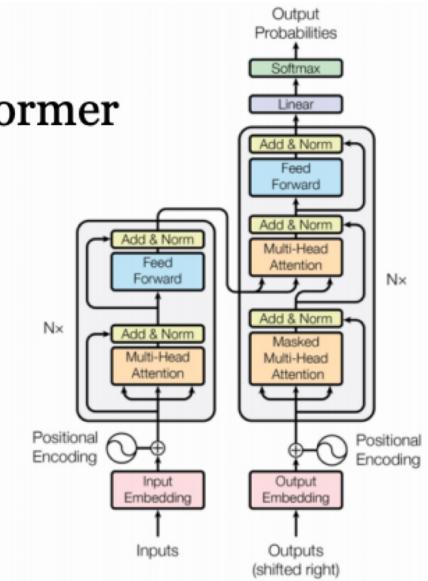


Always coupled with word embeddings...

Recurrent NNs



Transformer



# Neural Networks

- **Pros**
  - “**Meta**” **strategy**: Enables users to **design** model family
  - Design model families that capture **symmetries/structure** in the data (e.g., read a sentence forwards, translation invariance for images, etc.)
  - “Representation learning” (automatically learn features for certain domains)
  - More parameters!
- **Cons**
  - Very hard to train! (Non-convex loss functions)
  - Lots of parameters → need lots of data!
  - Lots of design decisions

# Agenda

- **Model family**
  - Custom model family rather than a single model family
- **Optimization**
  - Backpropagation algorithm for computing gradient

# Optimization Algorithm

- Based on gradient descent, with a few tweaks
  - **Note:** Loss is nonconvex, but gradient descent works well in practice
- **Key challenge:** How to compute the gradient?
  - **Strategy so far:** Work out gradient for every model family
  - **New strategy:** Algorithm for computing gradient of an arbitrary programmatic composition of layers
  - This algorithm is called **backpropagation**

# Gradient Descent

- $W_1 \leftarrow \text{Initialize}()$
- **for**  $t \in \{1, 2, \dots\}$  **until** convergence:

$$W_{t+1,j} \leftarrow W_{t,j} - \frac{\alpha}{n} \cdot \sum_{i=1}^n \nabla_{W_j} L(f_{W_t}(x_i), y_i) \quad (\text{for each } j)$$

- **return**  $f_{W_t}$

# Backpropagation

- **Input**
  - Example-label pair  $(x, y)$
  - Arbitrary model  $f_{W_m} \circ \dots \circ f_{W_1}$
  - Loss  $L(\hat{y}, y)$  for predicted label  $\hat{y}$  and true label  $y$
  - Derivative  $\nabla_{\hat{y}} L(\hat{y}, y)$  **(as a function)**
  - Derivatives  $D_{W_j} f_{W_j}(z)$  and  $D_z f_{W_j}(z)$  **(e.g., as a function)**
- **Output:**  $\nabla_{W_j} L(f_W(x), y)$

# Recall: Multi-Dimensional Derivatives

- **Given:**
  - Function  $f_W(z)$  mapping parameters  $W \in \mathbb{R}^d$  and input vector  $z \in \mathbb{R}^k$  to a vector  $f_W(z) \in \mathbb{R}^h$
  - Current parameters  $W$  and  $z$
- The **derivative** of  $f_W$  at  $W$  and  $z$  with respect to  $z$  is a matrix

$$D_z f_W(z) \in \mathbb{R}^{h \times k}$$

# Recall: Multi-Dimensional Derivatives

- **Given:**
  - Function  $f_W(z)$  mapping parameters  $W \in \mathbb{R}^d$  and input vector  $z \in \mathbb{R}^k$  to a vector  $f_W(z) \in \mathbb{R}^h$
  - Current parameters  $W$  and  $z$
- The **derivative** of  $f_W$  at  $W$  and  $z$  with respect to  $W$  is a matrix

$$D_W f_W(z) \in \mathbb{R}^{h \times d}$$

# Recall: Multi-Dimensional Derivatives

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  - Current parameters  $W$  and  $z$
- **Intuition:** The linear function that best approximates  $f_W$  at  $W$  and  $z$ :

$$f_{W+\textcolor{blue}{d}W}(z + \textcolor{blue}{dz}) \approx f_W(z) + \textcolor{green}{D}_z f_W(z) \textcolor{blue}{dz} + \textcolor{blue}{D}_W f_W(z) dW$$

# Backpropagation Example

- Gradient of MSE loss (for regression):

$$\begin{aligned}\nabla_{\mathbf{W}} L(\mathbf{W}, \boldsymbol{\beta}; \mathbf{Z}) &= \nabla_{\mathbf{W}} \frac{1}{n} \sum_{i=1}^n (\mathbf{f}_{\mathbf{W}, \boldsymbol{\beta}}(\mathbf{x}_i) - \mathbf{y}_i)^2 \\ &= \frac{2}{n} \sum_{i=1}^n (\mathbf{f}_{\mathbf{W}, \boldsymbol{\beta}}(\mathbf{x}_i) - \mathbf{y}_i) D_{\mathbf{W}} \mathbf{f}_{\mathbf{W}, \boldsymbol{\beta}}(\mathbf{x}_i)\end{aligned}$$

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# Backpropagation Example

- **Derivative of neural network:**

$$\begin{aligned} D_{\beta} f_{W,\beta}(x) &= D_{\beta}(f_{\beta} \circ g \circ f_W)(x) \\ &= D_{\beta} f_{\beta}(g \circ f_W(x)) \end{aligned}$$

$$\begin{aligned} D_W f_{W,\beta}(x) &= D_W(f_{\beta} \circ g \circ f_W)(x) \\ &= D_z f_{\beta}(g \circ f_W(x)) D_W(g \circ f_W)(x) \\ &= D_z f_{\beta}(g \circ f_W(x)) D_z g(f_W(x)) D_W f_W(x) \end{aligned}$$

# Backpropagation

- **General case:** Consider a neural network

$$f_W(\textcolor{blue}{x}) = f_{W_m} \circ f_{W_{m-1}} \circ \cdots \circ f_{W_1}(\textcolor{blue}{x})$$

$$\textcolor{blue}{z}^{(j)} = f_{W_j} \circ \cdots \circ f_{W_1}(\textcolor{blue}{x}) = \begin{cases} \textcolor{blue}{x} & \text{if } j = 0 \\ f_{W_j}(\textcolor{blue}{z}^{(j-1)}) & \text{if } j > 0 \end{cases}$$

- We have

$$D_{W_m} f_W(\textcolor{blue}{x})$$

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$$D_{W_{m-2}} f_W(\textcolor{blue}{x})$$

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# Backpropagation

- We have

$$D_{W_j} f_W(x) = D_z f_{W_m}(z^{(m-1)}) \dots D_z f_{W_{j+1}}(z^{(j)}) \underbrace{D_{W_j} f_{W_j}(z^{(j-1)})}_{\text{Portions shared across terms}} \quad \text{Denote it by } D^{(j)}$$

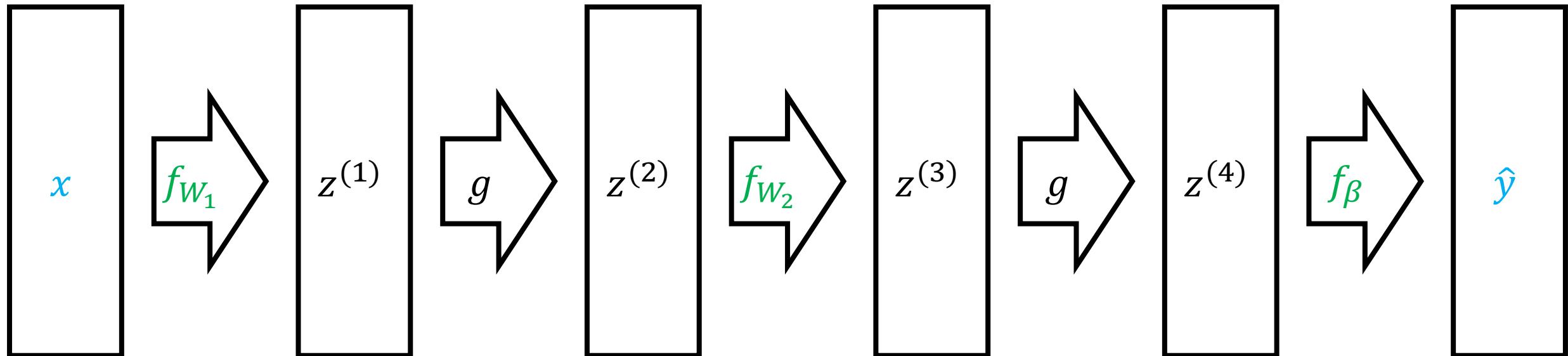
# Backpropagation Algorithm

- Compute recursively starting from  $j = m$  to  $j = 1$ :

