

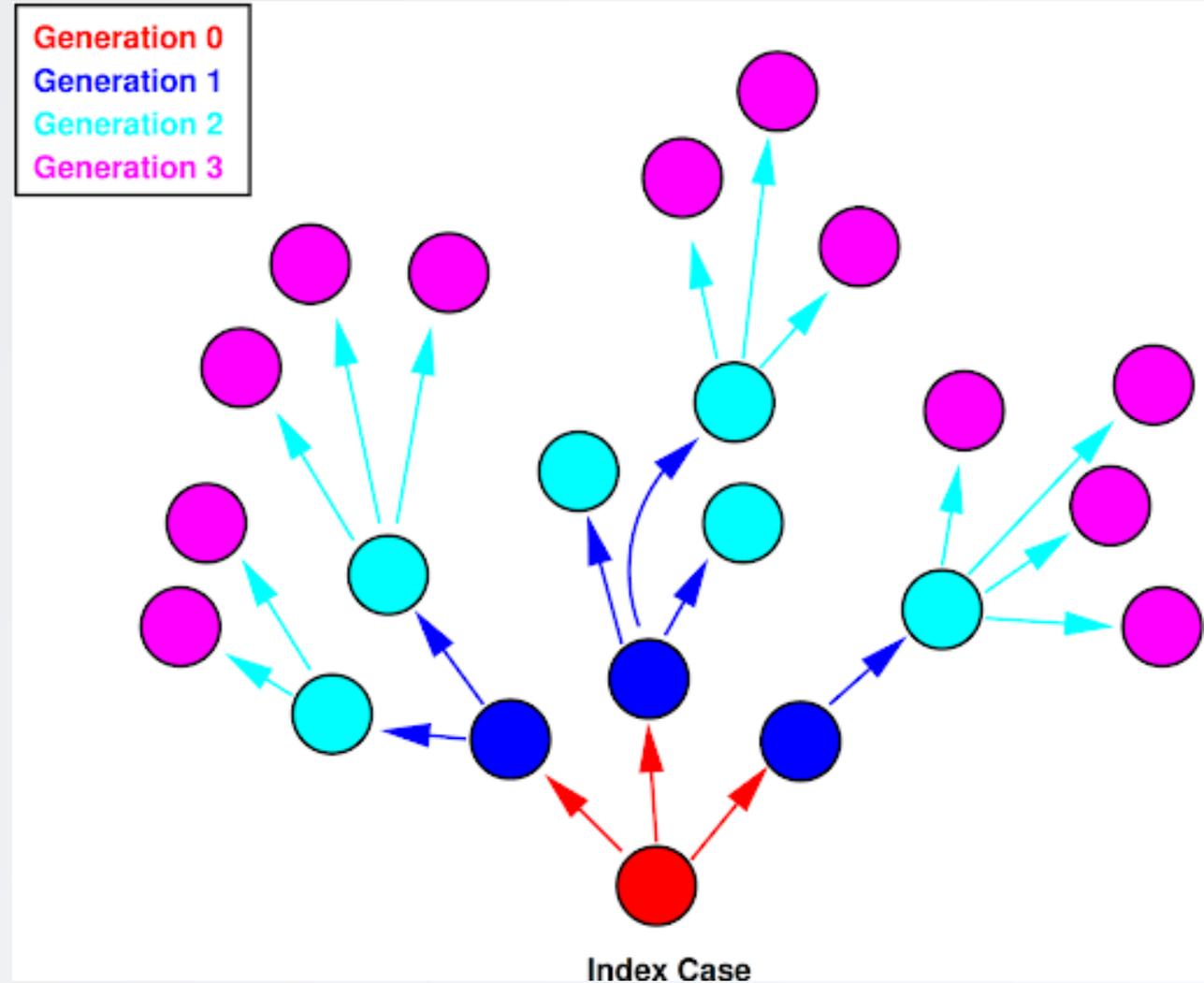
# **Graphs Applications: Epidemiology (HW6)**

## *Background*

- Graphs can be used to model contact between individuals
- Vertices represent individuals
- Edges represent a contact between two individuals
- The probability of infection can be represented as the weight of the edges

# Generations

- Waves of secondary infection that flow from each previous infection
- Structure of the graph leads to different knock-on impacts of a single infection
  - Can help assess the pressure on the healthcare system



## *Calculate Generation of a Node*

Just run BFS with a special `visitor` function that marks the generation of the node as  $1 +$  the generation of the parent.

