Lecture 20: Ensembles (Part 2)

CIS 4190/5190 Fall 2024

Recap: Ensemble Design Decisions

- How to learn the base models?
 - Bagging (randomize dataset)
 - Boosting (weighted dataset)
- How to combine the learned base models?
 - Averaging (regression) or majority vote (classification)

Recap: Bagging and Boosting

- Bagging (Boostrap Aggregating)
 - Main goal is to reduce variance
 - Models are trained independently with randomized dataset
- Boosting
 - Main goal is to reduce bias
 - Models are trained sequentially with weighted dataset

Recap: Bagging

- Step 1: Create bootstrap replicates of the original training dataset • Excludes $\left(1-\frac{1}{n}\right)^n \rightarrow \frac{1}{e}$ of the training examples $(n \rightarrow \infty)$.
- Step 2: Train a classifier for each replicate
- Step 3 (Optional): Use held-out validation set to weight models
 - Can just use average predictions

Recap: Bagging



Recap: Random Forests

- Ensemble of decision trees using bagging
 - Typically use simple average (over probabilities for classification)

• Intuition:

- Large decision trees are good nonlinear models, but high variance
- Random forests average over many decision trees to reduce variance without increasing bias

Recap: Random Forests

- **Tweak 1:** Randomize features in learning algorithm instead of bagging
 - At DT node splitting step, subsample $\approx \sqrt{d}$ features
 - Allows each tree to use all features, but not at every node
 - Aside: If a few features are highly predictive, then they will be selected in many trees, causing the base models to be highly correlated
- Tweak 2: Train unpruned decision trees
 - Ensures base models have higher capacity
 - Intuition: Skipping pruning increases variance

Recap: AdaBoost

• Input

- Training dataset Z
- Learning algorithm Train(Z, w) that can handle weights w
- Hyperparameter T indicating number of models to train

• Output

• Ensemble of models $F(x) = \sum_{t=1}^{T} \beta_t \cdot f_t(x)$

Recap: Learning with Weighted Examples

For MSE loss:

$$\ell(\boldsymbol{\beta}; \boldsymbol{Z}, \boldsymbol{w}) = \sum_{i=1}^{n} w_i \cdot \left\| y_i - f_{\boldsymbol{\beta}}(\boldsymbol{x}_i) \right\|_2^2$$

For maximum likelihood estimation:

$$\ell(\beta; Z, w) = \sum_{i=1}^{n} w_i \cdot \log p_\beta(y_i \mid x_i)$$



AdaBoost
1.
$$w_1 \leftarrow \left(\frac{1}{n}, \dots, \frac{1}{n}\right) (w_{1,i} \text{ weight for } (x_i, y_i))$$

2. for $t \in \{1, \dots, T\}$
3. $f_t \leftarrow \operatorname{Train}(Z, w_t)$
4. $\epsilon_t \leftarrow \operatorname{Error}(f_t, Z, w_t)$
5. $\beta_t \leftarrow \frac{1}{2} \ln \frac{1 - \epsilon_t}{\epsilon_t}$
6. $w_{t+1,i} \propto w_{t,i} \cdot e^{-\beta_t \cdot y_i \cdot f_t(x_i)} \text{ (for all } i)$
7. return $F(x) = \operatorname{sign}(\sum_{t=1}^T \beta_t \cdot f_t(x))$

$$t = 1$$

β_t measures the importance of f_t()
If ε_t ≤ 0.5, then β_t ≥ 0
otherwise flip h_t's predictions

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 β_t becomes larger as

 ϵ_t becomes smaller



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7. **return** $F(x) = \text{sign}(\sum_{t=1}^T \beta_t \cdot f_t(x))$
Use convention $y_i \in \{-1, +1\}$
If correct $(y_i = f_t(x_i))$ then multiply by $e^{-\beta_t}$
If incorrect $(y_i \neq f_t(x_i))$ then multiply by e^{β_t}



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AdaBoost Summary

• Strengths:

- Fast and simple to implement
- No hyperparameters (except for T)
- Very few assumptions on base models

• Weaknesses:

- Can be susceptible to noise/outliers when there is insufficient data
- No way to parallelize
- Small gains over complex base models
- Specific to classification!