$$\begin{aligned} D^{(j)} &= D_z f_{W_m}(z^{(m-1)}) \dots D_z f_{W_{j+1}}(z^{(j)}) \\ &= \begin{cases} 1 & \text{if } j = m \\ D^{(j+1)} D_z f_{W_{j+1}}(z^{(j)}) & \text{if } j < m \end{cases} \end{aligned}$$

$$D_{W_j} f_W(x) = D^{(j)} D_{W_j} f_{W_j}(z^{(j-1)})$$

# Backpropagation

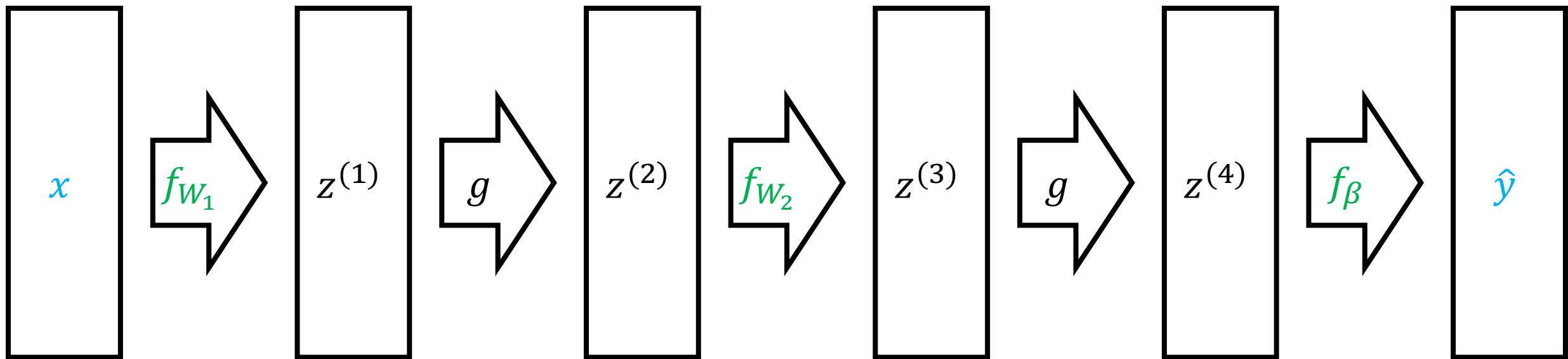


Forward pass: Compute  $z^{(j)} = f_{W_j}(z^{(j-1)})$

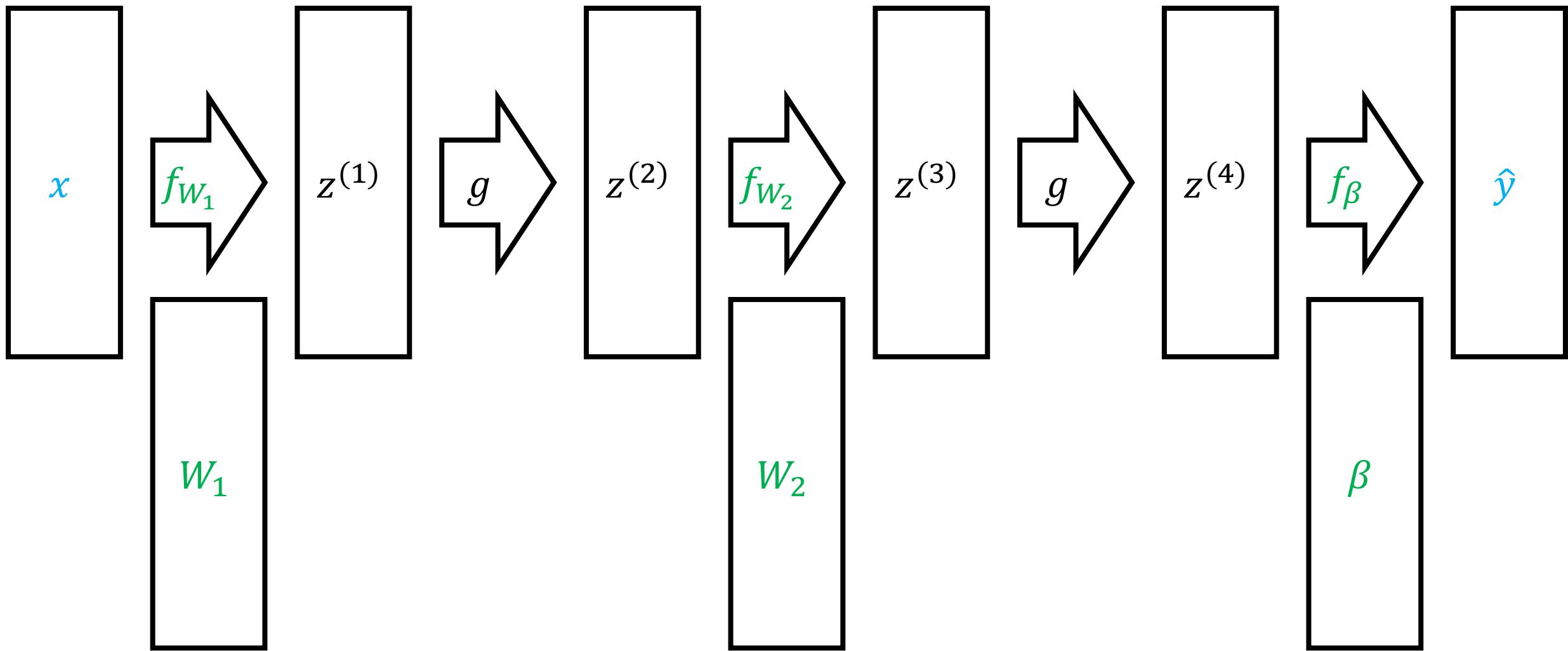
Backward pass: Compute  $D^{(j)} = D^{(j+1)}D_z f_{W_{j+1}}(z^{(j)})$  and  $D_{W_j} f_W(x) = D^{(j)} D_{W_j} f_{W_j}(z^{(j-1)})$