# *Immunization*

Goal: lower the **reproduction number**  $R_0 = \tau cd$

- $\tau$  is the *transmissibility*, or likelihood of an individual to infect one other on contact.
- $c$  is the *average degree of contact* between susceptible individuals; in other words, the **average degree of the graph**.
- $d$  is the duration of contact—we'll just assume  $d = 1$ .

If you remember from 2020-2021, we reduce the number of cases of a disease by bringing down  $R_0$ .

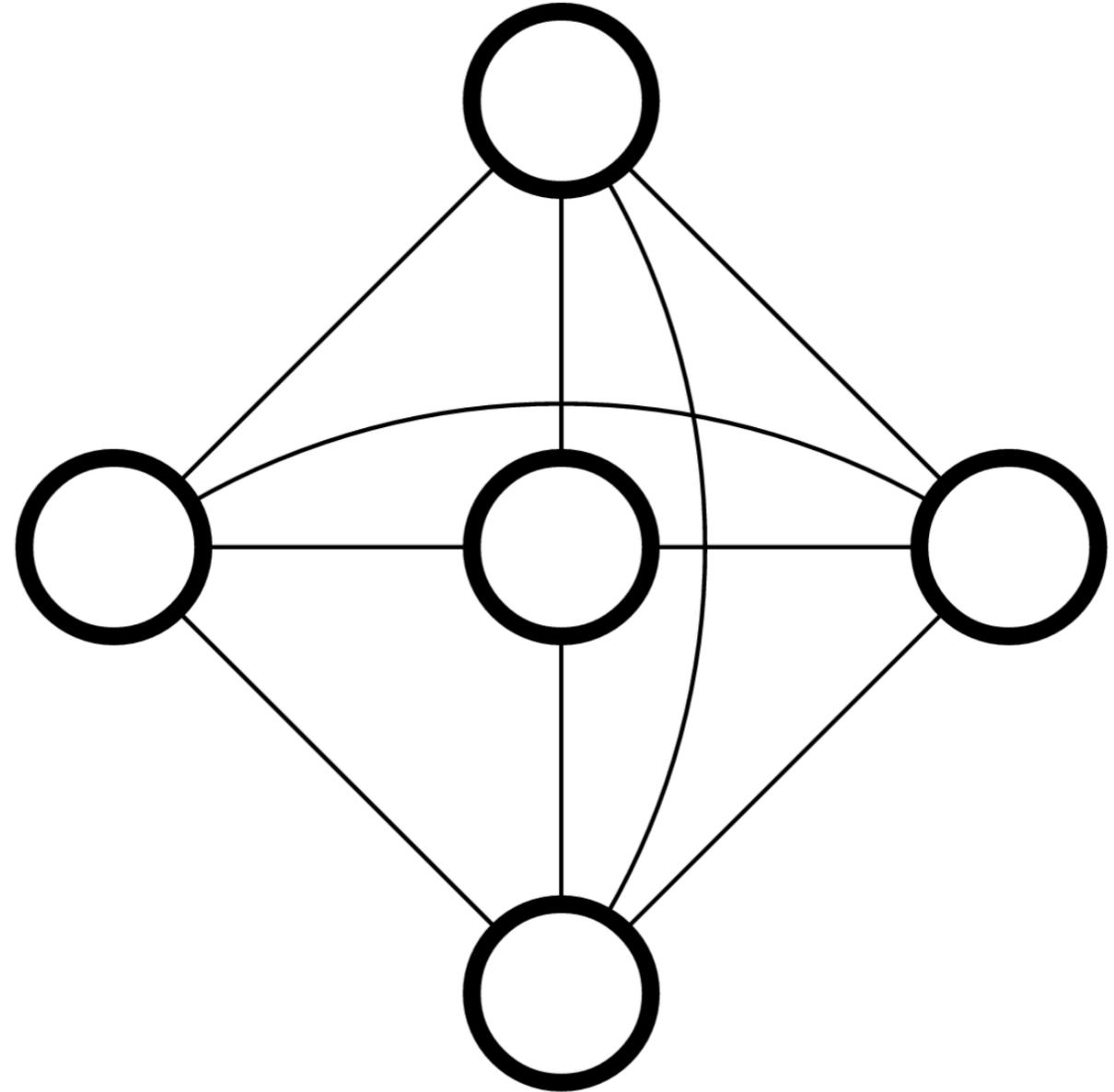
## *Immunization: Removing Nodes from the Graph*

We'll (incorrectly) assume that immunization is perfect, which means that immunization  
→ removing a node

1. Remove all nodes with a high degree
  - i. Give vaccines to popular people
2. Reduce the number of cliques in the graph (clustering coefficient)
  - i. Give vaccines to people whose friends hang out a lot
3. Remove nodes with high degrees that are less likely to be a member of a clique
  - i. Give vaccines to people who are important connections between friend groups.