- Both algorithms: new model = old model + update
- Gradient Descent:

$$\theta_{t+1} = \theta_t - \alpha \cdot \nabla_{\theta} L(\theta_t; Z)$$

• Boosting:

$$F_{t+1}(x) = F_t(x) + \beta_{t+1} \cdot f_{t+1}(x)$$

• Here,
$$F_t(x) = \sum_{i=1}^t \beta_i \cdot f_i(x)$$

• Assuming $\beta_t = 1$ for all t, then:

 $F_t(x_i) + f_{t+1}(x_i) = F_{t+1}(x_i)$

• Assuming $\beta_t = 1$ for all t, then:

$$F_t(x_i) + f_{t+1}(x_i) = F_{t+1}(x_i) \approx y_i$$

• Rewriting this equation, we have

$$f_{t+1}(x_i) = F_{t+1}(x_i) - F_t(x_i) \approx \underbrace{y_i - F_t(x_i)}_{}$$

"residuals", i.e., error of the current model

• In other words, at each step, boosting is training the next model f_{t+1} to approximate the residual:

$$f_{t+1}(x_i) \approx \underbrace{y_i - F_t(x_i)}_{}$$

"residuals", i.e., error of the current model

- Idea: Train f_{t+1} directly to predict residuals $y_i F_t(x_i)$
- This strategy works for regression as well!

• Algorithm: For each $t \in \{1, \dots, T\}$:

• Step 1: Train f_{t+1} using dataset

$$Z_{t+1} = \{ (x_i, y_i - F_t(x_i)) \}_{i=1}^n$$

• Step 2: Take

$$F_{t+1}(x) = F_t(x) + f_{t+1}(x)$$

• Return the final model F_T

Consider losses of the form

$$L(F;Z) = \frac{1}{n} \sum_{i=1}^{n} \tilde{L}(F(x_i); y_i)$$

- In other words, sum of individual label-level losses $\tilde{L}(\hat{y}; y)$ of a prediction $\hat{y} = F(x)$ if the ground truth label is y
- For example, $\tilde{L}(\hat{y}; y) = \frac{1}{2}(y y)^2$ yields the MSE loss

• Residuals are the gradient of the squared error $\tilde{L}(\hat{y}; y) = \frac{1}{2}(y - \hat{y})^2$:

$$-\frac{\partial \tilde{L}}{\partial \hat{y}}(F_t(x_i); y_i) = y_i - F_t(x_i) = \text{residual}_i$$

• For general \tilde{L} , instead of $\{(x_i, y_i - F_t(x_i))\}_{i=1}^n$ we can train f_{t+1} on

$$Z_{t+1} = \left\{ \left(x_i, -\frac{\partial \tilde{L}}{\partial \hat{y}} \left(F_t(x_i); y_i \right) \right) \right\}_{i=1}^n$$

• Algorithm: For each $t \in \{1, \dots, T\}$:

• Step 1: Train f_{t+1} using dataset

$$Z_{t+1} = \{ (x_i, y_i - F_t(x_i)) \}_{i=1}^n$$

• Step 2: Take

$$F_{t+1}(x) = F_t(x) + f_{t+1}(x)$$

• Return the final model F_T

- Algorithm: For each $t \in \{1, ..., T\}$:
 - Step 1: Train f_{t+1} using dataset

$$Z_{t+1} = \left\{ \left(x_i, -\frac{\partial \tilde{L}}{\partial \hat{y}} \left(F_t(x_i); y_i \right) \right) \right\}_{i=1}^n$$

• Step 2: Take

$$F_{t+1}(x) = F_t(x) + f_{t+1}(x)$$

• Return the final model F_T

- Casts ensemble learning in the loss minimization framework
 - Model family: Sum of base models $F_T(x) = \sum_{t=1}^T f_t(x)$
 - Loss: Any differentiable loss expressed as

$$L(F; \mathbf{Z}) = \sum_{i=1}^{n} \tilde{\mathbf{L}}(F(\mathbf{x}_i), \mathbf{y}_i)$$

• Gradient boosting is a general paradigm for training ensembles with specialized losses (e.g., most NLL losses)

Gradient Boosting in Practice

- Gradient boosting with depth-limited decision trees (e.g., depth 3) is one of the most powerful off-the-shelf classifiers available
 - Caveat: Inherits decision tree hyperparameters
- XGBoost is a very efficient implementation suitable for production use
 - A popular library for gradient boosted decision trees
 - Optimized for computational efficiency of training and testing
 - Used in many competition winning entries, across many domains
 - <u>https://xgboost.readthedocs.io</u>