Final output:  $\nabla_{\hat{y}} L(z^{(m)}, y)^\top D_{W_j} f_W(x)$

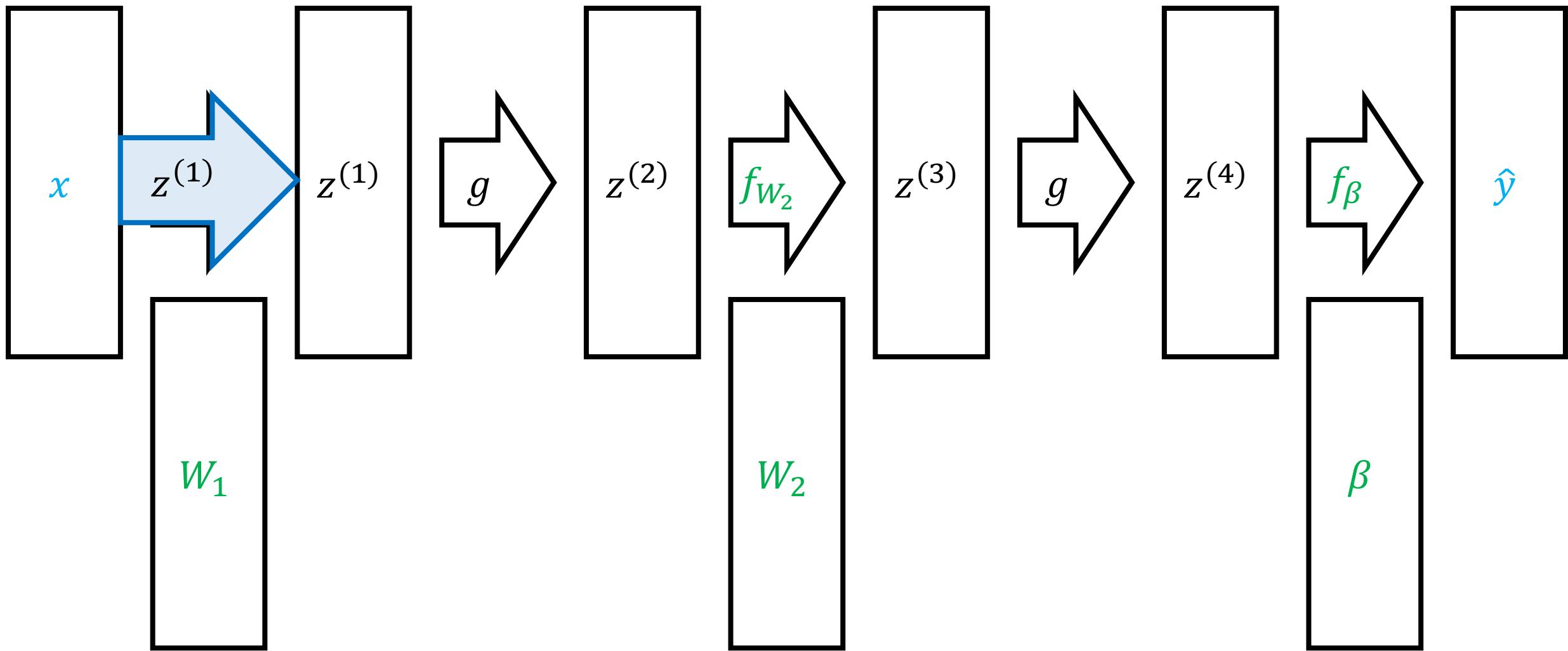
# Backpropagation



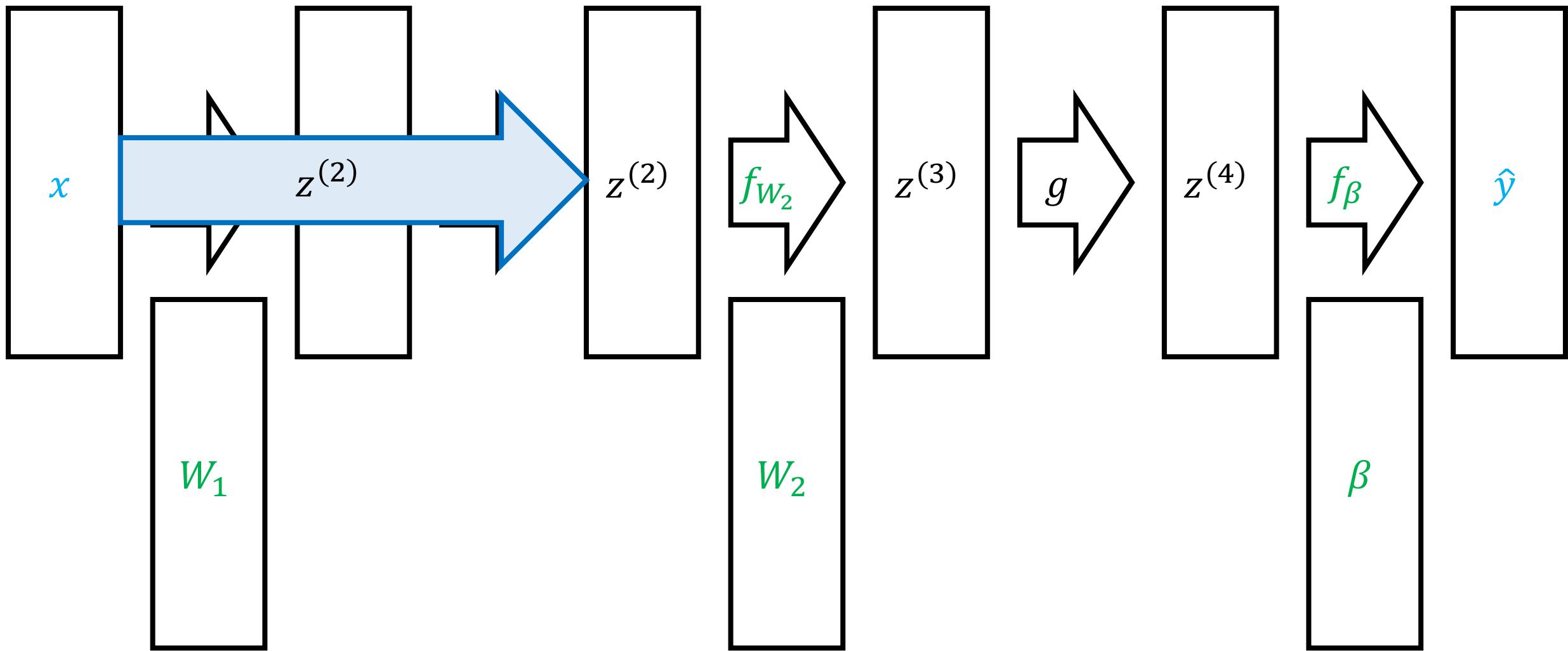
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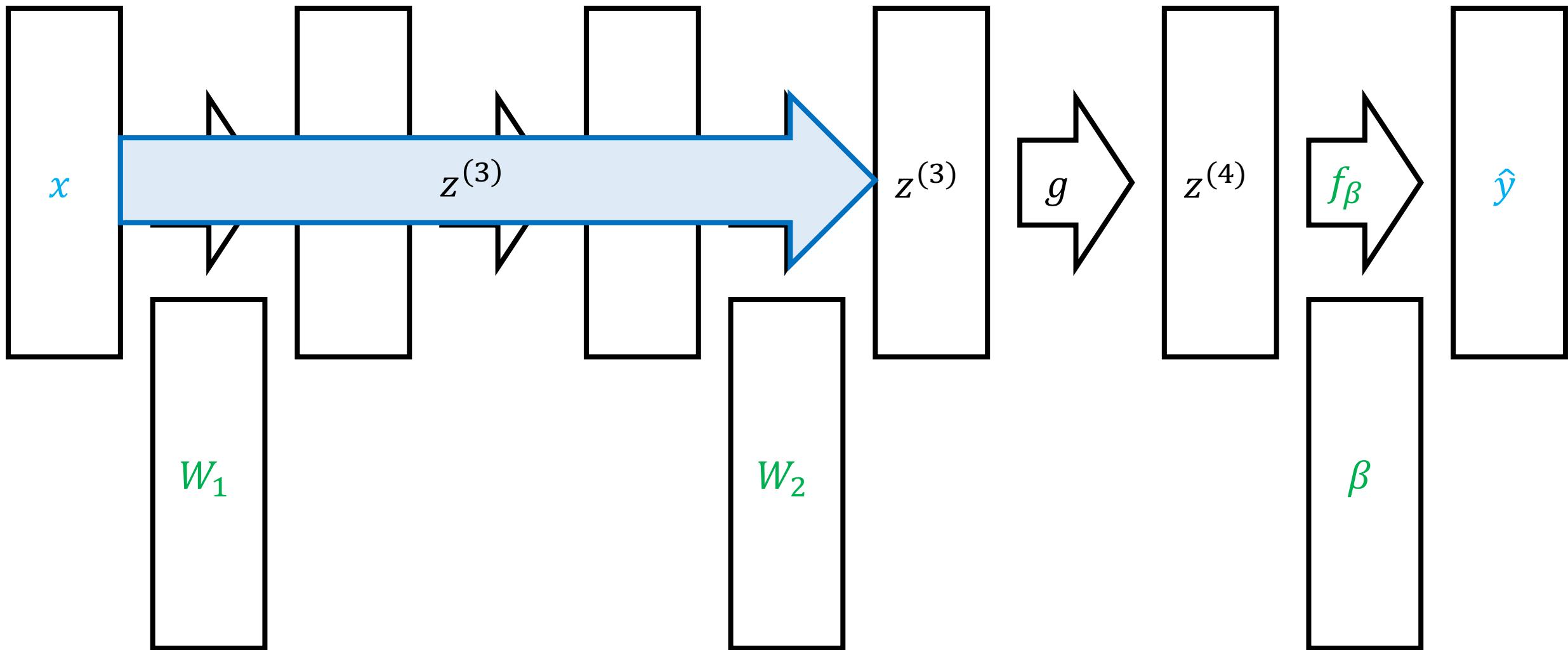