## *Clique*

- A **clique** is a subset of vertices of an undirected graph such that every two distinct vertices in the clique are adjacent



# Clustering Coefficient

The **clustering coefficient** (between 0 and 1) that measures the degree to which nodes in a graph tend to cluster together

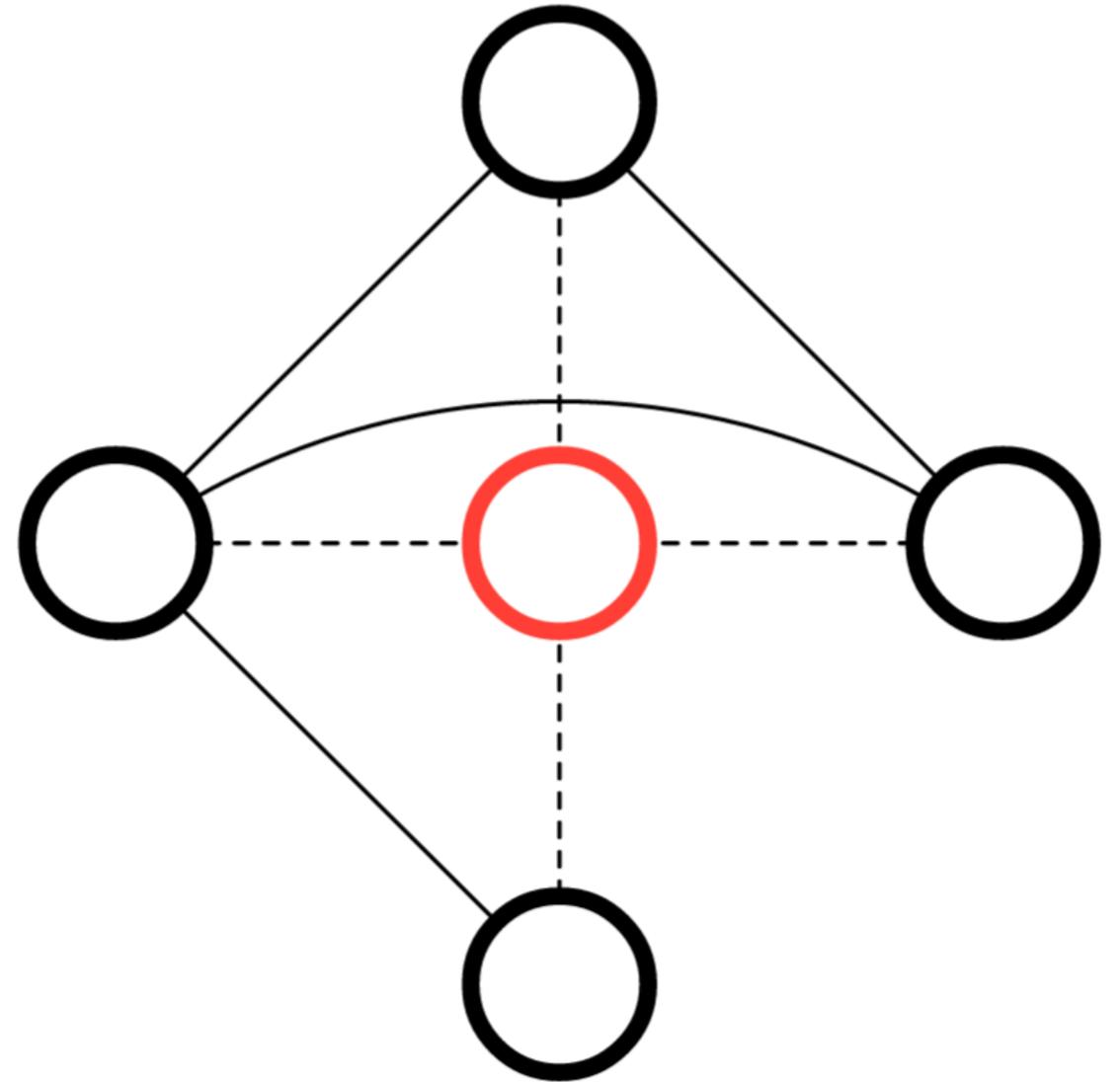
- quantifies how close the neighbors of a node are to being a clique

$$C_i = \frac{2|\{e_{jk} : v_j, v_k \in N_i, e_{jk} \in E\}|}{|N_i|(|N_i| - 1)}$$