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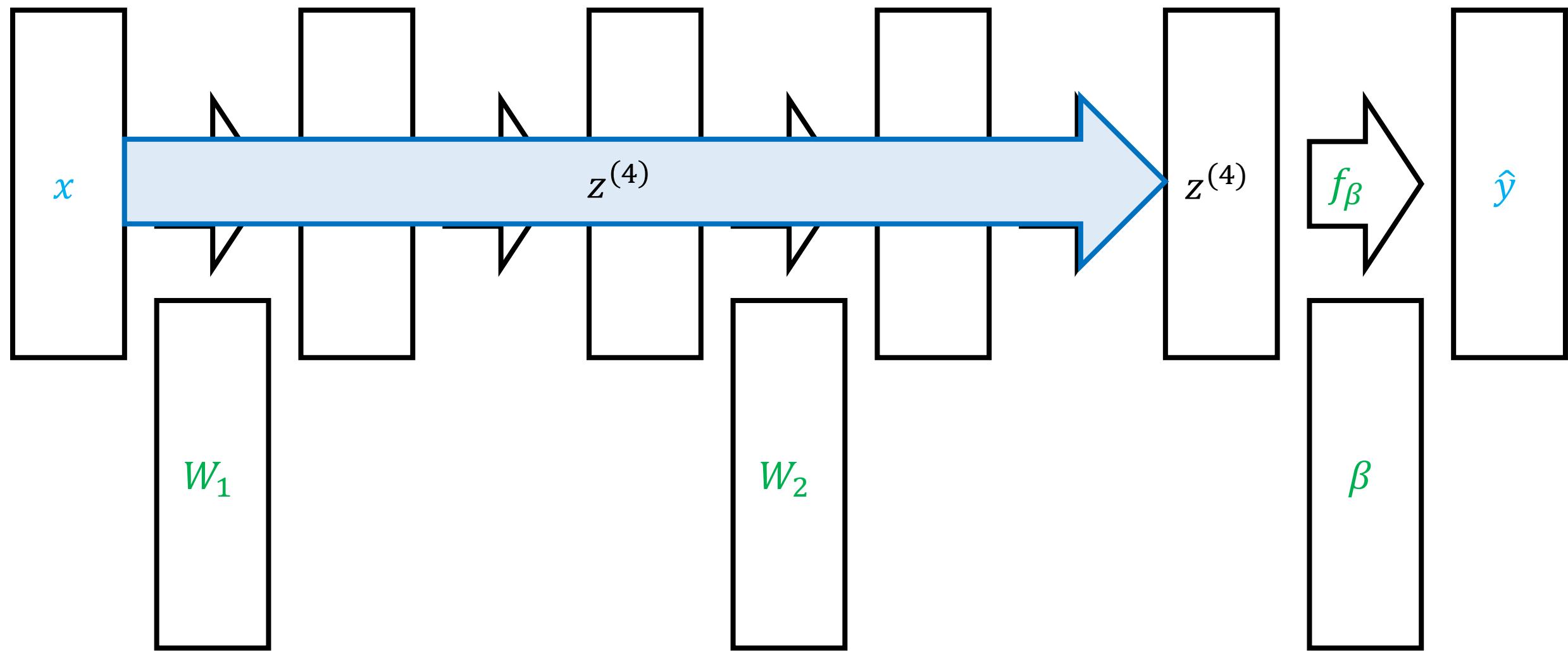
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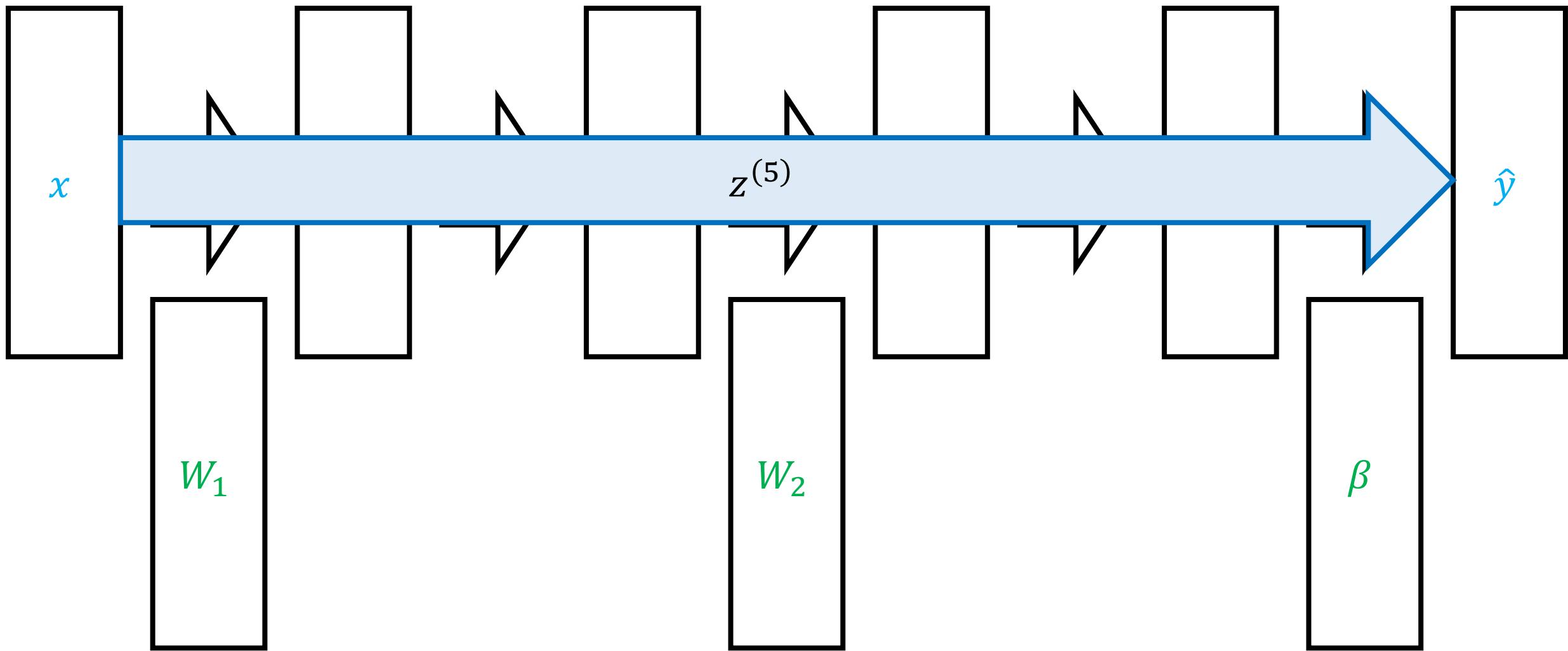
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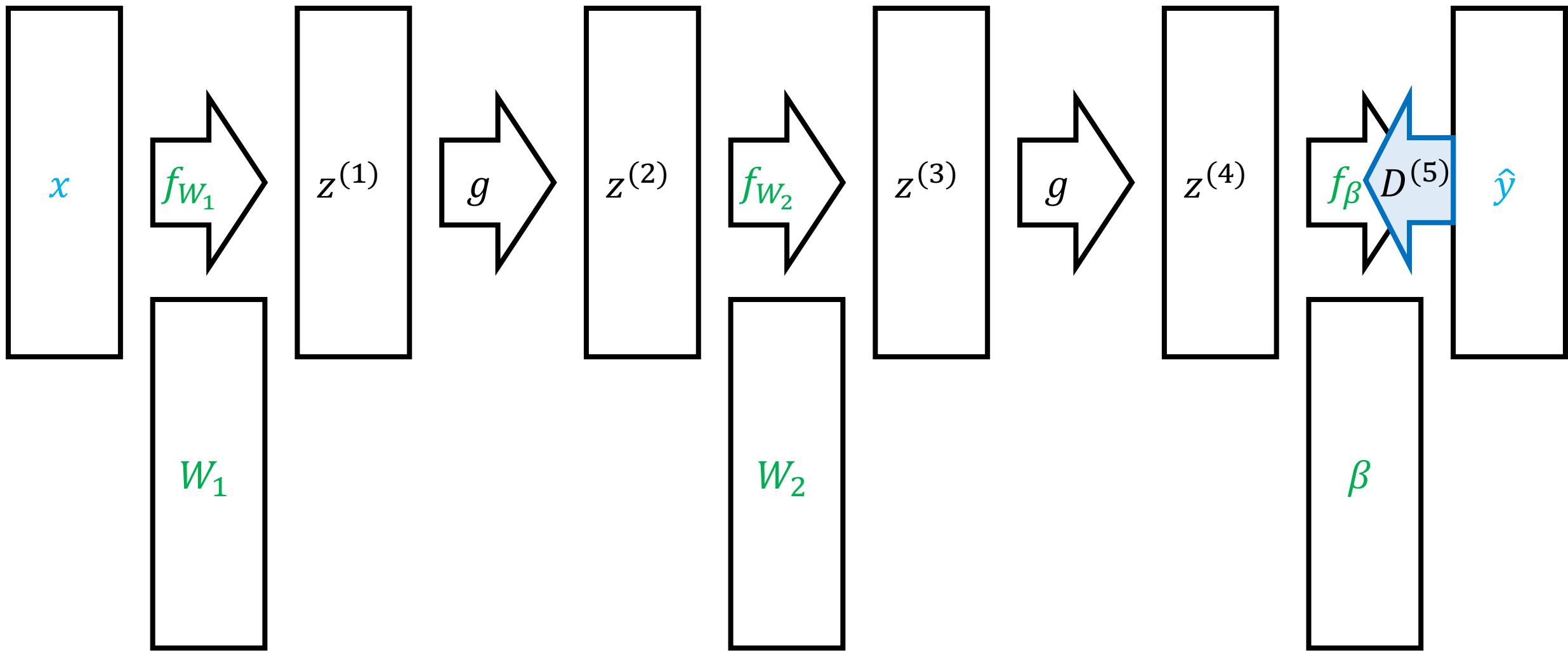
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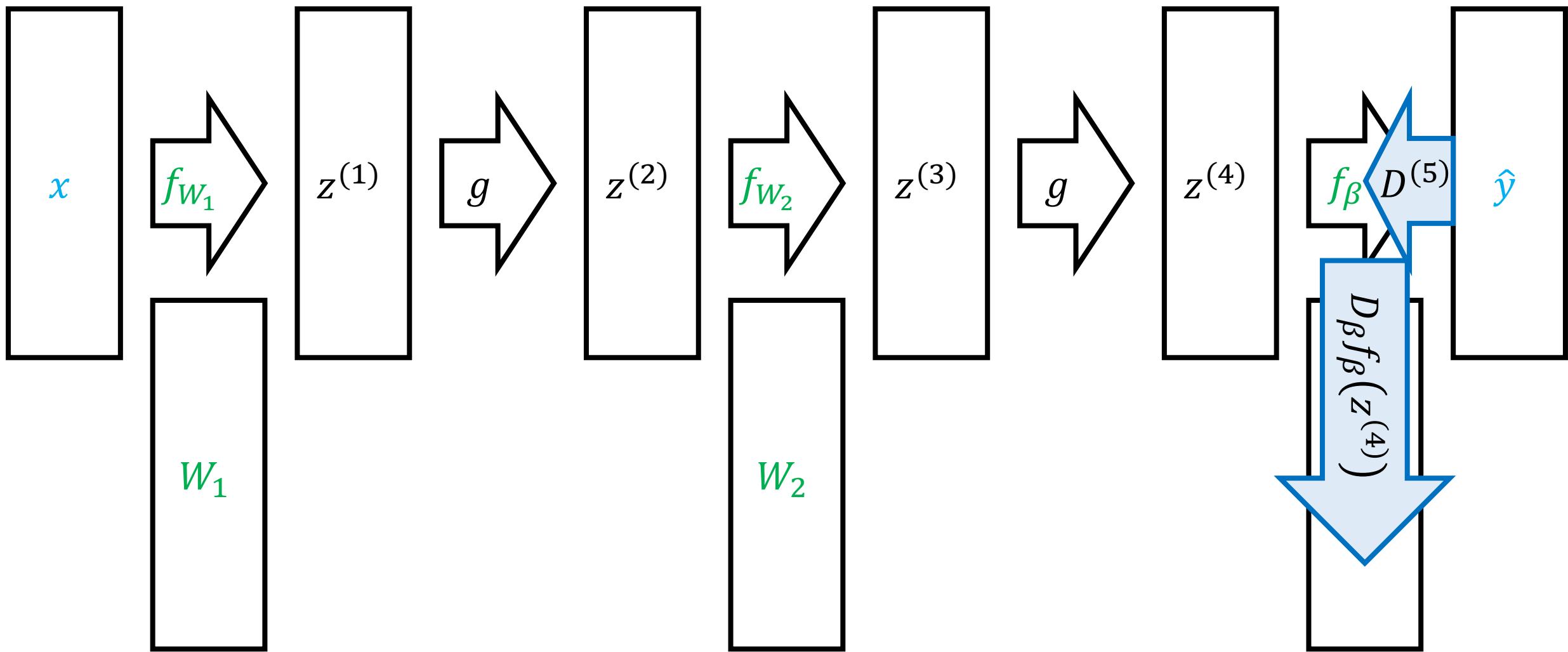