## Clustering Coefficient

The **clustering coefficient** of the red node to the right?

$$C_i = \frac{2|\{e_{jk} : v_j, v_k \in N_i, e_{jk} \in E\}|}{|N_i|(|N_i| - 1)}$$

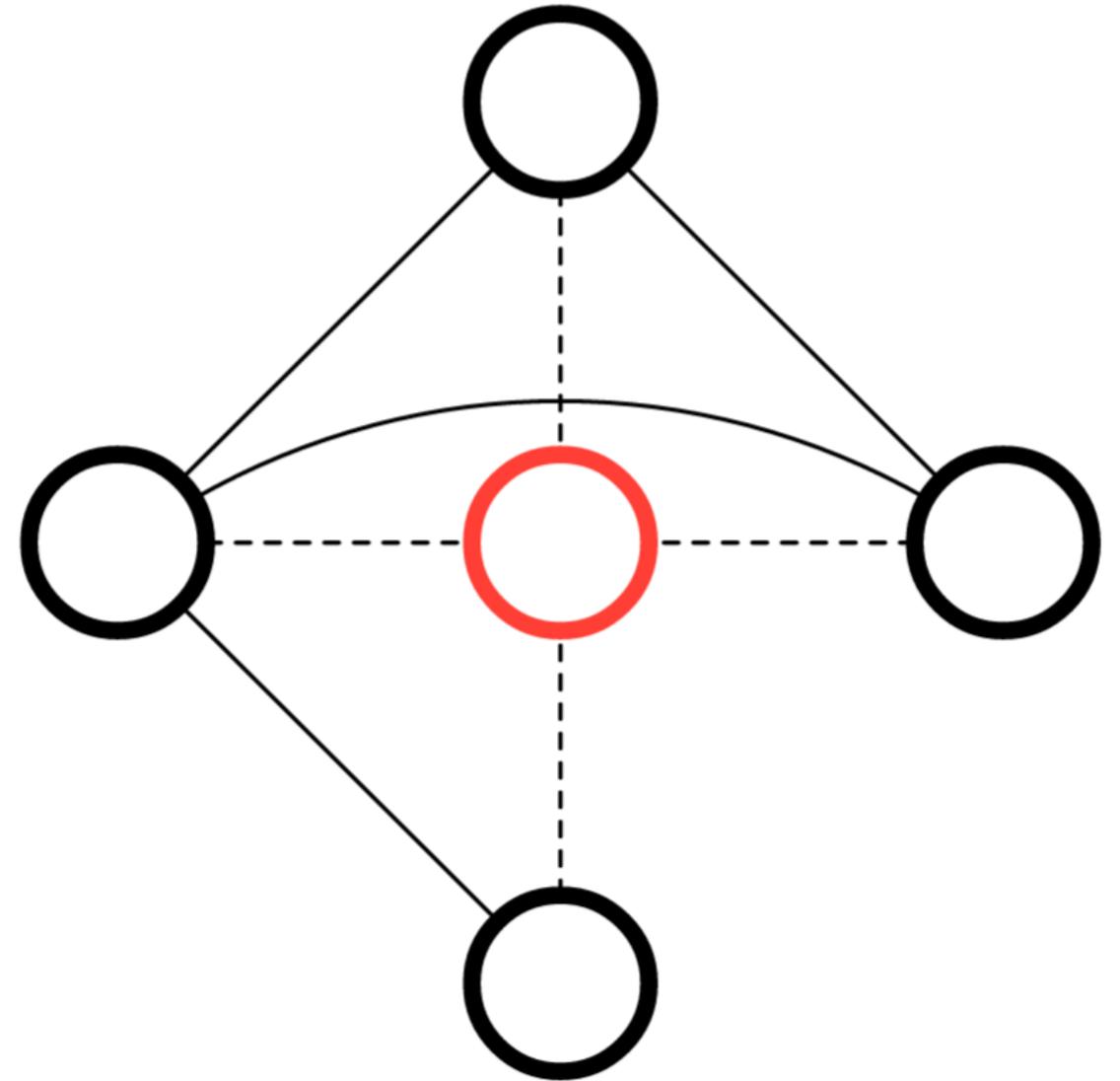


# Clustering Coefficient

The **clustering coefficient** of the red node to the right?

- Ignore the dashed edges
- There are four undirected edges (so eight directed...)
- There are  $4 * 3 = 12$  possible edges.
- $\rightarrow C_i = \frac{8}{12} = 0.666667$

$$C_i = \frac{2|\{e_{jk} : v_j, v_k \in N_i, e_{jk} \in E\}|}{|N_i|(|N_i| - 1)}$$



## *HW7 Goal*

- Which strategy will be the most effective?
- References
  - <https://web.stanford.edu/class/earthsys214/notes/R0.html>
  - [https://en.wikipedia.org/wiki/Clustering\\_coefficient](https://en.wikipedia.org/wiki/Clustering_coefficient)

## *Which Is Most Effective?*

1. Remove all nodes with a high degree
2. Reduce the number of cliques in the graph (clustering coefficient)
3. Remove nodes with high degrees that are less likely to be a member of a clique

... you're going to find out!

# Back to Dijkstra's

```

public static Map<Vertex, PathVertexInfo> dijkstraShortestPath(Graph graph, Vertex startVertex) {
    Map<Vertex, PathVertexInfo> info = new HashMap<>();
    Set<Vertex> visited = new HashSet<>();
    for (Vertex v : graph.getVertices()) {
        info.put(v, new PathVertexInfo(v));
    }

    PathVertexInfo start = info.get(startVertex);
    start.setDistance(0);

    for (int i = 0; i < graph.getVertices().size(); i++) {
        Vertex nextClosest = minVertex(graph, info, visited);
        visited.add(nextClosest); // mark as visited
        PathVertexInfo nextClosestInfo = info.get(nextClosest);
        if (nextClosestInfo.getDistance() == Double.POSITIVE_INFINITY) {
            return info;
        }
        for (Edge e : graph.getEdgesFrom(nextClosest)) {
            Vertex neighbor = e.toVertex;
            double weight = e.weight;
            double oldDistance = info.get(neighbor).getDistance();
            double newDistance = nextClosestInfo.getDistance() + weight;
            if (oldDistance > newDistance) {
                info.get(neighbor).setDistance(newDistance);
                info.get(neighbor).setPredecessor(nextClosest);
            }
        }
    }
}

```

## Back to Dijkstra's

```
// setup: init data structures
Map<Vertex, PathVertexInfo> info = new HashMap<>();
Set<Vertex> visited = new HashSet<>();
for (Vertex v : graph.getVertices()) {
    info.put(v, new PathVertexInfo(v));
}
```

## *Back to Dijkstra's*

```
// prime the search  
PathVertexInfo start = info.get(startVertex);  
start.setDistance(0);
```

## Back to Dijkstra's

```
for (int i = 0; i < graph.getVertices().size(); i++) {  
    // pull out the next vertex...  
    Vertex nextClosest = minVertex(graph, info, visited);  
    visited.add(nextClosest);  
    PathVertexInfo nextClosestInfo = info.get(nextClosest);  
    // ...and stop if we find an unreachable vertex  
    if (nextClosestInfo.getDistance() == Double.POSITIVE_INFINITY) {  
        return info;  
    }  
    ...  
}
```

## Back to Dijkstra's

```
// prime the search
for (int i = 0; i < graph.getVertices().size(); i++) {
    ...
    // update all edges with a new path if found
    for (Edge e : graph.getEdgesFrom(nextClosest)) {
        Vertex neighbor = e.toVertex;
        double weight = e.weight;
        double oldDistance = info.get(neighbor).getDistance();
        double newDistance = nextClosestInfo.getDistance() + weight;
        if (oldDistance > newDistance) {
            info.get(neighbor).setDistance(newDistance);
            info.get(neighbor).setPredecessor(nextClosest);
        }
    }
}
}
```

## Processing the Table

How to get from a table of predecessor pointers to an actual path?