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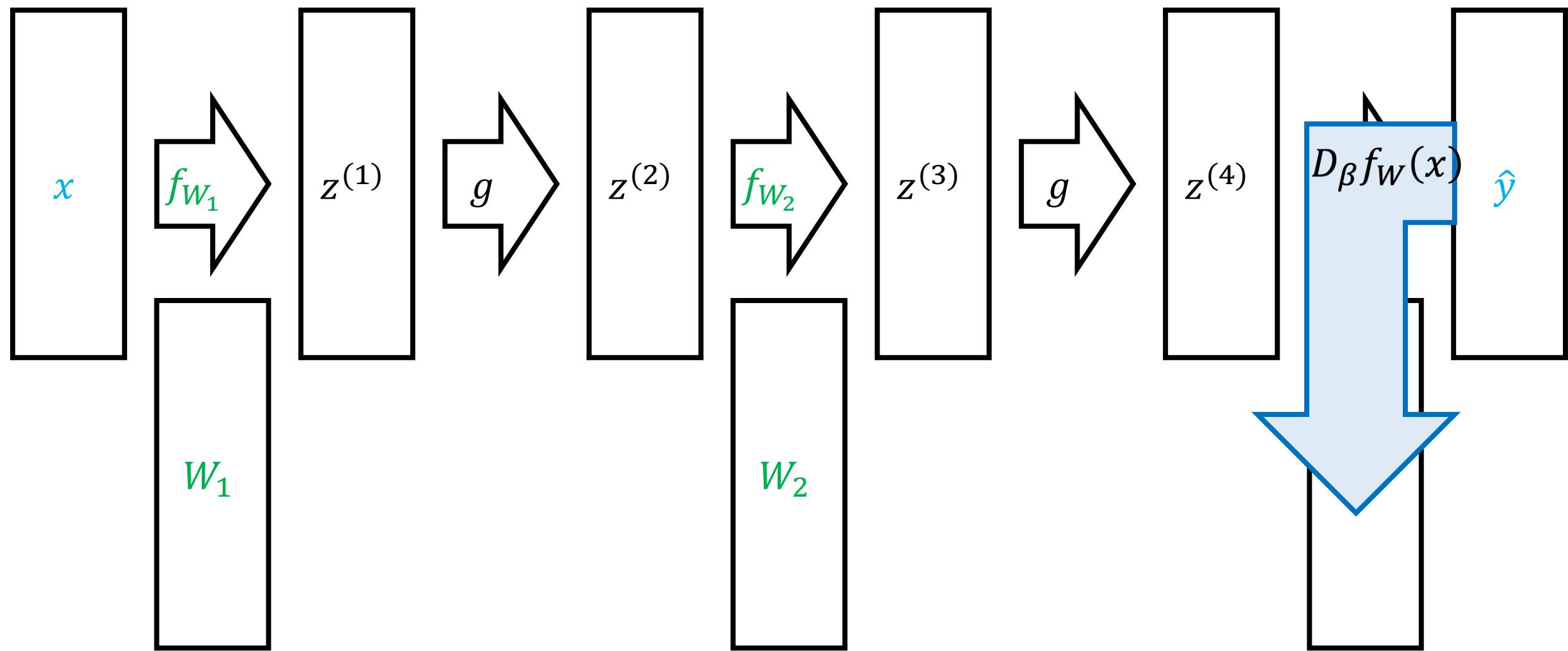
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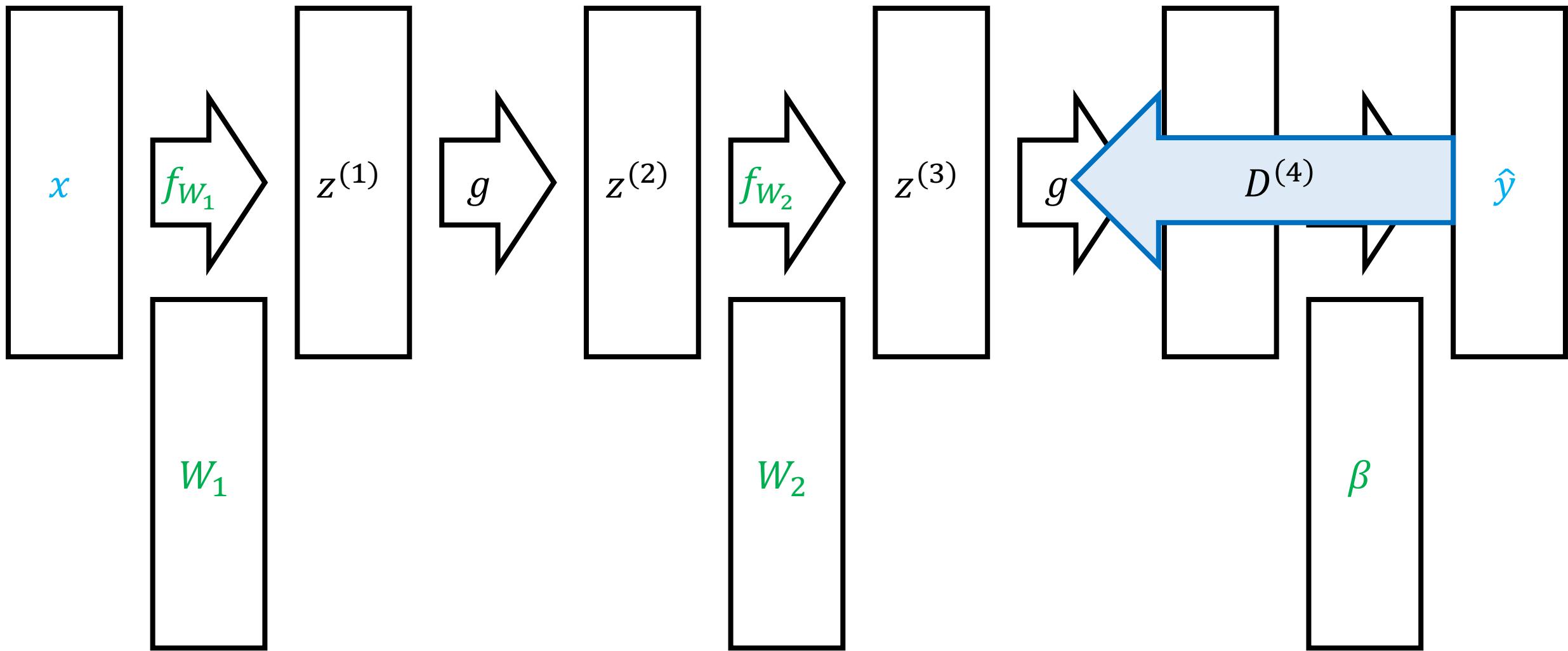
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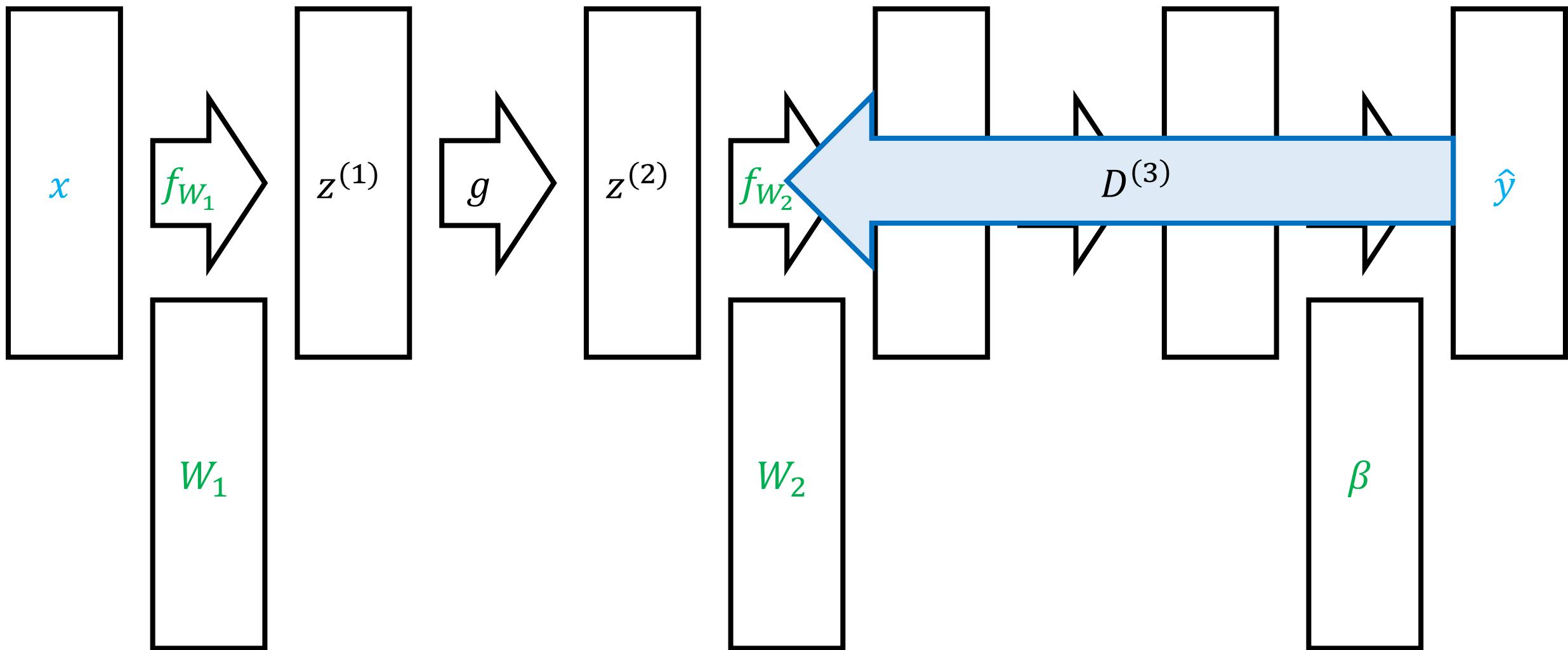