Node	Distance	Predecessor
A	0	null
B	8	A
C	4	D
D	3	A
E	6	C
F	10	E
G	11	F

## Processing the Table

```
public static String getShortestPath(Vertex endVertex,
                                     Map<Vertex, PathVertexInfo> infoMap) {
    StringBuilder path = new StringBuilder();
    Vertex current = endVertex;
    while (current != null) {
        path.append(current);
        current = infoMap.get(current).getPredecessor();
    }
    return path.toString();
}
```

*Activity: what's wrong with the approach above?*

## Processing the Table

```
public static String getShortestPath(Vertex endVertex,
                                     Map<Vertex, PathVertexInfo> infoMap) {
    StringBuilder path = new StringBuilder();
    Vertex current = endVertex;
    while (current != null) {
        path.insert(0, current);
        current = infoMap.get(current).getPredecessor();
    }
    return path.toString();
}
```

Now the path is no longer reversed...

## Finding the Min Vertex: Runtime?

```
private static Vertex minVertex(Graph graph, Map<Vertex, PathVertexInfo> info,
                                Set<Vertex> visited) {
    Vertex closest = null;
    double minDistance = Double.POSITIVE_INFINITY;
    for (Vertex candidate : info.keySet()) {
        if (visited.contains(candidate)) {
            continue;
        }
        PathVertexInfo data = info.get(candidate);
        if (closest == null || data.getDistance() < minDistance) {
            closest = candidate;
            minDistance = data.getDistance();
        }
    }
    return closest;
}
```

## Finding the Min Vertex: Runtime?

```

private static Vertex minVertex(Graph graph, Map<Vertex,PathVertexInfo> info,
                                Set<Vertex> visited) {
    Vertex closest = null;
    double minDistance = Double.POSITIVE_INFINITY;
    for (Vertex candidate : info.keySet()) {           // max O(V) iterations
        if (visited.contains(candidate)) {           // O(1) for HashSet
            continue;
        }
        PathVertexInfo data = info.get(candidate); // O(1) for HashMap
        if (closest == null || data.getDistance() < minDistance) {
            closest = candidate;
            minDistance = data.getDistance();
        }
        // all this is O(1)
    }
    return closest;
}

```

## Finding the Min Vertex: Runtime?

```
private static Vertex minVertex(Graph graph, Map<Vertex, PathVertexInfo> info,  
                                Set<Vertex> visited) {  
    ...  
}
```

Simple solution gives  $O(|V|)$  runtime per call—called  $V$  times, so  $O(|V|^2)$  indeed works as a real-world upper bound.

## *Functional Programming & Streams*

At a high-level, to implement `minVertex`, we:

- filter the set of all vertices to only include unvisited ones.
- find the minimum vertex based on the shortest distance of its `PathVertexInfo`

Can we express the ideas of these two *highly common* ideas a little more succinctly?

## Streams

*"A sequence of elements supporting sequential and parallel aggregate operations."*

To perform a computation, stream operations are composed into a **stream pipeline**:

- a source (which might be an array, a collection, a generator function, an I/O channel, etc)
- zero or more intermediate operations (which transform a stream into another stream, such as `filter(Predicate)`),
- and a terminal operation (which produces a result or side-effect, such as `count()` or `forEach(Consumer)`).

## Streams

```
private static Vertex minVertex(Map<Vertex, PathVertexInfo> info,  
                                Set<Vertex> visited) {  
    return info.keySet().stream()  
        ...  
}
```

## Filter

A function that *takes in a function* that returns a boolean deciding whether an element should be included.

How to pass in a function as an input to another? **Lambdas** (anonymous functions)

An example predicate lambda:

```
// input    -> boolean expression using input var  
element -> element < 0 || element % 2 == 1
```

## Streams

```
private static Vertex minVertex(Map<Vertex,PathVertexInfo> info,  
                                Set<Vertex> visited) {  
    return info.keySet().stream()  
        .filter(vertex -> !visited.contains(vertex))  
        ...  
}
```

## *Finding the Minimum*

`min()` allows you to find the minimum element of a stream using a comparator.

Could write a comparator using a lambda:

```
(e1, e2) -> info.get(e1).compareTo(info.get(e2))
```

## *Finding the Minimum*

`min()` allows you to find the minimum element of a stream using a comparator.

Could write a comparator using a lambda:

```
(e1, e2) -> info.get(e1).compareTo(info.get(e2))
```

Can also pass a named function as a reference:

```
Comparator.comparing(info::get)
```

"Make a comparator by comparing the result of calling `info.get()` with the element as an input."

## Streams

```
private static Vertex minVertex(Map<Vertex,PathVertexInfo> info,  
                                Set<Vertex> visited) {  
    return info.keySet().stream()  
        .filter(vertex -> !visited.contains(vertex))  
        .min(Comparator.comparing(info::get))  
        .orElse(null); // min might not find an answer, so return null  
}
```