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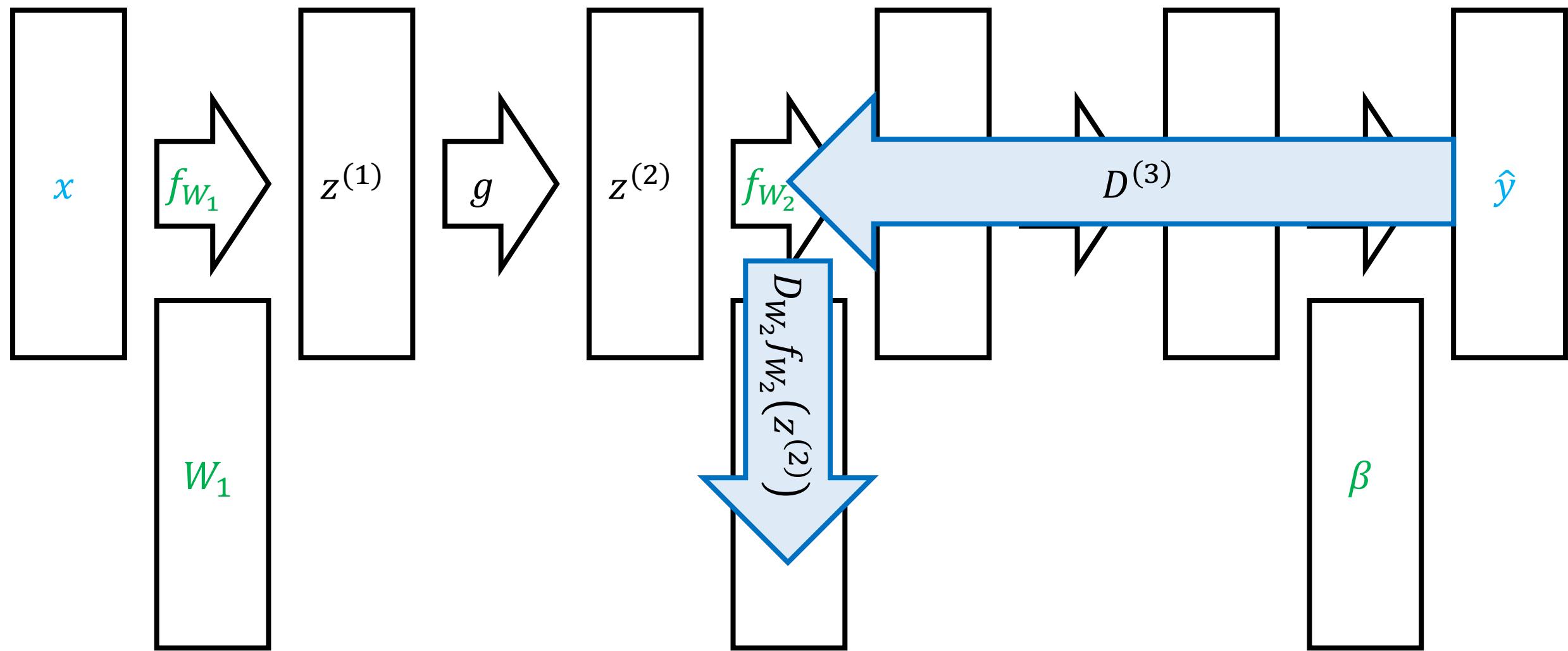
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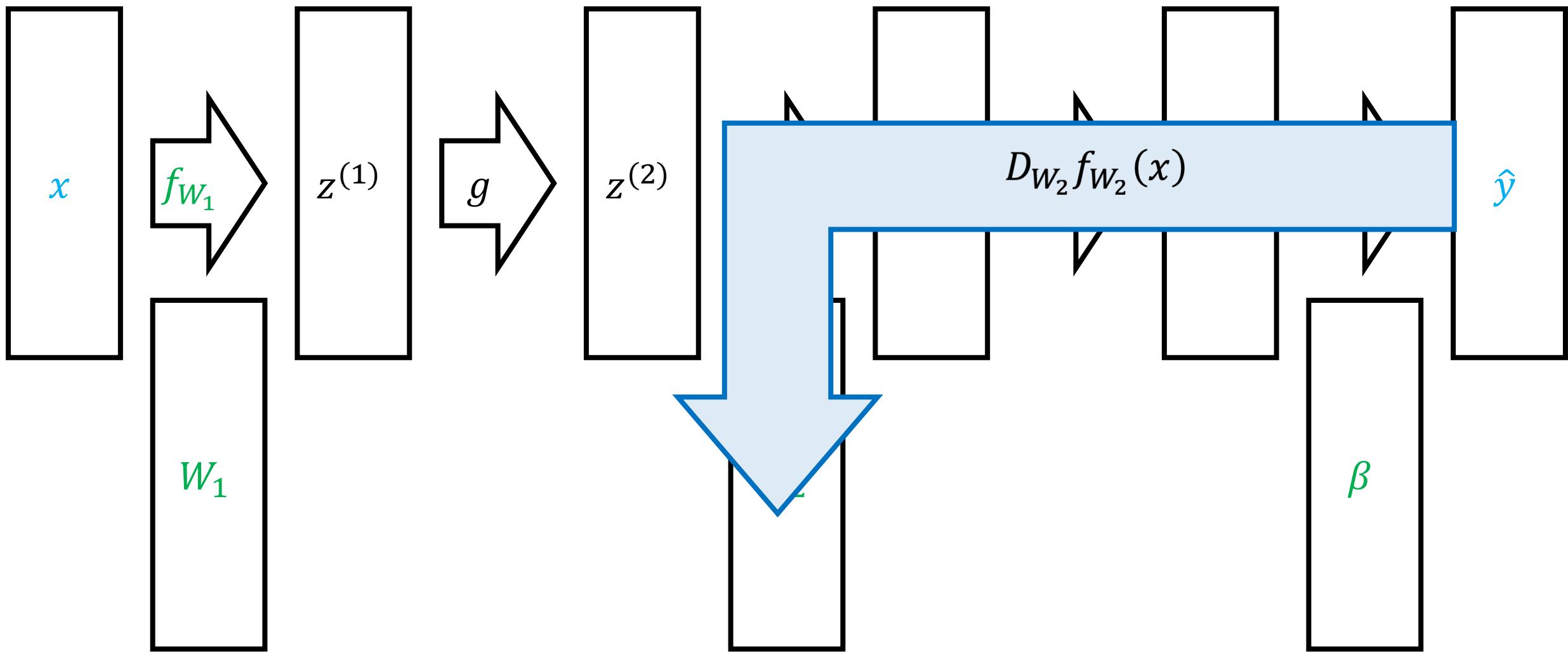
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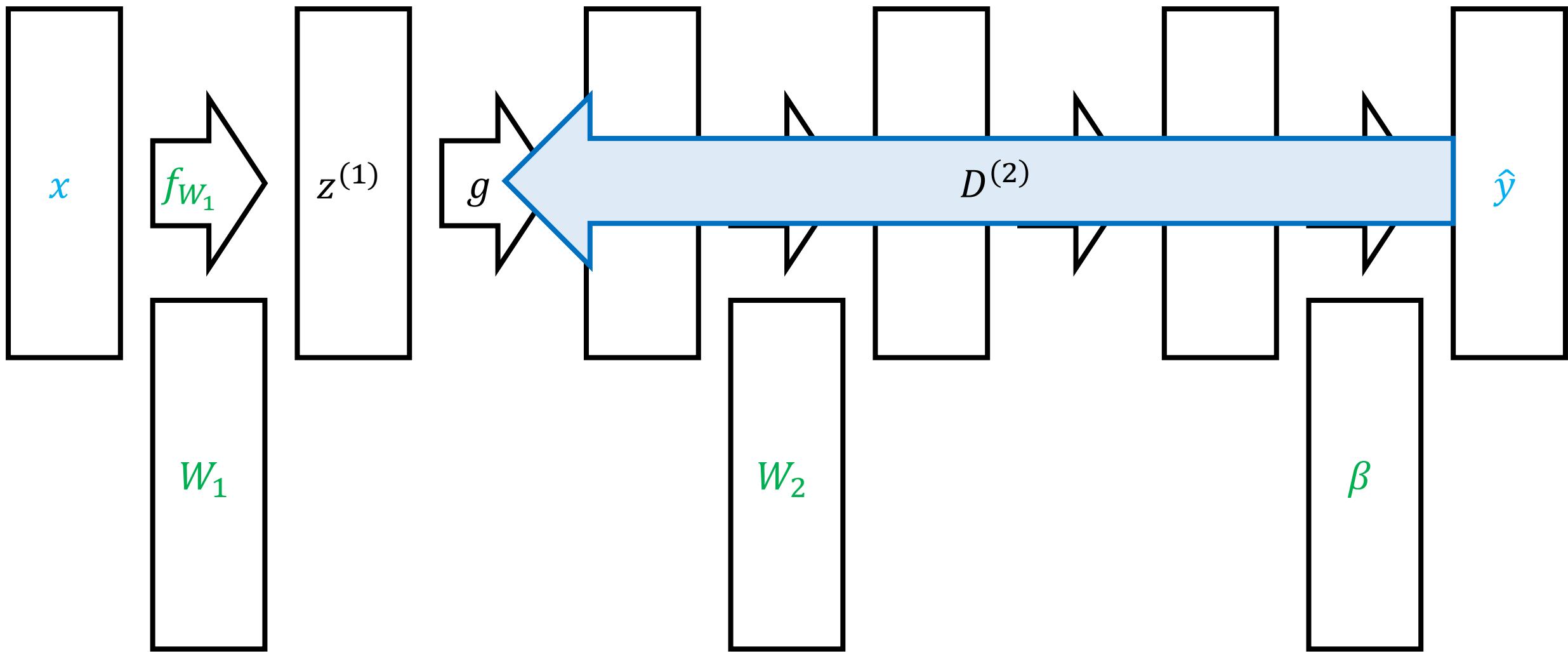
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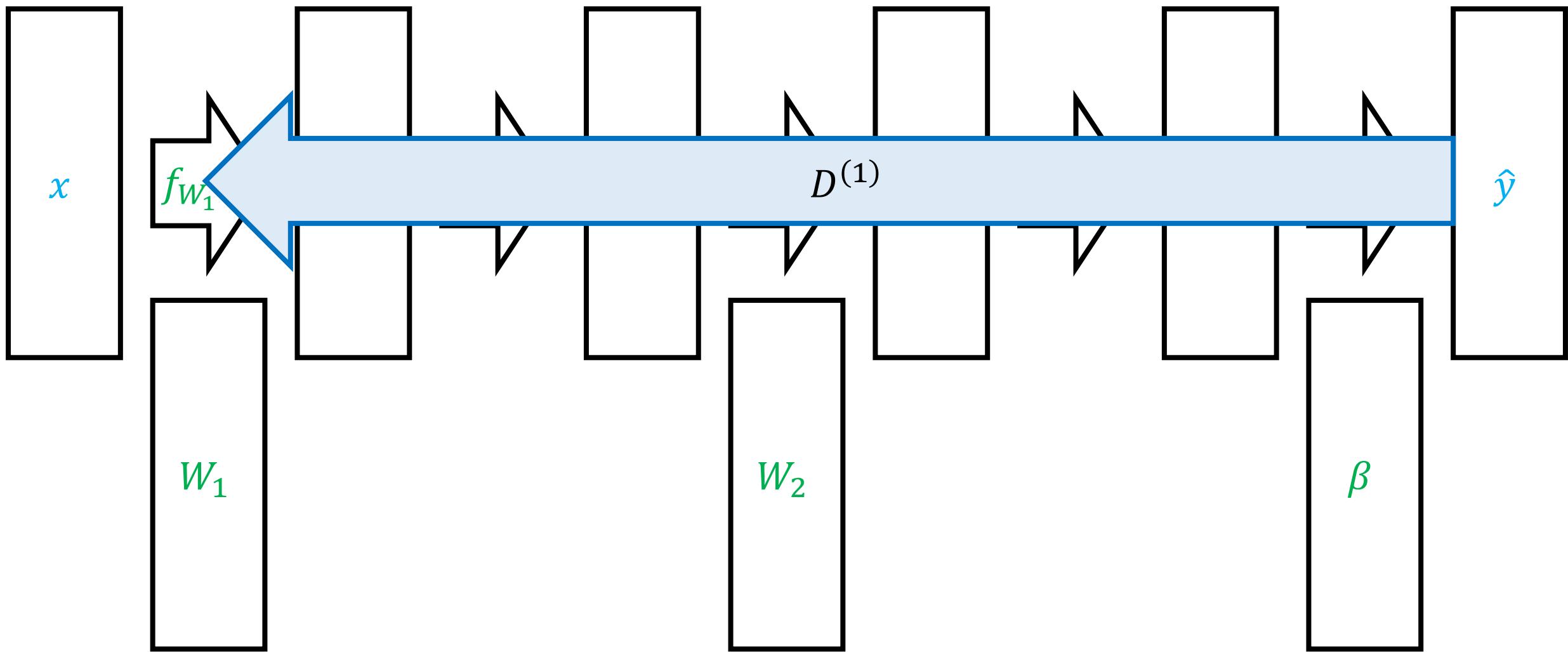
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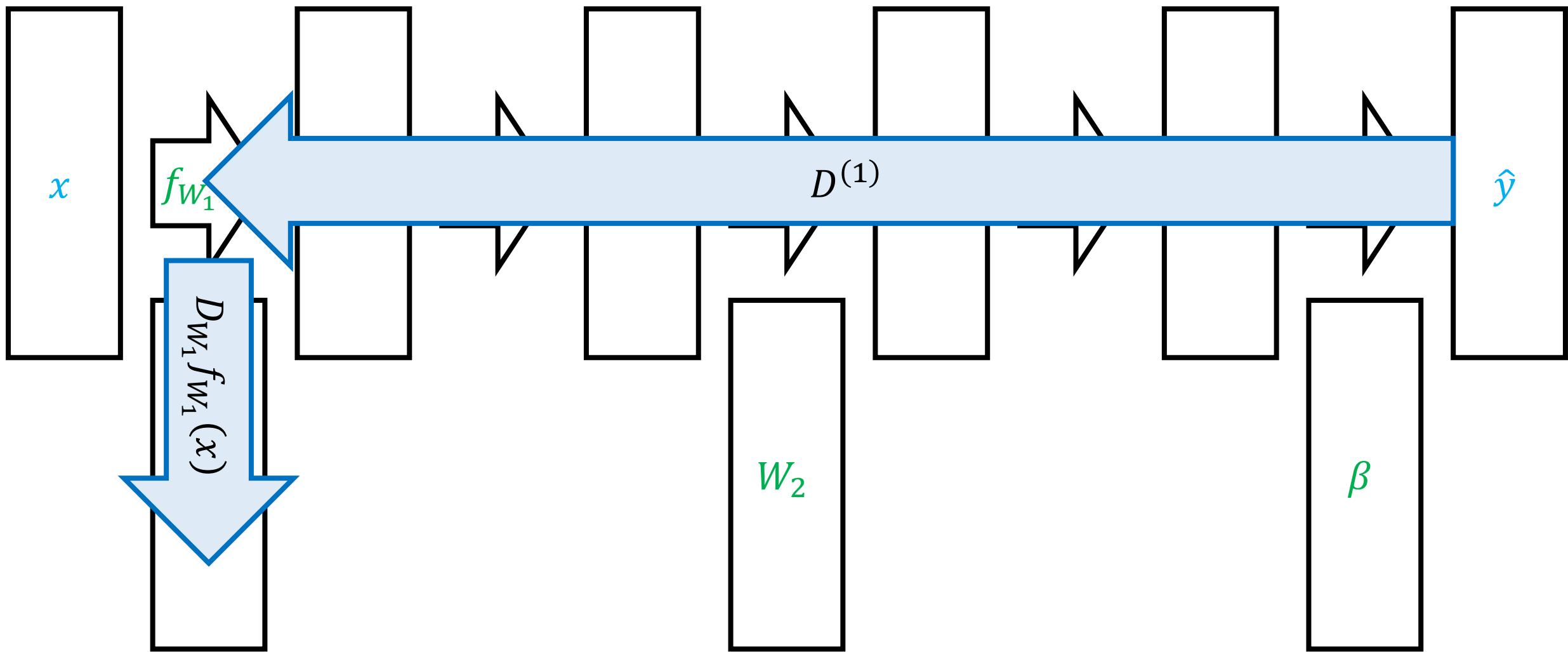
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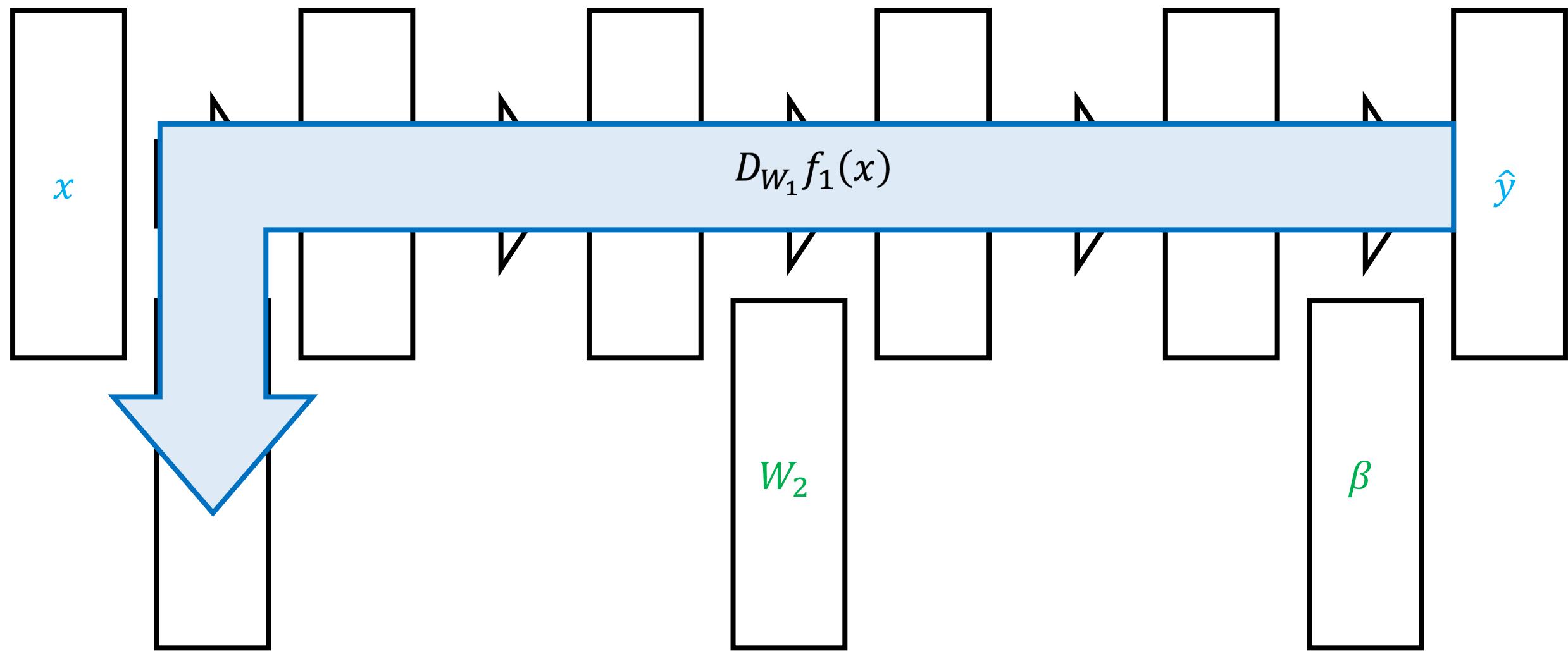
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# Backpropagation



# Backpropagation Algorithm

- **Forward pass:** Compute forwards from  $j = 0$  to  $j = m$ 
  - $z^{(j)} = \begin{cases} \mathbf{x} & \text{if } j = 0 \\ f_{W_j}(z^{(j-1)}) & \text{if } j > 0 \end{cases}$
- **Backward pass:** Compute backwards from  $j = m$  to  $j = 1$ 
  - $D^{(j)} = \begin{cases} 1 & \text{if } j = m \\ D^{(j+1)}D_z f_{W_{j+1}}(z^{(j)}) & \text{if } j < m \end{cases}$
  - $D_{W_j} f_W(\mathbf{x}) = D^{(j)} D_{W_j} f_{W_j}(z^{(j-1)})$
- **Final output:**  $\nabla_{W_j} L(f_W(\mathbf{x}), \mathbf{y})^\top = \nabla_{\hat{y}} L(z^{(m)}, \mathbf{y})^\top D_{W_j} f_W(\mathbf{x})$  for each  $j$

# Gradient Descent

- $W_1 \leftarrow \text{Initialize}()$
- **for**  $t \in \{1, 2, \dots\}$  **until** convergence:

$$W_{t+1,j} \leftarrow W_{t,j} - \frac{\alpha}{n} \cdot \sum_{i=1}^n \nabla_{W_j} L(f_{W_t}(x_i), y_i) \quad (\text{for each } j)$$

- **return**  $f_{W_t}$

# Gradient Descent

- $W_1 \leftarrow \text{Initialize}()$
- **for**  $t \in \{1, 2, \dots\}$  **until** convergence:
  - Compute gradients  $\nabla_{W_j} L(f_{W_t}(x_i), y_i)$  using backpropagation
  - Update parameters:

$$W_{t+1,j} \leftarrow W_{t,j} - \frac{\alpha}{n} \cdot \sum_{i=1}^n \nabla_{W_j} L(f_{W_t}(x_i), y_i) \quad (\text{for each } j)$$

- **return**  $f_{W_t}$